

20-W/15-W STEREO DIGITAL AMPLIFIER POWER STAGE

FEATURES

- 2×20 W at 10% THD+N Into 8-Ω BTL at 18 V (With Heatsink for TAS5102)
- 2×15 W at 10% THD+N Into 8-Ω BTL at 15.5 V for TAS5103
- 2×10 W at 10% THD+N Into 8-Ω BTL at 13 V
- >100-dB SNR (A-Weighted)
- <0.1% THD+N at 1 W
- Thermally Enhanced Package: 32-pin HTSSOP
 - DAD (TAS5102) Pad Up
 - DAP (TAS5103) Pad Down
- High-Efficiency Power Stage (>90%) With 180-mΩ Output MOSFETs
- Wide PVDD Range from 8V to 23V
- Power-On Reset for Protection on Power Up Without Any Power-Supply Sequencing
- Integrated Self-Protection Circuits Including Undervoltage, Overtemperature, Overcurrent, Short Circuit
- Built-In Regulator for Gate Drive Supply
- Error Reporting
- EMI Compliant When Used With Recommended System Design

APPLICATIONS

- Televisions
- Mini/Micro Audio Systems
- DVD Receivers
- Home Theaters

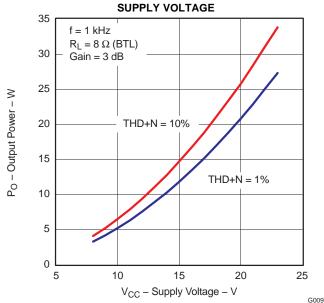
DESCRIPTION

The TAS5102/TAS5103 are integrated stereo digital amplifier power stages with an advanced protection system. The TAS5102/TAS5103 are capable of driving an 8- Ω bridge-tied load (BTL) at up to 20 W/15 W per channel with low integrated noise at the output, low THD+N performance, and low idle power dissipation.

A low-cost, high-fidelity audio system can be built using a TI chipset, comprising a modulator (e.g., TAS5086) and the TAS5102/TAS5103. This system only requires a simple passive LC demodulation filter to deliver high-quality, high-efficiency audio amplification with proven EMI compliance. These devices require two power supplies, at 3.3 V for VREG, and up to 23 V for PVDD. The TAS5102/TAS5103 does not require power-up sequencing due to internal power-on reset. The efficiency of this digital amplifier is greater than 90% into 8 $\Omega_{\rm c}$ which enables the use of smaller power supplies and heatsinks.

The TAS5102/3 has an innovative protection system integrated on chip, safeguarding the device against a wide range of fault conditions that could damage the system. These safeguards are short-circuit protection, overcurrent protection, undervoltage protection, and overtemperature protection. The TAS5102/TAS5103 has a new proprietary current-limiting circuit that reduces the possibility of device shutdown during high-level music transients.

BTL OUTPUT POWER vs



ATA.

Please be aware that an important notice concerning availability, standard warranty, and use in critical applications of Texas Instruments semiconductor products and disclaimers thereto appears at the end of this data sheet.

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These devices have limited built-in ESD protection. The leads should be shorted together or the device placed in conductive foam during storage or handling to prevent electrostatic damage to the MOS gates.

DEVICE INFORMATION

Pin Assignment

The TAS5102/TAS5103 are available in a thermally enhanced package:

- TAS5102 Pad Up 32-pin HTSSOP PowerPAD™ package (DAD)
- TAS5103 Pad Down 32-pin HTSSOP PowerPAD™ package (DAP)

DAD PACKAGE DAP PACKAGE (TOP VIEW) (TOP VIEW) GVDD AB □ GVDD CD □ 32 M2 □ VREG □ PVDD A PVDD D AGND □□ 30 □ OUT A M1 □ □ OUT D PGND_AB ── PGND_CD GND □ 29 OC ADJ == 29 SSTIMER == □ PGND_AB FAULT == 28 28 \square PGND_CD OTW \square 27 □ OUT B PWM D □ 6 27 □ OUT C RESET == PWM C □□ 26 \longrightarrow PVDD_B 26 \longrightarrow PVDD_C PWM A === PWM B □□ 25 25 8 PWM_B === 9 ── BST_C PWM_A === ── BST_B 24 9 24 PWM_C ___ PVDD C RESET ___ 23 10 23 PWM D === ☐ OUT C OTW ___ ☐ OUT B 22 22 FAULT === SSTIMER == 21 12 21 ── PGND_CD □ PGND_AB OC_ADJ === GND □ 13 20 13 20 OUT D AGND == □ OUT A M1 ___ 19 19 14 M2 □□ PVDD_D VREG □□ 15 18 15 18 GVDD CD □ □ BST D GVDD AB □ □ BST A 17 16

MODE Selection Pins

Мо	ode	PWM INPUT	OUTPUT CONFIGURATION	PROTECTION SCHEME		
M2	M1	PWWINPUT	OUTPUT CONFIGURATION	PROTECTION SCHEWIE		
0	0	2N (1) AD/BD modulation	2 channels BTL output	BTL mode (2)		
0	1	1N ⁽¹⁾ AD modulation	2 channels BTL output	BTL mode (2)		
1	0	1N ⁽¹⁾ AD modulation	4 channels SE output	Protection works similarly to BTL mode ⁽²⁾ . Only difference in SE mode is that OUT_X is Hi-Z instead of a pulldown through internal pulldown resistor.		
1	1	Reserved				

The 1N and 2N naming convention is used to indicate the required number of PWM lines to the power stage per channel in a specific (1) mode.

Package Heat Dissipation Ratings

PARAMETER	TAS5102DAD	TAS5103DAP
R _{eJC} (°C/W)	1.69	1.69
R _{eJA} (°C/W)	See Note (1)	23.5

(1) The TAS5102 package is thermally enhanced for conductive cooling using an exposed metal pad area. It is impractical to use the device with the pad exposed to ambient air as the only means for heat dissipation for higher power applications. For this reason, R_{0JA}, a system parameter that characterizes the thermal treatment, is provided in the Application Information section of the data sheet. An example and discussion of typical system R_{0JA} values are provided in the Thermal Information section. This example

provides additional information regarding the power dissipation ratings. This example should be used as a reference to calculate the heat dissipation ratings for a specific application. TI application engineering provides technical support to design heatsinks if needed. Also, for additional general information on PowerPad packages, see TI document SLMA002B.

An overcurrent protection (OC) occurring on A or B causes all channels to shut down. An OC on C or D works similarly. Global errors like overtemperature error (OTE), undervoltage protection (UVP), and power-on reset (POR) affect all channels.



ABSOLUTE MAXIMUM RATINGS(1)

over operating free-air temperature range (unless otherwise noted)

			UNIT
	PVDD_X to GND_X DC	-0.3 to 23	V
	PVDD_X to GND_X (2)	-0.3 to 32	V
	OUT_X to GND_X (2)	-0.3 to 32	V
	BST_X to GND_X (2)	-0.3 to 43.2	V
	VREG to AGND	-0.3 to 4.2	V
	GVDD to GND	-0.3 to 13.2	V
	GND_X to GND	-0.3 to 0.3	V
	GND_X to AGND	-0.3 to 0.3	V
	GND to AGND	-0.3 to 0.3	V
	PWM_X, OC_ADJ, M1, M2 to AGND	-0.3 to 4.2	V
	RESET_X, FAULT, OTW to AGND	−0.3 V to 7	V
	Maximum continuous sink current (FAULT, OTW)	9	mA
TJ	Maximum operating junction temperature range,	0 to 150	°C
T _{STG}	Storage temperature range	-65 to 150	°C
	Minimum pulse duration, low	50	ns

⁽¹⁾ Stresses beyond those listed under "absolute maximum ratings" may cause permanent damage to the device. These are stress ratings only, and functional operation of the device at these or any other conditions beyond those indicated under "recommended operating conditions" is not implied. Exposure to absolute-maximum-rated conditions for extended periods may affect device reliability.

ORDERING INFORMATION

T _A	PACKAGE ⁽¹⁾	DESCRIPTION
0°C to 70°C	TAS5102DAD	32-pin HTSSOP
0 0 10 70 0	TAS5103DAP	32-pin HTSSOP

(1) For the most current package and ordering information, see the Package Option Addendum at the end of this document, or see the TI website at www.ti.com.

⁽²⁾ These voltages represent the dc voltage + peak ac waveform measured at the terminal of the device in all conditions.



