



General Description

The MAX7360 I²C-interfaced peripheral provides microprocessors with management of up to 64 key switches, with an additional eight LED drivers/GPIOs that feature constant-current, PWM intensity control, and rotary switch control options.

The key-switch drivers interface with metallic or resistive switches with on-resistances up to $5k\Omega$. Key inputs are monitored statically, not dynamically, to ensure low-EMI operation. The MAX7360 features autosleep and autowake modes to further minimize the power consumption of the device. The autosleep feature puts the device in a low-power state (1µA typ) after a sleep timeout period. The autowake feature configures the MAX7360 to return to normal operating mode from sleep upon a keypress.

The key controller debounces and maintains a FIFO of keypress and release events (including autorepeat, if enabled). An interrupt (INTK) output can be configured to alert keypresses, as they occur, or at maximum rate.

There are eight open-drain I/O ports, which can be used to drive LEDs. The maximum constant-current level for each open-drain port is 20mA. The intensity of the LED on each open-drain port can be individually adjusted through a 256-step PWM control. An input port pair (PORT6, PORT7) can be configured to accept 2-bit gray code inputs from a rotary switch. In addition, if not used for key-switch control, up to six column pins can be used as general-purpose open-drain outputs (GPOs) for LED drive or logic control.

The MAX7360 is offered in a 40-pin (5mm x 5mm) thin QFN package with an exposed pad, and a small 36-bump wafer level package (WLP) for cell phones, pocket PCs, and other portable consumer electronic applications. The MAX7360 operates over the -40°C to +85°C extended temperature range.

Applications

Cell Phones

PDAs

Handheld Games

Portable Consumer Electronics

Printers

Instrumentation

Features

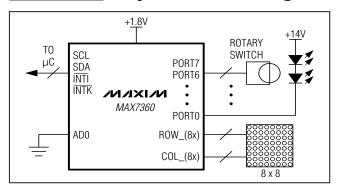
- ♦ Integrated ESD Protection ±8kV IEC 61000-4-2 Contact Discharge ±15kV IEC 61000-4-2 Air-Gap Discharge
- ◆ +14V Tolerant, Open-Drain I/O Ports Capable of Constant-Current LED Drive
- ♦ Rotary Switch-Capable Input Pair (PORT6, PORT7)
- ♦ 256-Step PWM Individual LED Intensity Control
- ♦ Individual LED Blink Rates and Common LED Fade In/Out Rates from 256ms to 4096ms
- ♦ FIFO Queues Up to 16 Debounced Key Events
- ♦ User-Configurable Key Debounce (9ms to 40ms)
- ♦ Keyscan Uses Static Matrix Monitoring for Low EMI Operation
- ♦ +1.62V to +3.6V Operation
- ♦ Monitors Up to 64 Keys
- ♦ Key-Switch Interrupt (INTK) on Each Debounced Event/FIFO Level, or End of Definable Time Period
- ♦ Port Interrupt (INTI) for Input Ports for Special-Key Functions
- ♦ 400kbps, +5.5V Tolerant 2-Wire Serial Interface with Selectable Bus Timeout
- ♦ Four I²C Address Choices

Ordering Information

PART	TEMP RANGE	PIN-PACKAGE
MAX7360ETL+	-40°C to +85°C	40 TQFN-EP*
MAX7360EWX+	-40°C to +85°C	36 WLP

+Denotes a lead(Pb)-free/RoHS-compliant package. *EP = Exposed pad.

Simplfied Block Diagram



Pin Configurations appear at end of data sheet.

Maxim Integrated Products 1

ABSOLUTE MAXIMUM RATINGS

VCC to GND	Operating Temperature Range
DC Current on PORT0-PORT7, COL2-COL725mA	All Pins±2kV
GND Current80mA	IEC 61000-4-2 (RD = 330Ω , Cs = $150pF$)
Continuous Power Dissipation (T _A = +70°C) 40-Pin TQFN (derate 22.2mW/°C above +70°C)1777mW 36-Bump WLP (derate 21.7mW/°C above +70°C)1739mW Junction-to-Case Thermal Resistance (θ _{JC}) (Note 1) 40-Pin TQFN	Contact Discharge ROW0-ROW7, COL0-COL7, PORT0-PORT7 to GND±8kV Air-Gap Discharge ROW0-ROW7, COL0-COL7, PORT0-PORT7 to GND±15kV Lead Temperature (TQFN only, soldering, 10s)+300°C Soldering Temperature (reflow)+260°C
Junction-to-Ambient Thermal Resistance (θJA) (Note 1) 40-Pin TQFN45°C/W	
36-Bump WLP46°C/W	

Note 1: Package thermal resistances were obtained using the method described in JEDEC specification JESD51-7, using a single-layer board. For detailed information on package thermal considerations, refer to www.maxim-ic.com/thermal-tutorial.

Stresses beyond those listed under "Absolute Maximum Ratings" may cause permanent damage to the device. These are stress ratings only, and functional operation of the device at these or any other conditions beyond those indicated in the operational sections of the specifications is not implied. Exposure to absolute maximum rating conditions for extended periods may affect device reliability.