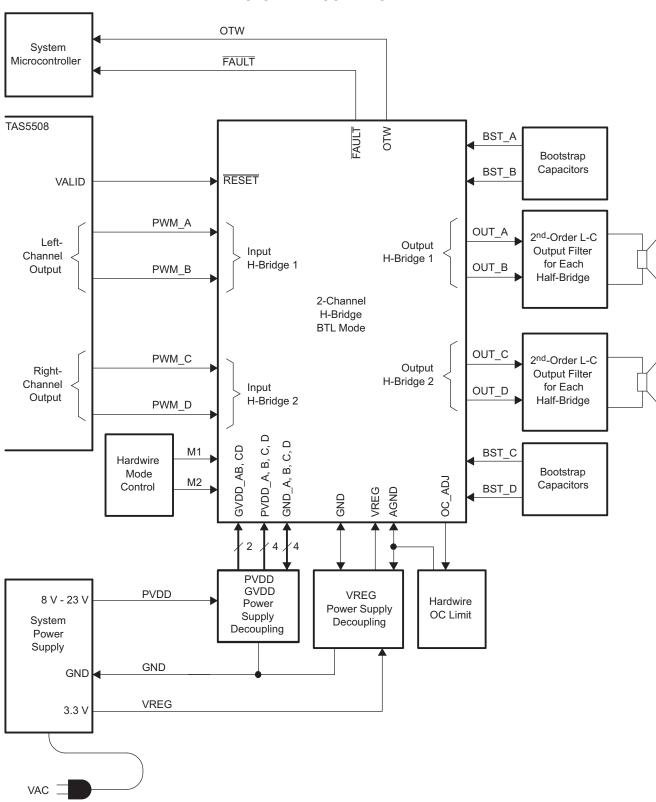
Pin Functions

		PIN			
BST_A 32 17 P HS bootstrap supply (BST). External capacitor to OUT_A required. BST_B 25 24 P HS bootstrap supply (BST). External capacitor to OUT_B required. BST_C 24 25 P HS bootstrap supply (BST). External capacitor to OUT_C required. BST_D 17 32 P HS bootstrap supply (BST). External capacitor to OUT_C required. BST_D 17 32 P HS bootstrap supply (BST). External capacitor to OUT_D required. FAULT 12 5 O Device error signal (shutdown): open drain GND 4 13 P Ground PGND_AB 29 20 P Power ground for half-bridges A and B PGND_AB 29 20 P Power ground for half-bridges A and B PGND_AB 28 21 P Power ground for half-bridges C and D PGND_CD 21 28 P Power ground for half-bridges C and D PGND_CD 20 29 P Power ground for half-bridges C and D GVDD_CD 16 1 P Gate-drive voltage supply. Requires 1-µF capacitor to GND. M2 15 2 I Mode selection 2, connect to either AGND or VREG, no pull-up or pull-down resistors M1 14 3 I resistors M1 14 3 I resistors M2 15 2 O Analog overcurrent programming. Requires resistor to ground. MCA 30 19 O Overtemperature warning signal, push-pull, active high OUT_B 27 22 O Output, half-bridge C OUT_D 19 30 O Output, half-bridge B PVDD_A 31 18 P Power supply input for half-bridge B. Requires close decoupling of 0.1-µF capacitor to GND_B. PVDD_B 26 23 P Power supply input for half-bridge B. Requires close decoupling of 0.1-µF capacitor to GND_B. PVDD_D 18 31 P Power supply input for half-bridge D. Requires close decoupling of 0.1-µF capacitor to GND_B. PVDD_D 18 31 P Power supply input for half-bridge B. Requires close decoupling of 0.1-µF capacitor to GND_C. PVDD_D 18 31 P Power supply input for half-bridge B. Requires close decoupling of 0.1-µF capacitor to GND_C. PVDD_D 18 31 P Power supply input for half-bridge D. Requires close decoupling of 0.1-µF capacitor to GND_C. PVDD_D 18 31 P Power supply input for half-bridge D. Requires close decoupling of 0.1-µF capacitor to GND_C. PVDD_D 19 B 10 P Power supply input for half-bridge D. Requires close decoupling of 0.1-µF capacito	NAME			FUNCTION (1)	DESCRIPTION
BST_B 25 24 P HS bootstrap supply (BST). External capacitor to OUT_B required. BST_C 24 25 P HS bootstrap supply (BST). External capacitor to OUT_C required. BST_D 17 32 P HS bootstrap supply (BST). External capacitor to OUT_C required. BST_D 17 32 P HS bootstrap supply (BST). External capacitor to OUT_D required. BST_D 17 32 P HS bootstrap supply (BST). External capacitor to OUT_D required. BST_D 17 32 P HS bootstrap supply (BST). External capacitor to OUT_D required. BST_D 17 32 P HS bootstrap supply (BST). External capacitor to OUT_D required. BST_D 17 32 P HS bootstrap supply (BST). External capacitor to OUT_D required. BST_D 17 32 P HS bootstrap supply (BST). External capacitor to OUT_D required. BST_D 17 32 P HS bootstrap supply (BST). External capacitor to OUT_D required. BST_D 17 32 P HS bootstrap supply (BST). External capacitor to OUT_D required. BST_D 17 32 P HS bootstrap supply (BST). External capacitor to OUT_D required. BST_D 17 32 P HS bootstrap supply (BST). External capacitor to OUT_D required. BST_D 17 32 P HS bootstrap supply (BST). External capacitor to OUT_D required. BST_D 17 32 P HS bootstrap supply (BST). External capacitor to OUT_D required. BST_D 17 32 P HS bootstrap supply (BST). External capacitor to OUT_D required. BST_D 17 32 P HS bootstrap supply (BST). External capacitor to OUT_D required. BST_D 17 32 P HS bootstrap supply (BST). External capacitor to OUT_D required. BST_D 17 32 P P Bower supply (BST). External capacitor to OUT_D required. BST_D 17 32 P HS bootstrap supply (BST). External capacitor to OUT_D required. BST_D 17 32 P P Bower supply input for half-bridge D. Requires close decoupling of 0.1-µF capacitor to OND_C. BST_D 17 10 PWM is not active if RESET goes low. Controls start/stop time of PWM modulation. Requires 2.2 nF capacitor to GN potents. BST_MER 5 12 I I put signal for half-bridge D.	AGND	3	14	Р	Analog ground
BST_C 24 25 P HS bootstrap supply (BST). External capacitor to OUT_C required. BST_D 17 32 P HS bootstrap supply (BST). External capacitor to OUT_D required. FAULT 12 5 O Device error signal (shutdown); open drain GND 4 13 P Ground PGND_AB 29 20 P Power ground for half-bridges A and B PGND_AB 29 20 P Power ground for half-bridges A and B PGND_CD 21 28 P Power ground for half-bridges C and D PGND_CD 20 29 P Power ground for half-bridges C and D GVDD_AB 1 16 P Gate-drive voltage supply. Requires 1-µF capacitor to GND. GVD_AB 1 16 P Gate-drive voltage supply. Requires 1-µF capacitor to GND. M2 15 2 I Mode selection 2, connect to either AGND or VREG, no pull-up or pull-down resistors M1 14 3 I Mode selection 2, connect to either AGND or VREG, no pull-up or pull-down resistors	BST_A	32	17	Р	HS bootstrap supply (BST). External capacitor to OUT_A required.
BST_D 17 32 P HS bootstrap supply (BST). External capacitor to OUT_D required. FAULT 12 5 O Device error signal (shutdown); open drain GND 4 13 P Ground PGND_AB 29 20 P Power ground for half-bridges A and B PGND_AB 28 21 P Power ground for half-bridges A and B PGND_CD 21 28 P Power ground for half-bridges A and B PGND_CD 20 29 P Power ground for half-bridge D GVDD_AB 1 16 P Gate-drive voltage supply. Requires 1-μF capacitor to GND. GVDD_AB 1 16 P Gate-drive voltage supply. Requires 1-μF capacitor to GND. MZ 15 2 I Mode selection 2, connect to either AGND or VREG, no pull-up or pull-down resistors M1 14 3 I Mode selection 1, connect to either AGND or VREG, no pull-up or pull-down resistors M1 14 3 I Mode selection 1, connect to either AGND or VREG, no pull-up or pull-down resistors M1 14 3 O Analog overcurrent programming. Requires resistor to ground. OTW 6 11 O Overtemperature warming signal, push-pull, active high OUT_A 30 19 O Output, half-bridge A OUT_B 27 22 O Output, half-bridge C OUT_D 19 30 O Output, half-bridge C OUT_D 19 30 O Output, half-bridge C OUT_D 19 30 O Output, half-bridge C PVDD_A 31 18 P Power supply input for half-bridge B. Requires close decoupling of 0.1-μF capacitor to GND_B. PVDD_B 26 23 P Power supply input for half-bridge B. Requires close decoupling of 0.1-μF capacitor to GND_B. PVDD_C 23 26 P Power supply input for half-bridge C. Requires close decoupling of 0.1-μF capacitor to GND_C. PVDD_D 18 31 P Power supply input for half-bridge D. Requires close decoupling of 0.1-μF capacitor to GND_C. PVM_B 9 8 I Input signal for half-bridge A PWM_B 9 8 I Input signal for half-bridge B PWM_C 10 7 I Input signal for half-bridge D RESET 7 10 I PWM is not active if RESET goes low. Controls start/stop time of PWM modulation. Requires 2.2 nF capacitor to GND D. Controls start/stop time of PWM modulation. Requires 2.2 nF capacitor to GND D.	BST_B	25	24	Р	HS bootstrap supply (BST). External capacitor to OUT_B required.
FAULT 12 5 0 Device error signal (shutdown): open drain GND 4 13 P Ground PGND_AB 29 20 P Power ground for half-bridges A and B PGND_AB 28 21 P Power ground for half-bridges A and B PGND_CD 21 28 P Power ground for half-bridges C and D PGND_CD 20 29 P Power ground for half-bridge D GVDD_AB 1 16 P Gate-drive voltage supply. Requires 1-µF capacitor to GND. GVDD_CD 16 1 P Gate-drive voltage supply. Requires 1-µF capacitor to GND. M2 15 2 I Mode selection 2, connect to either AGND or VREG, no pull-up or pull-down resistors M1 14 3 I Mode selection 1, connect to either AGND or VREG, no pull-up or pull-down resistors M1 14 3 I Mode selection 1, connect to either AGND or VREG, no pull-up or pull-down resistors OC_ADJ 13 4 O Analog overcurrent programming. Requires resistor to ground. OTW 6 111 O Overtemperature warming signal, push-pull, active high OUT_A 30 19 O Output, half-bridge B OUT_B 27 22 O Output, half-bridge B OUT_C 22 27 O Output, half-bridge B OUT_D 19 30 O Output, half-bridge B PVDD_A 31 18 P Power supply input for half-bridge A. Requires close decoupling of 0.1-µF capacitor to GND_A. PVDD_B 26 23 P Power supply input for half-bridge B. Requires close decoupling of 0.1-µF capacitor to GND_C. PVDD_D 18 31 P Power supply input for half-bridge D. Requires close decoupling of 0.1-µF capacitor to GND_C. PVDD_D 38 9 I Input signal for half-bridge D. Requires close decoupling of 0.1-µF capacitor to GND_C. PVM_A 8 9 I Input signal for half-bridge B PWM_C 10 7 I Input signal for half-bridge B PWM_D 11 6 I Input signal for half-bridge D RESET 7 10 I Input signal for half-bridge D SSTIMER 5 12 I Input signal for half-bridge D	BST_C	24	25	Р	HS bootstrap supply (BST). External capacitor to OUT_C required.
GND	BST_D	17	32	Р	HS bootstrap supply (BST). External capacitor to OUT_D required.
PGND_AB 29 20 P Power ground for half-bridges A and B PGND_AB 28 21 P Power ground for half-bridges C and D PGND_CD 21 28 P Power ground for half-bridges C and D PGND_CD 20 29 P Power ground for half-bridge D GVDD_AB 1 16 P Gate-drive voltage supply. Requires 1-μF capacitor to GND. M2 15 2 I Mode selection 2, connect to either AGND or VREG, no pull-up or pull-down resistors M1 14 3 I Mode selection 1, connect to either AGND or VREG, no pull-up or pull-down resistors OC_ADJ 13 4 O Analog overcurrent programming. Requires resistor to ground. OUT_A 30 19 O Output, half-bridge A OUT_B 27 22 O Output, half-bridge B OUT_C 22 27 O Output, half-bridge D PVDD_A 31 18 P Power supply input for half-bridge A. Requires close decoupling of 0.1-μF capacitor to GND_A. PVDD_B	FAULT	12	5	0	Device error signal (shutdown); open drain
PGND_AB 28 21 P Power ground for half-bridges A and B PGND_CD 21 28 P Power ground for half-bridges C and D PGND_CD 20 29 P Power ground for half-bridge D GVDD_AB 1 16 P Gate-drive voltage supply. Requires 1-μF capacitor to GND. M2 15 2 I Mode selection 2, connect to either AGND or VREG, no pull-up or pull-down resistors M1 14 3 I Mode selection 1, connect to either AGND or VREG, no pull-up or pull-down resistors OC_ADJ 13 4 O Analog overcurrent programming. Requires resistor to ground. OTW 6 11 O Overtemperature warning signal, push-pull, active high OUT_A 30 19 O Output, half-bridge B OUT_B 27 22 O Output, half-bridge C OUT_D 19 30 O Output, half-bridge C OUT_D 23 26 P Power supply input for half-bridge A. Requires close decoupling of 0.1-μF capacitor to GND_B.	GND	4	13	Р	Ground
PGND_CD 21 28 P Power ground for half-bridges C and D PGND_CD 20 29 P Power ground for half-bridge D GVDD_AB 1 16 P Gate-drive voltage supply. Requires 1-µF capacitor to GND. GVDD_CD 16 1 P Gate-drive voltage supply. Requires 1-µF capacitor to GND. M2 15 2 I Mode selection 2, connect to either AGND or VREG, no pull-up or pull-down resistors M1 14 3 I Mode selection 1, connect to either AGND or VREG, no pull-up or pull-down resistors OC_ADJ 13 4 O Analog overcurrent programming. Requires resistor to ground. OTW 6 11 O Overtemperature warning signal, push-pull, active high OUT_A 30 19 O Output, half-bridge A OUT_B 27 22 O Output, half-bridge B OUT_C 22 27 O Output, half-bridge C OUT_D 19 30 O Output, half-bridge D PVDD_A 31 18 P Power supply input for half-bridge A. Requires close decoupling of 0.1-µF capacitor to GND_A. PVDD_B 26 23 P Power supply input for half-bridge B. Requires close decoupling of 0.1-µF capacitor to GND_B. PVDD_C 23 26 P Power supply input for half-bridge C. Requires close decoupling of 0.1-µF capacitor to GND_C. PVDD_D 18 31 P Power supply input for half-bridge D. Requires close decoupling of 0.1-µF capacitor to GND_D. PVDD_D 18 31 P Power supply input for half-bridge D. Requires close decoupling of 0.1-µF capacitor to GND_D. PVDD_D 18 31 P Power supply input for half-bridge D. Requires close decoupling of 0.1-µF capacitor to GND_D. PVM_A 8 9 I Input signal for half-bridge B PVM_C 10 7 I Input signal for half-bridge C PVM_D 11 6 I Input signal for half-bridge C PVM_D 11 6 I Input signal for half-bridge C Controls start/stop time of PVM modulation. Requires 2.2 nF capacitor to GND ENT mode. Also, leave pin floating for found for AB ENT. Leave pin floating (NC) for BD BTL mode. Also, leave pin floating for floating pin floating (NC) for BD BTL mode. Also, leave pin floating for floating found for half-bridge D	PGND_AB	29	20	Р	Power ground for half-bridges A and B
PGND_CD 20 29 P Power ground for half-bridge D GVDD_AB 1 16 P Gate-drive voltage supply. Requires 1-μF capacitor to GND. GVDD_CD 16 1 P Gate-drive voltage supply. Requires 1-μF capacitor to GND. M2 15 2 I Mode selection 2, connect to either AGND or VREG, no pull-up or pull-down resistors M1 14 3 I Mode selection 1, connect to either AGND or VREG, no pull-up or pull-down resistors OC_ADJ 13 4 O Analog overcurrent programming. Requires resistor to ground. OTW 6 11 O Overtemperature warning signal, push-pull, active high OUT_A 30 19 O Output, half-bridge A OUT_B 27 22 O Output, half-bridge B OUT_D 19 30 O Output, half-bridge C OUT_D 19 30 O Output, half-bridge A PVDD_B 26 23 P Power supply input for half-bridge A. Requires close decoupling of 0.1-μF capacitor to GND_D. <	PGND_AB	28	21	Р	Power ground for half-bridges A and B
GVDD_AB 1 166 P Gate-drive voltage supply. Requires 1-μF capacitor to GND. GVDD_CD 16 1 P Gate-drive voltage supply. Requires 1-μF capacitor to GND. M2 15 2 I Mode selection 2, connect to either AGND or VREG, no pull-up or pull-down resistors M1 14 3 I Mode selection 1, connect to either AGND or VREG, no pull-up or pull-down resistors OC_ADJ 13 4 O Analog overcurrent programming. Requires resistor to ground. OTW 6 11 O Overtemperature warning signal, push-pull, active high OUT_A 30 19 O Output, half-bridge A OUT_B 27 22 O Output, half-bridge B OUT_C 22 27 O Output, half-bridge C OUT_D 19 30 O Output, half-bridge D PVDD_A 31 18 P Power supply input for half-bridge A. Requires close decoupling of 0.1-μF capacitor to GND_A. PVDD_B 26 23 P Power supply input for half-bridge B. Requires close decoupling of 0.1-μF capacitor to GND_B. PVDD_C 23 26 P Power supply input for half-bridge C. Requires close decoupling of 0.1-μF capacitor to GND_B. PVDD_D 18 31 P Power supply input for half-bridge C. Requires close decoupling of 0.1-μF capacitor to GND_B. PVDD_D 18 31 P Power supply input for half-bridge C. Requires close decoupling of 0.1-μF capacitor to GND_D. PVM_A 8 9 I Input signal for half-bridge B PWM_B 9 8 I Input signal for half-bridge B PWM_B 9 8 I Input signal for half-bridge C PWM_B 9 8 I Input signal for half-bridge C PWM_D 11 6 I Input signal for half-bridge D RESET 7 10 I PWM is not active if RESET goes low. Controls start/stop time of PWM modulation. Requires 2.2 nF capacitor to GND ENTL mode. Also, leave pin floating	PGND_CD	21	28	Р	Power ground for half-bridges C and D
GVDD_CD 16 1 P Gate-drive voltage supply. Requires 1-µF capacitor to GND. M2 15 2 I Mode selection 2, connect to either AGND or VREG, no pull-up or pull-down resistors M1 14 3 I Mode selection 1, connect to either AGND or VREG, no pull-up or pull-down resistors OC_ADJ 13 4 O Analog overcurrent programming. Requires resistor to ground. OTW 6 11 O Overtemperature warning signal, push-pull, active high OUT_A 30 19 O Output, half-bridge A OUT_B 27 22 O Output, half-bridge B OUT_C 22 27 O Output, half-bridge C OUT_D 19 30 O Output, half-bridge D PVDD_A 31 18 P Power supply input for half-bridge A. Requires close decoupling of 0.1-µF capacitor to GND_A. PVDD_B 26 23 P Power supply input for half-bridge B. Requires close decoupling of 0.1-µF capacitor to GND_B. PVDD_C 23 26 P Power supply input for half-bridge C. Requires close decoupling of 0.1-µF capacitor to GND_B. PVDD_D 18 31 P Power supply input for half-bridge D. Requires close decoupling of 0.1-µF capacitor to GND_C. PVDD_D 18 31 P Power supply input for half-bridge D. Requires close decoupling of 0.1-µF capacitor to GND_C. PVM_A 8 9 I Input signal for half-bridge B PWM_B 9 8 I Input signal for half-bridge B PWM_C 10 7 I Input signal for half-bridge C PWM_D 11 6 I Input signal for half-bridge C RESET 7 10 I PWM is not active if RESET goes low. Controls start/stop time of PWM modulation. Requires 2.2 nF capacitor to GN B STIMER 5 12 I for AD BTL. Leave pin floating (NC) for BD BTL mode. Also, leave pin floating (NC) for BD BTL mode.	PGND_CD	20	29	Р	Power ground for half-bridge D
M2 15 2 I Mode selection 2, connect to either AGND or VREG, no pull-up or pull-down resistors M1 14 3 I Mode selection 1, connect to either AGND or VREG, no pull-up or pull-down resistors OC_ADJ 13 4 O Analog overcurrent programming. Requires resistor to ground. OTW 6 11 O Overtemperature warning signal, push-pull, active high OUT_A 30 19 O Output, half-bridge A OUT_B 27 22 O Output, half-bridge B OUT_C 22 27 O Output, half-bridge C OUT_D 19 30 O Output, half-bridge D PVDD_A 31 18 P Power supply input for half-bridge A. Requires close decoupling of 0.1-μF capacitor to GND_A. PVDD_B 26 23 P Power supply input for half-bridge B. Requires close decoupling of 0.1-μF capacitor to GND_C. PVDD_D 18 31 P Power supply input for half-bridge C. Requires close decoupling of 0.1-μF capacitor to GND_C. PVDD_D 18 31 P Power supply input for half-bridge D. Requires close decoupling of 0.1-μF capacitor to GND_D. PVM_A 8 9 I Input signal for half-bridge B PWM_B 9 8 I Input signal for half-bridge B PWM_C 10 7 I Input signal for half-bridge C PWM_D 11 6 I Input signal for half-bridge D RESET 7 10 I PWM is not active if RESET goes low. Controls start/stop time of PWM modulation. Requires 2.2 n F capacitor to GND STILL Leave pin floating (NC) for BD BTL mode. Also, leave pin floating for AD BTL. Leave pin floating (NC) for BD BTL mode. Also, leave pin floating for AD BTL. Leave pin floating (NC) for BD BTL mode. Also, leave pin floating for AD BTL. Leave pin floating (NC) for BD BTL mode. Also, leave pin floating for AD BTL. Leave pin floating (NC) for BD BTL mode. Also, leave pin floating for AD BTL. Leave pin floating (NC) for BD BTL mode. Also, leave pin floating for AD BTL. Leave pin floating (NC) for BD BTL mode. Also, leave pin floating for AD BTL. Leave pin floating (NC) for BD BTL mode. Also, leave pin floating for AD BTL. Leave pin floating (NC) for BD BTL mode. Also, leave pin floating for AD BTL Leave pin floating f	GVDD_AB	1	16	Р	Gate-drive voltage supply. Requires 1-μF capacitor to GND.
M1 14 3 I resistors Mode selection 1, connect to either AGND or VREG, no pull-up or pull-down resistors OC_ADJ 13 4 O Analog overcurrent programming. Requires resistor to ground. OTW 6 11 O Overtemperature warning signal, push-pull, active high OUT_A 30 19 O Output, half-bridge A OUT_B 27 22 O Output, half-bridge B OUT_C 22 27 O Output, half-bridge C OUT_D 19 30 O Output, half-bridge D PVDD_A 31 18 P Power supply input for half-bridge A. Requires close decoupling of 0.1-μF capacitor to GND_A. PVDD_B 26 23 P Power supply input for half-bridge B. Requires close decoupling of 0.1-μF capacitor to GND_B. PVDD_D 18 31 P Power supply input for half-bridge C. Requires close decoupling of 0.1-μF capacitor to GND_C. PVDD_D 18 31 P Power supply input for half-bridge D. Requires close decoupling of 0.1-μF capacitor to GND_C. PVM_A 8 9 I Input signal for half-bridge B PWM_A 8 9 I Input signal for half-bridge B PWM_C 10 7 I Input signal for half-bridge C PWM_D 11 6 I Input signal for half-bridge D RESET 7 10 I PWM is not active if RESET goes low. Controls start/stop time of PWM modulation. Requires 2.2 n F capacitor to GND STIL. Leave pin floating (NC) for BD BTL mode. Also, leave pin floating for AD BTL. Leave pin floating (NC) for BD BTL mode. Also, leave pin floating for AD BTL. Leave pin floating (NC) for BD BTL mode. Also, leave pin floating for AD BTL. Leave pin floating (NC) for BD BTL mode. Also, leave pin floating for AD BTL. Leave pin floating (NC) for BD BTL mode. Also, leave pin floating for AD BTL. Leave pin floating (NC) for BD BTL mode. Also, leave pin floating for AD BTL. Leave pin floating (NC) for BD BTL mode. Also, leave pin floating for AD BTL. Leave pin floating (NC) for BD BTL mode. Also, leave pin floating for AD BTL. Leave pin floating (NC) for BD BTL mode. Also, leave pin floating for AD BTL Leave pin floating (NC) for BD BTL mode. Also, leave pin floating for AD BTL Leave pin floating for AD B	GVDD_CD	16	1	Р	Gate-drive voltage supply. Requires 1-μF capacitor to GND.
OC_ADJ 13 4 O Analog overcurrent programming. Requires resistor to ground. OTW 6 11 O Overtemperature warning signal, push-pull, active high OUT_A 30 19 O Output, half-bridge A OUT_B 27 22 O Output, half-bridge B OUT_C 22 27 O Output, half-bridge C OUT_D 19 30 O Output, half-bridge D PVDD_A 31 18 P Power supply input for half-bridge A. Requires close decoupling of 0.1-μF capacitor to GND_A. PVDD_B 26 23 P Power supply input for half-bridge B. Requires close decoupling of 0.1-μF capacitor to GND_B. PVDD_D 18 31 P Power supply input for half-bridge C. Requires close decoupling of 0.1-μF capacitor to GND_C. PVDD_D 18 31 P Power supply input for half-bridge D. Requires close decoupling of 0.1-μF capacitor to GND_D. PVM_A 8 9 I Input signal for half-bridge A PWM_B 9 8 I Input signal for half-bridge B PWM_C 10 7 I Input signal for half-bridge C PWM_D 11 6 I Input signal for half-bridge C SSTIMER 5 12 I PWM is not active if RESET goes low. Controls start/stop time of PWM modulation. Requires 2.2 nF capacitor to GN BTL mode. Also, leave pin floating SSTIMER of the Also, leave pin floating to the Also, leave pin floating the Also, leave pin floating the Also is the Also in the Also in the Also is the Also in	M2	15	2	I	
OTW 6 11 O Overtemperature warning signal, push-pull, active high OUT_A 30 19 O Output, half-bridge A OUT_B 27 22 O Output, half-bridge B OUT_C 22 27 O Output, half-bridge C OUT_D 19 30 O Output, half-bridge D PVDD_A 31 18 P Power supply input for half-bridge A. Requires close decoupling of 0.1-μF capacitor to GND_A. PVDD_B 26 23 P Power supply input for half-bridge B. Requires close decoupling of 0.1-μF capacitor to GND_B. PVDD_C 23 26 P Power supply input for half-bridge C. Requires close decoupling of 0.1-μF capacitor to GND_C. PVDD_D 18 31 P Power supply input for half-bridge D. Requires close decoupling of 0.1-μF capacitor to GND_D. PVM_A 8 9 I Input signal for half-bridge D. Requires close decoupling of 0.1-μF capacitor to GND_D. PWM_B 9 8 I Input signal for half-bridge A PWM_C 10 7 I Input signal for half-bridge C PWM_D 11 6 I Input signal for half-bridge D RESET 7 10 I PWM is not active if RESET goes low. Controls start/stop time of PWM modulation. Requires 2.2 nF capacitor to GN BTL. Leave pin floating (NC) for BD BTL mode. Also, leave pin floating SSTIMER	M1	14	3	I	
OUT_A 30 19 O Output, half-bridge A OUT_B 27 22 O Output, half-bridge B OUT_C 22 27 O Output, half-bridge C OUT_D 19 30 O Output, half-bridge D PVDD_A 31 18 P Power supply input for half-bridge A. Requires close decoupling of 0.1-μF capacitor to GND_A. PVDD_B 26 23 P Power supply input for half-bridge B. Requires close decoupling of 0.1-μF capacitor to GND_B. PVDD_C 23 26 P Power supply input for half-bridge C. Requires close decoupling of 0.1-μF capacitor to GND_C. PVDD_D 18 31 P Power supply input for half-bridge D. Requires close decoupling of 0.1-μF capacitor to GND_C. PVM_A 8 9 I Input signal for half-bridge A PWM_B 9 8 I Input signal for half-bridge B PWM_C 10 7 I Input signal for half-bridge C PWM_D 11 6 I Input signal for half-bridge C RESET 7 10 I PWM is not active if RESET goes low. Controls start/stop time of PWM modulation. Requires 2.2 nF capacitor to GND STL heave pin floating (NC) for BD BTL mode. Also, leave pin floating the put in the put	OC_ADJ	13	4	0	Analog overcurrent programming. Requires resistor to ground.
OUT_B OUT_C OUT_C OUT_D O	OTW	6	11	0	Overtemperature warning signal, push-pull, active high
OUT_C 22 27 O Output, half-bridge C OUT_D 19 30 O Output, half-bridge D PVDD_A 31 18 P Power supply input for half-bridge A. Requires close decoupling of 0.1-μF capacitor to GND_A. PVDD_B 26 23 P Power supply input for half-bridge B. Requires close decoupling of 0.1-μF capacitor to GND_B. PVDD_C 23 26 P Power supply input for half-bridge C. Requires close decoupling of 0.1-μF capacitor to GND_C. PVDD_D 18 31 P Power supply input for half-bridge D. Requires close decoupling of 0.1-μF capacitor to GND_D. PWM_A 8 9 I Input signal for half-bridge A PWM_B 9 8 I Input signal for half-bridge B PWM_C 10 7 I Input signal for half-bridge C PWM_D 11 6 I Input signal for half-bridge D RESET 7 10 I PWM is not active if RESET goes low. SSTIMER 5 12 I Controls start/stop time of PWM modulation. Requires 2.2 nF capacitor to GN port AD BTL. Leave pin floating (NC) for BD BTL mode. Also, leave pin floating the port AD BTL. </td <td>OUT_A</td> <td>30</td> <td>19</td> <td>0</td> <td>Output, half-bridge A</td>	OUT_A	30	19	0	Output, half-bridge A
OUT_D 19 30 O Output, half-bridge D PVDD_A 31 18 P Power supply input for half-bridge A. Requires close decoupling of 0.1-μF capacitor to GND_A. PVDD_B 26 23 P Power supply input for half-bridge B. Requires close decoupling of 0.1-μF capacitor to GND_B. PVDD_C 23 26 P Power supply input for half-bridge C. Requires close decoupling of 0.1-μF capacitor to GND_C. PVDD_D 18 31 P Power supply input for half-bridge D. Requires close decoupling of 0.1-μF capacitor to GND_D. PWM_A 8 9 I Input signal for half-bridge A PWM_B 9 8 I Input signal for half-bridge B PWM_C 10 7 I Input signal for half-bridge C PWM_D 11 6 I Input signal for half-bridge D RESET 7 10 I PWM is not active if RESET goes low. Controls start/stop time of PWM modulation. Requires 2.2 nF capacitor to GND STIMER 5 12 I Controls start/stop time of PWM modulation. Requires 2.2 nF capacitor to GND STIMER ST	OUT_B	27	22	0	Output, half-bridge B
PVDD_A 31 18 P Power supply input for half-bridge A. Requires close decoupling of 0.1-μF capacitor to GND_A. PVDD_B 26 23 P Power supply input for half-bridge B. Requires close decoupling of 0.1-μF capacitor to GND_B. PVDD_C 23 26 P Power supply input for half-bridge C. Requires close decoupling of 0.1-μF capacitor to GND_C. PVDD_D 18 31 P Power supply input for half-bridge D. Requires close decoupling of 0.1-μF capacitor to GND_D. PWM_A 8 9 I Input signal for half-bridge A PWM_B 9 8 I Input signal for half-bridge B PWM_C 10 7 I Input signal for half-bridge C PWM_D 11 6 I Input signal for half-bridge D RESET 7 10 I PWM is not active if RESET goes low. SSTIMER 5 12 I Controls start/stop time of PWM modulation. Requires 2.2 nF capacitor to GN for AD BTL. Leave pin floating (NC) for BD BTL mode. Also, leave pin floating the properties of the prope	OUT_C	22	27	0	Output, half-bridge C
PVDD_B 26 23 P Power supply input for half-bridge B. Requires close decoupling of 0.1-μF capacitor to GND_B. PVDD_C 23 26 P Power supply input for half-bridge C. Requires close decoupling of 0.1-μF capacitor to GND_C. PVDD_D 18 31 P Power supply input for half-bridge D. Requires close decoupling of 0.1-μF capacitor to GND_D. PWM_A 8 9 I Input signal for half-bridge B PWM_C 10 7 I Input signal for half-bridge C PWM_D 11 6 I Input signal for half-bridge D RESET 7 10 I PWM is not active if RESET goes low. Controls start/stop time of PWM modulation. Requires 2.2 nF capacitor to GN BTL. Leave pin floating (NC) for BD BTL mode. Also, leave pin floating to the properties of th	OUT_D	19	30	0	Output, half-bridge D
PVDD_C 23 26 P Power supply input for half-bridge C. Requires close decoupling of 0.1-μF capacitor to GND_C. PVDD_D 18 31 P Power supply input for half-bridge D. Requires close decoupling of 0.1-μF capacitor to GND_D. PWM_A 8 9 I Input signal for half-bridge A PWM_B 9 8 I Input signal for half-bridge B PWM_C 10 7 I Input signal for half-bridge C PWM_D 11 6 I Input signal for half-bridge D RESET 7 10 I PWM is not active if RESET goes low. Controls start/stop time of PWM modulation. Requires 2.2 nF capacitor to GN BTL. Leave pin floating (NC) for BD BTL mode. Also, leave pin floating to the production of t	PVDD_A	31	18	Р	
PVDD_D 18 31 P Power supply input for half-bridge D. Requires close decoupling of 0.1-μF capacitor to GND_D. PWM_A 8 9 I Input signal for half-bridge A PWM_B 9 8 I Input signal for half-bridge B PWM_C 10 7 I Input signal for half-bridge C PWM_D 11 6 I Input signal for half-bridge D RESET 7 10 I PWM is not active if RESET goes low. Controls start/stop time of PWM modulation. Requires 2.2 nF capacitor to GN Controls start/stop time of PWM modulation. Requires 2.2 nF capacitor to GN for AD BTL. Leave pin floating (NC) for BD BTL mode. Also, leave pin floating	PVDD_B	26	23	Р	
PWM_A 8 9 I Input signal for half-bridge A PWM_B 9 8 I Input signal for half-bridge B PWM_C 10 7 I Input signal for half-bridge C PWM_D 11 6 I Input signal for half-bridge D RESET 7 10 I PWM is not active if RESET goes low. Controls start/stop time of PWM modulation. Requires 2.2 nF capacitor to GN SSTIMER 5 12 I for AD BTL. Leave pin floating (NC) for BD BTL mode. Also, leave pin floating	PVDD_C	23	26	Р	
PWM_B 9 8 I Input signal for half-bridge B PWM_C 10 7 I Input signal for half-bridge C PWM_D 11 6 I Input signal for half-bridge D RESET 7 10 I PWM is not active if RESET goes low. Controls start/stop time of PWM modulation. Requires 2.2 nF capacitor to GN for AD BTL. Leave pin floating (NC) for BD BTL mode. Also, leave pin floating	PVDD_D	18	31	Р	
PWM_C 10 7 I Input signal for half-bridge C PWM_D 11 6 I Input signal for half-bridge D RESET 7 10 I PWM is not active if RESET goes low. Controls start/stop time of PWM modulation. Requires 2.2 nF capacitor to GN for AD BTL. Leave pin floating (NC) for BD BTL mode. Also, leave pin floating	PWM_A	8	9	I	Input signal for half-bridge A
PWM_D 11 6 I Input signal for half-bridge D RESET 7 10 I PWM is not active if RESET goes low. Controls start/stop time of PWM modulation. Requires 2.2 nF capacitor to GN for AD BTL. Leave pin floating (NC) for BD BTL mode. Also, leave pin floating	PWM_B	9	8	I	Input signal for half-bridge B
RESET 7 10 I PWM is not active if RESET goes low. Controls start/stop time of PWM modulation. Requires 2.2 nF capacitor to GN for AD BTL. Leave pin floating (NC) for BD BTL mode. Also, leave pin floating	PWM_C	10	7	I	Input signal for half-bridge C
Controls start/stop time of PWM modulation. Requires 2.2 nF capacitor to GN SSTIMER 5 12 I for AD BTL. Leave pin floating (NC) for BD BTL mode. Also, leave pin floating	PWM_D	11	6	I	Input signal for half-bridge D
SSTIMER 5 12 I for AD BTL. Leave pin floating (NC) for BD BTL mode. Also, leave pin floating	RESET	7	10	I	PWM is not active if RESET goes low.
	SSTIMER	5	12	I	Controls start/stop time of PWM modulation. Requires 2.2 nF capacitor to GND for AD BTL. Leave pin floating (NC) for BD BTL mode. Also, leave pin floating (NC) for SE mode.
VREG 2 15 P Digital regulator supply filter. Requires 0.1-μF capacitor to AGND.	VREG	2	15	Р	Digital regulator supply filter. Requires 0.1-μF capacitor to AGND.

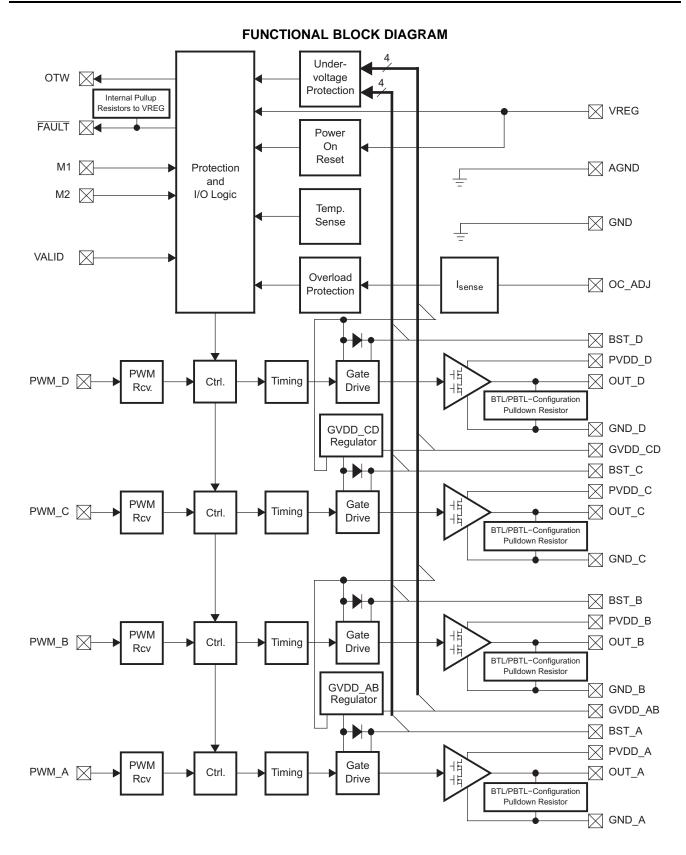
⁽¹⁾ I = input, O = output, P = power



SYSTEM BLOCK DIAGRAM









RECOMMENDED OPERATING CONDITIONS

			MIN	TYP	MAX	UNIT
V	Half-bridge supply, PVDD_X	DC supply voltage	8	18	23	V
V_{SS}	Supply for Protection and I/O Logic, VREG	DC supply voltage	3	3.3	3.6	V
R _L (BTL)		Output filter: L = 10 μH, C = 470 nF.		6-8		
R _L (SE)	Load impedance	Output AD modulation, switching		3-4		Ω
R _L (PBTL)		frequency > 350 kHz		3-4		
L _O (BTL)				200		
L _O (SE)	Output-filter inductance	Minimum output inductance under short-circuit condition		200		nΗ
L _O (PBTL)		Short chourt condition		200		
F _{PWM}	PWM frame rate		192	384	432	kHz
TJ	Junction temperature		0		125	°C

AC Characteristics (BTL)

PVDD_X = 18 V, BTL mode, $R_L = 8~\Omega$, $R_{OC} = 22~K\Omega$, $C_{BST} = 33$ -nF, audio frequency = 1 kHz, AES17 filter, $F_{PWM} = 384~kHz$, ambient temperature = 25°C (unless otherwise noted). Audio performance is recorded as a chipset, using TAS5086 PWM processor with an effective modulation index limit of 96.1%. All performance is in accordance with recommended operating conditions, unless otherwise specified.

	PARAMETER	TEST CONDITIONS		TYP	MAX	UNIT		
		PVDD = 18 V, 10% THD						
D		PVDD = 18 V, 7% THD	18			10/		
Po	Power output per channel	PVDD = 12 V, 10% THD		9		W		
		PVDD = 12 V, 7% THD		8				
	Total harmonic distortion + noise	PVDD = 18V, Po =10 W (half-power)	0.15					
THD+N		PVDD = 12V, Po =4.5 W (half-power)		0.18		%		
		1 W		0.05				
V _n	Output integrated noise	A-weighted		50		μV		
SNR	Signal-to-noise ratio (1)	A-weighted	94	105		dB		
DNR	Dynamic range	A-weighted, input level = -60 dBFS using TAS5086 modulator	94	105		dB		
P _D	Power dissipation due to idle losses (IPVDD_X)	P _O = 0 W, 4 channels switching ⁽²⁾		0.6		W		

⁽¹⁾ SNR is calculated relative to 0-dBFS input level.

⁽²⁾ Actual system idle losses are affected by core losses of output inductors.



AC Characteristics (Single-Ended Output)

PVDD_X = 18 V, SE mode, R_L = 4 Ω , R_{OC} = 22 $k\Omega$, C_{BST} = 33-nF, audio frequency = 1 kHz, AES17 filter, F_{PWM} = 384 kHz, ambient temperature = 25°C (unless otherwise noted). Audio performance is recorded as a chipset, using TAS5086 PWM processor with an effective modulation index limit of 96.1%. All performance is in accordance with recommended operating conditions, unless otherwise specified.

	PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT	
		PVDD = 18 V, 10% THD		10			
Б	Dower cutnut nor channel	PVDD = 18 V, 7% THD		9		10/	
Po	Power output per channel	PVDD = 12 V, 10% THD		4.5		W	
		PVDD = 12 V, 7% THD		4		1	
THD+	Total harmonic distortion + noise	PVDD = 18V, Po =5 W (half-power)		0.2		%	
N	Total narmonic distortion + noise	PVDD = 12V, Po =2.25 W (half-power)		0.2		70	
V_n	Output integrated noise	A-weighted		50		μV	
SNR	Signal-to-noise ratio ⁽¹⁾	A-weighted		105		dB	
DNR	Dynamic range	A-weighted, input level = -60 dBFS using TAS5086 modulator		105		dB	
P _D	Power dissipation due to idle losses (IPVDD_X)	P _O = 0 W, 4 channels switching ⁽²⁾		0.6		W	

⁽¹⁾ SNR is calculated relative to 0-dBFS input level.

⁽²⁾ Actual system idle losses are affected by core losses of output inductors.



DC Characteristics

 R_L = 8 Ω , F_{PWM} = 384 kHz (unless otherwise noted). All performance is in accordance with recommended operating conditions, unless otherwise specified.

	PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT
Internal Volta	ge Regulator and Current Consumption		ļ			
V _{SS}	Digital Input Supply Voltage, VREG		3	3.3	3.6	V
1	Supply ourrent VPEC	Operating, 50% duty cycle		6.5	10	A
I _(VREG)	Supply current, VREG	Reset mode, no switching		6.5	10	mA
	Total Half builder idle sument	50% duty cycle, without output filter or load		35	50	Λ
I _(PVDD_X)	Total Half-bridge idle current	Reset mode, no switching		5	6.3	mA
Output Stage	MOSFETs		ļ			
D	Drain-to-source resistance, LS	T _J = 25°C, includes metallization resistance		180		mΩ
R _{DS(on)}	Drain-to-source resistance, HS	T _J = 25°C, includes metallization resistance		180		mΩ
I/O Protection	1					
$V_{\text{uvp,G}}$	Undervoltage protection limit, GVDD_X, voltage rising			5.7		V
$V_{\text{uvp,G}}$	Undervoltage protection limit, GVDD_X, voltage falling			5.5		٧
OTW ⁽¹⁾	Overtemperature warning			125		°C
OTW _{HYST} ⁽¹⁾	Temperature drop needed below OTW temperature for OTW to be inactive after the OTW event			25		°C
OTE ⁽¹⁾	Overtemperature error			150		°Ç
OTE-OTW ⁽¹⁾	OTE-OTW differential			25		°C
OTE _{HYST} ⁽¹⁾	A RESET must occur to exit shutdown and to release FAULT following an OTE event.			30		°C
OCPC	Overcurrent protection counter	F _{PWM} = 384 kHz		0.63		ms
loc	Overcurrent limit protection	Resistor—programmable, max. current, $R_{OCP} = 22 \text{ k}\Omega$		4.5		Α
I _{OCT}	Overcurrent response time			150		ns
R _{OCP}	OC programming resistor range	Resistor tolerance = 5% for typical value; the minimum resistance should not be less than $20k\Omega$.	20	22	24	kΩ
R _{PD}	Internal pulldown resistor at the output of each half-bridge	Connected when RESET is active to provide bootstrap capacitor charge. Not used in SE mode		3		kΩ

⁽¹⁾ Specified by design

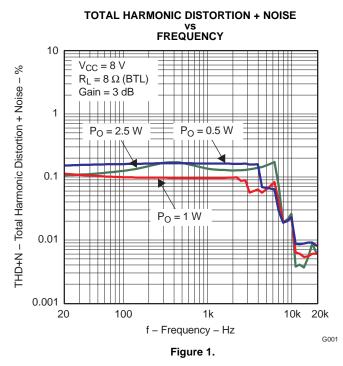


DC Characteristics (continued)

 R_L = 8 Ω , F_{PWM} = 384 kHz (unless otherwise noted). All performance is in accordance with recommended operating conditions, unless otherwise specified.

PARAMETER		TEST CONDITIONS		TYP	MAX	UNIT	
Static Digi	tal Specifications		•				
V _{IH}	High-level input voltage	PWM_A, PWM_B, PWM_C, PWM_D, M1, M2,	2			V	
V _{IL}	Low-level input voltage	RESET			8.0	V	
	Static, High PWM_A, PWM_B, PWM_C, PWM_D, M1, M2, RESET			100	^		
^I lkg	Input leakage current	Static, Low PWM_A, PWM_B, PWM_C, PWM_D, M1, M2, RESET	-10		10	μΑ	
FAULT			•				
R _{INT_PU}	Internal pullup resistance, FAULT		20	26	32	kΩ	
V _{OH}	High lovel output voltage	Internal pullup resistor	3	3.3	3.6	V	
	High-level output voltage	External pullup of 4.7 kΩ to 5 V			5.5	V	
V _{OL}	Low-level output voltage	I _O = 4 mA		0.25	0.5	V	

TYPICAL CHARACTERISTICS



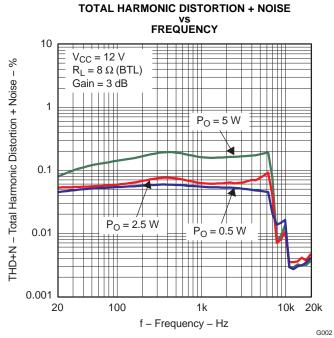


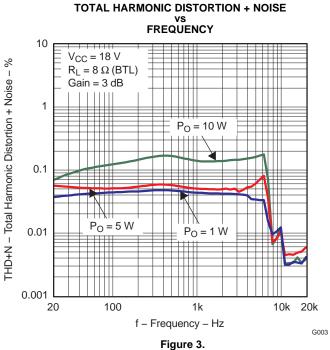
Figure 2.

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TYPICAL CHARACTERISTICS (continued)



TOTAL HARMONIC DISTORTION + NOISE vs OUTPUT POWER

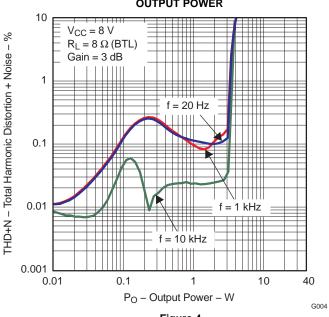
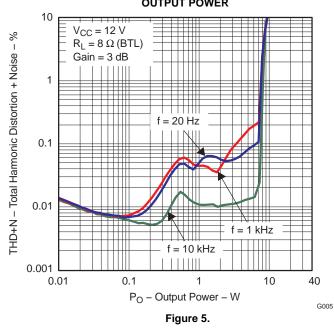


Figure 4.

TOTAL HARMONIC DISTORTION + NOISE vs OUTPUT POWER



TOTAL HARMONIC DISTORTION + NOISE vs OUTPUT POWER

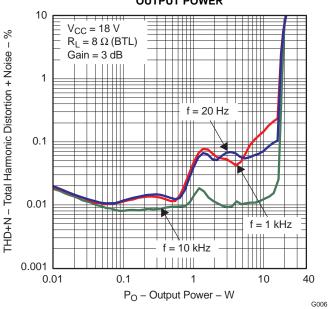
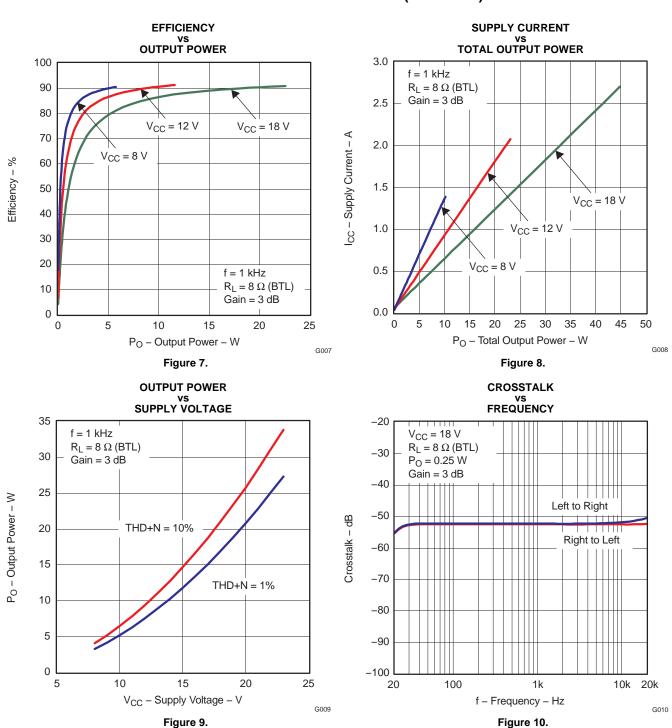


Figure 6.



TYPICAL CHARACTERISTICS (continued)





TYPICAL CHARACTERISTICS (continued)

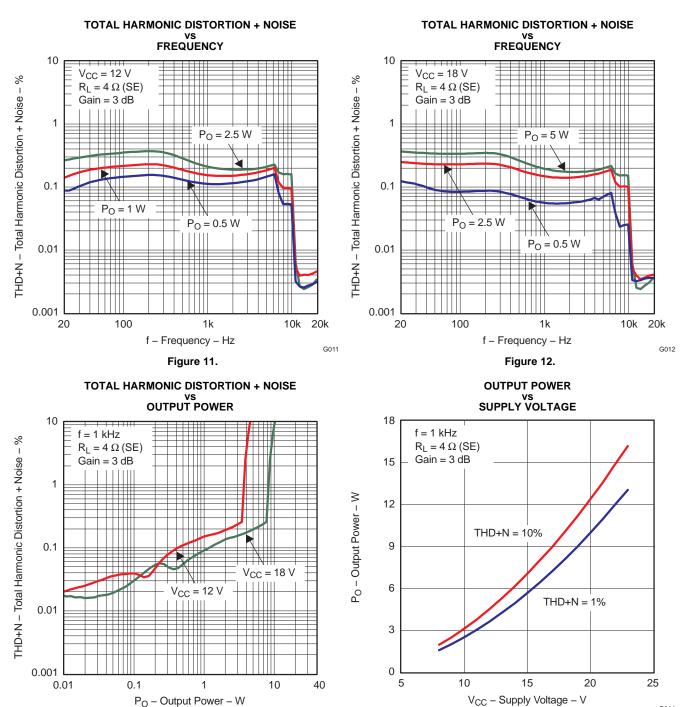


Figure 13.

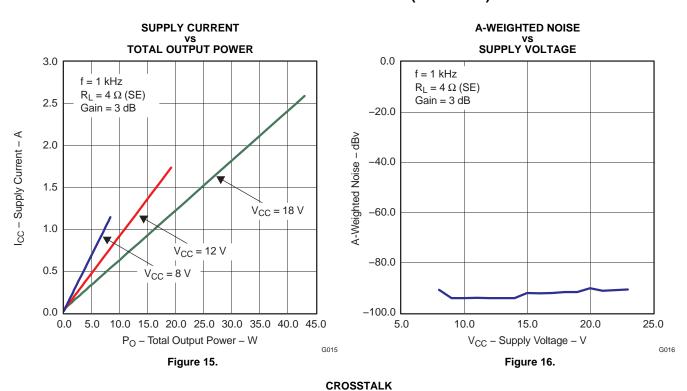
Figure 14.

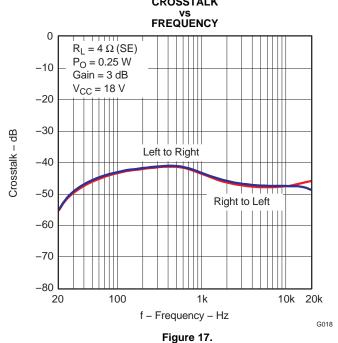
G014

G013

TEXAS INSTRUMENTS

TYPICAL CHARACTERISTICS (continued)







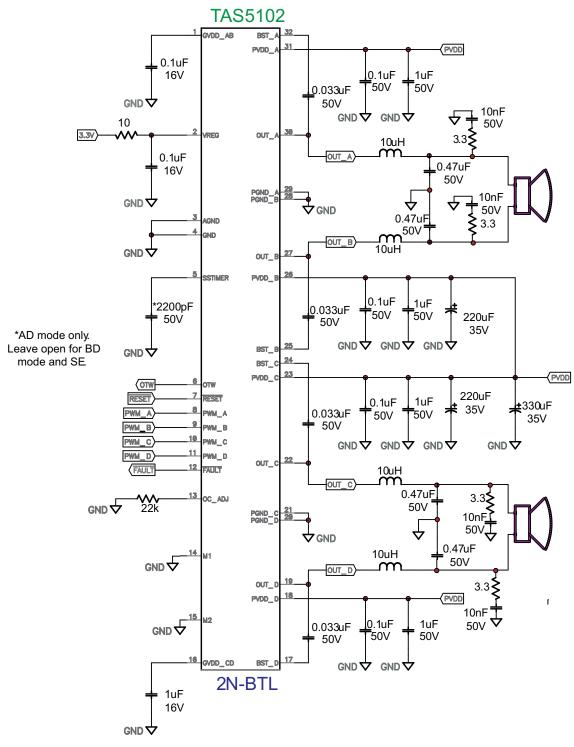


Figure 18. Typical Differential (2N) BTL Application With AD Modulation Filters



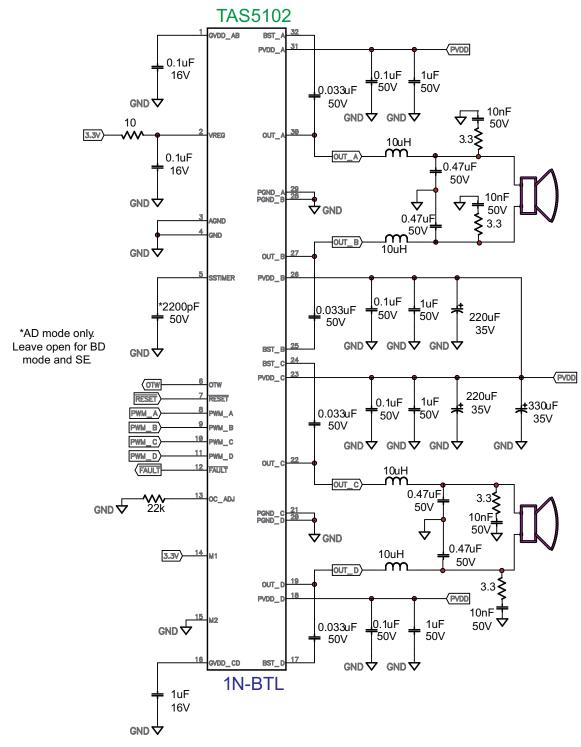


Figure 19. Typical Non-Differential (1N) BTL Application With AD Modulation Filters



THEORY OF OPERATION

POWER SUPPLIES

To facilitate system design, the TAS5102/3 needs only a 3.3-V supply in addition to the (typical) 18-V power-stage supply. An internal voltage regulator provides suitable voltage levels for the gate drive circuitry. Additionally, all circuitry requiring a floating voltage supply, e.g., the high-side gate drive, is accommodated by built-in bootstrap circuitry requiring only a few external capacitors.

In order to provide outstanding electrical and acoustical characteristics, the PWM signal path for the output stage is designed as identical, independent half-bridges. For this reason, each half-bridge has separate bootstrap pins (BST_X), and power-stage supply pins (PVDD_X). The gate drive voltages (GVDD AB and GVDD CD) are derived from the PVDD voltage. Separate, internal voltage regulators reduce and regulate the PVDD voltage to a voltage appropriate for efficient gave drive operation. Furthermore, an additional pin (VREG) is provided as supply for all common logic circuits. Special attention should be paid to placing all decoupling capacitors as close to their associated pins as possible. In general, inductance between the power supply pins and decoupling capacitors must be avoided. (See reference board documentation for additional information.)

For a properly functioning bootstrap circuit, a small ceramic capacitor must be connected from each bootstrap pin (BST_X) to the power-stage output pin (OUT X). When the power-stage output is low, the bootstrap capacitor is charged through an internal diode connected between the gate-drive powersupply pin (GVDD X) and the bootstrap pin. When the power-stage output is high, the bootstrap capacitor potential is shifted above the output potential and thus provides a suitable voltage supply for the high-side gate driver. In an application with PWM switching frequencies in the range from 352 kHz to 384 kHz, it is recommended to use 33-nF ceramic capacitors, size 0603 or 0805, for the bootstrap supply. These 33-nF capacitors ensure sufficient energy storage, even during minimal PWM duty cycles, to keep the high-side power stage FET (LDMOS) fully turned on during the remaining part of the PWM cycle. In an application running at a reduced switching frequency, generally 192 kHz, the bootstrap capacitor might need to be increased in value.

Special attention should be paid to the power-stage power supply; this includes component selection, PCB placement, and routing. As indicated, each half-bridge has independent power-stage supply pins (PVDD_X). For optimal electrical performance, EMI

compliance, and system reliability, it is important that each PVDD_X pin is decoupled with a 100-nF ceramic capacitor placed as close as possible to each supply pin. It is recommended to follow the PCB layout of the TAS5102/3 reference design. For additional information on recommended power supply and required components, see the application diagrams given previously in this data sheet.

The 3.3-V supply should be from a low-noise, low-output-impedance voltage regulator. Likewise, the 18-V power-stage supply is assumed to have low output impedance and low noise. The power-supply sequence is not critical as facilitated by the internal power-on-reset circuit. Moreover, the TAS5102/3 is fully protected against erroneous power-stage turnon due to parasitic gate charging.

INTEGRATED GATE DRIVE SUPPLY (GVDD)

The TAS5103 has an integrated gate drive supply, which eliminates the need for an external regulator. If the PVDD is 12 V (i.e., max PVDD < 13.2 V), it is possible to connect the PVDD to the GVDD through a ten ohm resistor. This will allow the power stage to operate as low a 7 V during dips. Otherwise the GVDD undervoltage protection will shutdown the outputs when the supply drops to 8 V. Care must be taken to not connect GVDD and PVDD together in this manner if the operating voltage is higher than 12 V.

SYSTEM POWER-UP/POWER-DOWN SEQUENCE

Powering Up

The outputs of the H-bridges remain in a high-impedance state until the internal gate-drive supply voltage (GVDD_XY) and external VREG voltages are above the undervoltage protection (UVP) voltage threshold (see the *Electrical Characteristics* section of this data sheet). Although not specifically required, it is recommended to hold RESET in a low state while powering up the device. This allows an internal circuit to charge the external bootstrap capacitors by enabling a weak pulldown of the half-bridge output. The output impedance approximately $3K\Omega$ under this condition, unless mode 1, 0 (Single-ended Mode), is used. This means that the TAS5102/3 should be held in reset for at least 200 µS to ensure that the bootstrap capacitors are charged. This also assumes that the recommended 0.033-uF bootstrap capacitors are used. Changes to bootstrap capacitor values will change the bootstrap capacitor charge time. To avoid pops and clicks, follow the recommended timing diagram in Figure 20.

When the TAS5102/3 is being used with TI PWM modulators such as the TAS5086, no special attention to the state of RESET is required, provided that the chipset is configured as recommended.

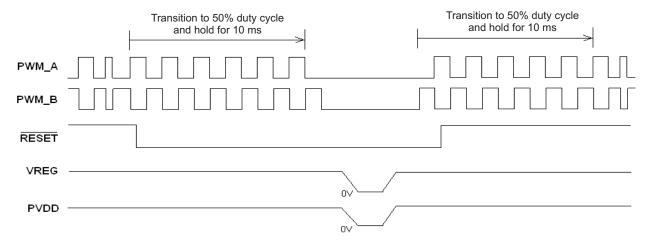


Figure 20. Power-Down/Power-Up Timing Diagram

Powering Down

The device remains fully operational as long as the gate-drive supply voltage and VREG voltages are above the undervoltage protection (UVP) voltage threshold (see the *Electrical Characteristics* section of this data sheet). Although not specifically required, it is a good practice to hold RESET low during power down, thus preventing audible artifacts, including pops or clicks. To avoid pops and clicks, follow the recommended timing diagram in Figure 20.

When the TAS5102/3 is being used with TI PWM modulators such as the TAS5086, no special attention to the state of RESET is required, provided that the chipset is configured as recommended.

ERROR REPORTING

The FAULT pin is an active-low, open-drain output. The OTW pin is a push-pull, active-high output. Their function is for protection-mode signaling to a PWM controller or other system-control device.

Any fault resulting in device shutdown is signaled by the FAULT pin going low. Likewise, OTW goes high when the device junction temperature exceeds 125°C (see Table 1).

Table 1.

FAULT	OTW	DESCRIPTION
0	0	Overcurrent (OC) or undervoltage (UVP) warning or overtemperature error (OTE)
0	1	Overtemperature warning (OTW) or overcurrent (OC) or undervoltage (UVP)

Table 1. (continued)

FAULT	OTW	DESCRIPTION
1	0	Junction temperature lower than 125°C and no faults (normal operation)
1	1	Junction temperature higher than 125°C (overtemperature warning)

Note that asserting either RESET low forces the FAULT signal high, independent of faults being present. TI recommends monitoring the OTW signal using the system microcontroller and responding to an overtemperature warning signal by, e.g., turning down the volume to prevent further heating of the device, resulting in device shutdown (OTE).

To reduce external component count, an internal pullup resistor to 3.3 V is provided on the FAULT output. Level compliance for 5-V logic can be obtained by adding external pullup resistors to 5 V (see the *Electrical Characteristics* section of this data sheet for further specifications).

DEVICE PROTECTION SYSTEM

The TAS5102/3 contains advanced protection circuitry carefully designed to facilitate system integration and ease of use, as well as to safeguard the device from permanent failure due to a wide range of fault conditions such as short circuits, overtemperature, and undervoltage. The TAS5102/3 responds to a fault by immediately setting the power stage in a high-impedance (Hi-Z) state and asserting the FAULT pin low. In situations other than overcurrent (OC) and overtemperature error (OTE), the device automatically recovers when the fault



condition has been removed. For highest possible reliability, recovering from an overcurrent fault requires external reset of the device (see the *Device Reset* section of this data sheet) no sooner than 300 ms after the shutdown.

Use of TAS5102/3 in High-Modulation-Index Capable Systems

This device requires at least 50 ns of low time on the output per 384-kHz PWM frame rate in order to keep the bootstrap capacitors charged. As an example, if the modulation index is set to 99.2% in the TAS5086, this setting allows PWM pulse durations down to 20 ns. This signal, which does not meet the 50-ns requirement, is sent to the PWM_X pin, and this low-state pulse time does not allow the bootstrap capacitor to stay charged. In this situation, the low voltage across the bootstrap capacitor can cause the bootstrap UVP circuitry to activate and shutdown the device. The TAS5102/3 device requires limiting the TAS5086 modulation index to 96.1% to keep the bootstrap capacitor charged under all signals and loads.

Therefore, TI strongly recommends using a TI PWM processor, such as TAS5508 or TAS5086, with the modulation index set at 96.1% to interface with TAS5102/3. This is done by writing 0x04 to the Modulation Limit Register (0x10) in the TAS5086 or 0x04 to the Modulation Limit Register (0x16) in the TAS5508.

Overcurrent (OC) Protection With Current Limiting

The device has independent, fast-reacting current detectors on all high-side and low-side power-stage FETs. The detector outputs are closely monitored by two protection systems. The first protection system controls the power stage in order to prevent the output current further increasing, i.e., it performs a cycle-by-cycle current-limiting function, rather than prematurely shutting down during combinations of high-level music transients and extreme speaker load impedance drops. If the high-current condition situation persists, i.e., the power stage is being overloaded, a second protection system triggers a latching shutdown, resulting in the power stage being set in the high-impedance (Hi-Z) state. Current overcurrent protection limiting and are not independent for half-bridges A and B respectively, C and D. That is, if the bridge-tied load between half-bridges A and B causes an overcurrent fault, half-bridges A, B, C, and D are shut down.

The overcurrent protection threshold is set by a resistor to ground from the OC_ADJ pin. A value of $22k\Omega$ will result in an overcurrent threshold of 4.5 A.

Overtemperature Protection

The TAS5102/3 has a two-level temperature-protection system that asserts an active-high warning signal (OTW) when the device junction temperature exceeds 125°C (nominal) and, if the device junction temperature exceeds 150°C (nominal), the device is put into thermal shutdown, resulting in all half-bridge outputs being set in the high-impedance (Hi-Z) state and FAULT being asserted low. OTE is latched in this case. To clear the OTE latch, RESET must be asserted. Thereafter, the device resumes normal operation.

Undervoltage Protection (UVP) and Power-On Reset (POR)

The UVP and POR circuits of the TAS5102/3 fully protect the device in any power-up/down and brownout situation. While powering up, the POR circuit resets the overload circuit (OLP) and ensures that all circuits are fully operational when the GVDD_XY and VREG supply voltages reach 5.7 V (typical) and 2.7 V, respectively. Although GVDD_XY and VREG are independently monitored, a supply voltage drop below the UVP threshold on VREG or either GVDD_XY pin results in all half-bridge outputs immediately being set in the high-impedance (Hi-Z) state and FAULT being asserted low. The device automatically resumes operation when all supply voltages have increased above the UVP threshold.

DEVICE RESET

One reset pin is <u>provided</u> for control of half-bridges A/B/C/D. When RESET is asserted low, all four power-stage FETs in half-bridges A, B, C, and D are forced into a high-impedance (Hi-Z) state. Thus, the reset pin is well suited for hard-muting the power stage if needed.

In BTL modes, to accommodate bootstrap charging prior to switching start, asserting the reset input low enables weak pulldown of the half-bridge outputs. In the SE mode, the weak pulldowns are not enabled, and it is therefore recommended to ensure bootstrap capacitor charging by providing a low pulse on the PWM inputs when reset is asserted high.

Asserting the reset input low removes any fault information to be signaled on the FAULT output, i.e., FAULT is forced high.

A rising-edge transition on the reset input allows the device to resume operation after an overcurrent fault.



SSTIMER FUNCTIONALITY

The SSTIMER pin uses a capacitor connected between this pin and ground to control the <u>output</u> duty cycle when a transition occurs on the RESET pin. The capacitor on the SSTIMER pin is slowly charged through an internal current source, and the charge time determines the rate at which the output transitions from a near zero duty cycle to the duty cycle that is present on the inputs. This allows for a smooth transition with no audible *pop* or *click* noises when the RESET pin transitions from high-to-low or low-to-high.

For a high-to-low transition of the RESET pin (shutdown case), it is important for the modulator to remain switching for a period of at least 10 ms (if using a 2.2 nF capacitor). Larger capacitors will increase the start-up/shutdown time, while capacitors smaller than 2.2 nF will decrease start-up/shutdown time. The inputs MUST remain switching on the shutdown transition to allow the outputs to slowly ramp down the duty cycle to near zero before completely shutting off. The SSTIMER pin should be left floating for BD modulation and also for SE (single-ended) mode.

THERMAL INFORMATION

The thermally augmented package provided with the TAS5102 is designed to be interfaced directly to a heatsink using a thermal interface compound (for example, Wakefield Engineering type 126 thermal grease.) The heatsink then absorbs heat from the IC and couples it to the local air. If the heatsink is carefully designed, this process can reach equilibrium

and heat can be continually removed from the IC. Because of the efficiency of the TAS5102, heatsinks can be used which are much smaller than those required for linear amplifiers of equivalent performance.

 $R_{\theta,JA}$ is a system thermal resistance from junction to ambient air. As such, it is a system parameter with roughly the following components: $R_{\theta JC}$ (the thermal resistance from junction to case, or in this instance the metal pad), thermal grease thermal resistance, and heatsink thermal resistance. $R_{\theta JC}$ has been provided in the Device Information section. The thermal grease thermal resistance can be calculated from the exposed pad area and the thermal grease manufacturer's area thermal resistance (expressed in °C-in²/W). The area thermal resistance of the example thermal grease with a 0.001-inch thick layer is about 0.054 °C-in²/W. The approximate exposed pad area is 0.01164 in². Dividing the example thermal grease area resistance by the area of the pad gives the actual resistance through the thermal grease, 3.3 °C/W.

Heatsink thermal resistance is generally predicted by the heatsink vendor, modeled using a continuous flow dynamics (CFD) model, or measured.

Thus for a single IC, the system $R_{\theta JA} = R_{\theta JC}$ + thermal grease resistance + heatsink resistance.

Thermal information for the TAS5103 Pad Down design can be found in TI document SLMA002B. PowerPAD Thermally Enhanced Package Application Report . Additional material regarding thermal metrics can be found in TI document SPRA953A, IC Package Thermal Metrics (Rev. A).





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PACKAGING INFORMATION

Orderable Device	Status ⁽¹⁾	Package Type	Package Drawing	Pins	Package Qty	e Eco Plan ⁽²⁾	Lead/Ball Finish	MSL Peak Temp (3)
TAS5102DAD	ACTIVE	HTSSOP	DAD	32	46	Green (RoHS & no Sb/Br)	CU NIPDAU	Level-3-260C-168 HR
TAS5102DADG4	ACTIVE	HTSSOP	DAD	32	46	Green (RoHS & no Sb/Br)	CU NIPDAU	Level-3-260C-168 HR
TAS5102DADR	ACTIVE	HTSSOP	DAD	32	2000	Green (RoHS & no Sb/Br)	CU NIPDAU	Level-3-260C-168 HR
TAS5102DADRG4	ACTIVE	HTSSOP	DAD	32	2000	Green (RoHS & no Sb/Br)	CU NIPDAU	Level-3-260C-168 HR
TAS5103DAP	ACTIVE	HTSSOP	DAP	32	46	Green (RoHS & no Sb/Br)	CU NIPDAU	Level-3-260C-168 HR
TAS5103DAPG4	ACTIVE	HTSSOP	DAP	32	46	Green (RoHS & no Sb/Br)	CU NIPDAU	Level-3-260C-168 HR
TAS5103DAPR	ACTIVE	HTSSOP	DAP	32	2000	Green (RoHS & no Sb/Br)	CU NIPDAU	Level-3-260C-168 HR
TAS5103DAPRG4	ACTIVE	HTSSOP	DAP	32	2000	Green (RoHS & no Sb/Br)	CU NIPDAU	Level-3-260C-168 HR

⁽¹⁾ The marketing status values are defined as follows:

ACTIVE: Product device recommended for new designs.

LIFEBUY: TI has announced that the device will be discontinued, and a lifetime-buy period is in effect.

NRND: Not recommended for new designs. Device is in production to support existing customers, but TI does not recommend using this part in a new design.

PREVIEW: Device has been announced but is not in production. Samples may or may not be available.

OBSOLETE: TI has discontinued the production of the device.

(2) Eco Plan - The planned eco-friendly classification: Pb-Free (RoHS), Pb-Free (RoHS Exempt), or Green (RoHS & no Sb/Br) - please check http://www.ti.com/productcontent for the latest availability information and additional product content details.

TBD: The Pb-Free/Green conversion plan has not been defined.

Pb-Free (RoHS): TI's terms "Lead-Free" or "Pb-Free" mean semiconductor products that are compatible with the current RoHS requirements for all 6 substances, including the requirement that lead not exceed 0.1% by weight in homogeneous materials. Where designed to be soldered at high temperatures, TI Pb-Free products are suitable for use in specified lead-free processes.

Pb-Free (RoHS Exempt): This component has a RoHS exemption for either 1) lead-based flip-chip solder bumps used between the die and package, or 2) lead-based die adhesive used between the die and leadframe. The component is otherwise considered Pb-Free (RoHS compatible) as defined above.

Green (RoHS & no Sb/Br): TI defines "Green" to mean Pb-Free (RoHS compatible), and free of Bromine (Br) and Antimony (Sb) based flame retardants (Br or Sb do not exceed 0.1% by weight in homogeneous material)

(3) MSL, Peak Temp. -- The Moisture Sensitivity Level rating according to the JEDEC industry standard classifications, and peak solder temperature.

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TAPE AND REEL INFORMATION





A0	Dimension designed to accommodate the component width
B0	Dimension designed to accommodate the component length
	Dimension designed to accommodate the component thickness
W	Overall width of the carrier tape
P1	Pitch between successive cavity centers

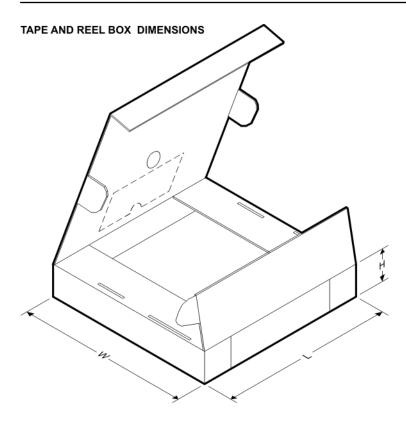
QUADRANT ASSIGNMENTS FOR PIN 1 ORIENTATION IN TAPE



*All dimensions are nominal

Device	Package Type	Package Drawing			Reel Diameter (mm)	Reel Width W1 (mm)	A0 (mm)	B0 (mm)	K0 (mm)	P1 (mm)	W (mm)	Pin1 Quadrant
TAS5102DADR	HTSSOP	DAD	32	2000	330.0	24.4	8.6	11.5	1.6	12.0	24.0	Q1
TAS5103DAPR	HTSSOP	DAP	32	2000	330.0	24.4	8.6	11.5	1.6	12.0	24.0	Q1

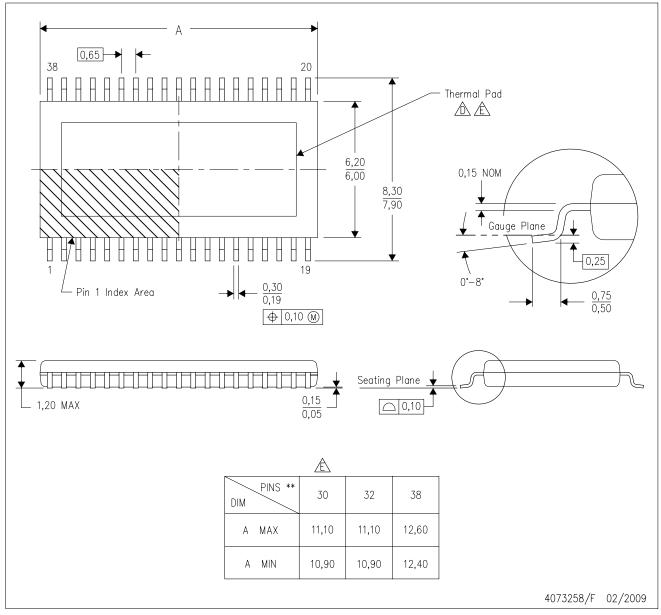




*All dimensions are nominal

Device	Package Type	Package Drawing	Pins	SPQ	Length (mm)	Width (mm)	Height (mm)
TAS5102DADR	HTSSOP	DAD	32	2000	346.0	346.0	41.0
TAS5103DAPR	HTSSOP	DAP	32	2000	346.0	346.0	41.0

DAD (R-PDSO-G**) PowerPAD™ PLASTIC SMALL-OUTLINE (DIE DOWN)
38 PIN SHOWN



NOTES:

- A. All linear dimensions are in millimeters. Dimensioning and tolerancing per ASME Y14.5M-1994.
- B. This drawing is subject to change without notice.
- C. Body dimensions do not include mold flash or protrusion. Mold flash and protrusion shall not exceed 0.15 per side.
- This package is designed to be attached directly to an external heatsink. Refer to Technical Brief, PowerPad Thermally Enhanced Package, Texas Instruments Literature No. SLMA002 for information regarding recommended board layout. This document is available at www.ti.com www.ti.com. See the product data sheet for details regarding the exposed thermal pad dimensions.
- Falls within JEDEC MO-153, except 30 pin body length and JEDEC variations for top side thermal pad.

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