ELECTRICAL CHARACTERISTICS

 $(VCC = +1.62V \text{ to } +3.6V, TA = -40^{\circ}C \text{ to } +85^{\circ}C, \text{ unless otherwise noted.}$ Typical values are at $VCC = +3.3V, TA = +25^{\circ}C.$) (Notes 2, 3)

PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS
Operating Supply Voltage	Vcc		1.62	3.3	3.6	V
External Supply Voltage PORT0-PORT7	VPORT_				14	V
Operating Supply Current	Icc	All key switches open, oscillator running, COL2–COL7 configured as key switches, VPORT_ = VCC		34	50	μA
		N keys pressed		34 + 20 x N		
Sleep-Mode Supply Current	I _{SL}			1.3	3	μΑ
Key-Switch Source Current	IKEY			20	35	μA
Key-Switch Source Voltage	VKEY			0.43	0.5	V
Key-Switch Resistance	RKEY	(Note 4)			5	kΩ
Startup Time from Shutdown	tstart			2	2.4	ms
Output Low Voltage COL2-COL7	VoL	ISINK = 10mA			0.5	V
Oscillator Frequency (PWM Clock)	,	TA = +25°C, VCC = +2.61V	125	128	131	
	fosc	T _A = T _{MIN} to T _{MAX} , V _{CC} ≤ 3.6V	102		164	kHz
Oscillator Frequency Variation	Δfosc	TA = +25°C	-6		+8.5	%
Key-Scan Frequency	fKEY	Derived from oscillator clock		64		kHz

ELECTRICAL CHARACTERISTICS (continued)

(VCC = +1.62V to +3.6V, TA = -40°C to +85°C, unless otherwise noted. Typical values are at VCC = +3.3V, TA = +25°C.) (Notes 2, 3)

PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS
GPIO SPECIFICATIONS						
Input High Voltage PORT0-PORT7	VIH		0.7 x VCC			V
Input Low Voltage PORT0-PORT7	VIL				0.3 x VCC	V
Input Leakage Current	liN	VIN ≤ VCC	-0.25		+0.25	μA
PORT0-PORT7	IIIN	VCC < VIN	-1		+5	μΑ
Output Low Voltage PORT0-PORT7	VoL	ISINK < 20mA			0.6	V
Input Capacitance PORT0-PORT7				20		рF
10mA Port Sinking Current		$V_{CC} = +1.62V \text{ to } +3.6V, T_A = +25^{\circ}C$	8.55		11.52	
PORT0-PORT7		VCC = +3.3V, VOL = +1V	8.67	9.76	10.51	mA
20mA Port Sinking Current		VCC = +1.62V to +3.6V, TA = +25°C	19.40		21.33	mA
PORT0-PORT7		V _{CC} = +3.3V, V _{OL} = +1V	19.55	20	20.69	111/4
Port Sink Current Variation		V _{CC} = +3.3V, V _{OL} = +1V, T _A = +25°C, 20mA output mode		+±1.5	+±2.4	%
Output Logic-Low Voltage INTI, INTK		ISINK = 10mA			0.6	V
PWM Frequency	fpwm	Derived from oscillator clock		500		Hz
SERIAL-INTERFACE SPECIFICA	TIONS					
Input High Voltage SDA, SCL, AD0	VIH		0.7 x VCC			V
Input Low Voltage SDA, SCL, AD0	VIL				0.3 x VCC	V
Input Leakage Current	lini	V _{IN} ≤ V _C C	-0.25		+0.25	μΑ
SDA, SCL, AD0	I _{IN}	VIN > VCC	-0.5		+0.5	μΑ
Output Low Voltage SDA	VoL	ISINK = 6mA			0.6	V
Input Capacitance SDA, SCL, AD0	CIN			10		рF
I ² C TIMING SPECIFICATIONS	,		1			
SCL Serial-Clock Frequency	fscl	Bus timeout disabled	0		400	kHz
Bus Free Time Between a STOP and START Condition	tBUF		1.3			μs
Hold Time (Repeated) START Condition	tHD, STA		0.6			μs
Repeated START Condition Setup Time	tsu, sta		0.6			μs
STOP Condition Setup Time	tsu, sto		0.6			μs

ELECTRICAL CHARACTERISTICS (continued)

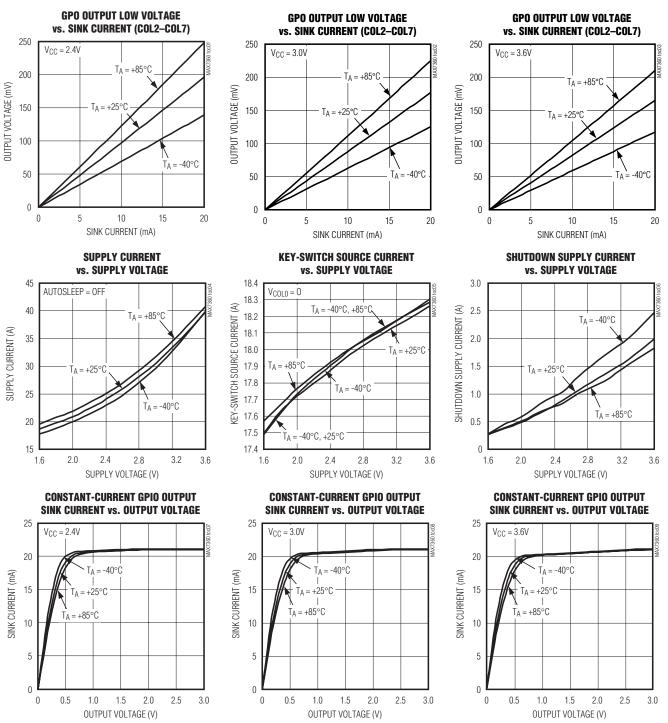
(VCC = +1.62V to +3.6V, TA = -40°C to +85°C, unless otherwise noted. Typical values are at VCC = +3.3V, TA = +25°C.) (Notes 2, 3)

PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS
Data Hold Time	tHD, DAT	(Note 5)			0.9	μs
Data Setup Time	tsu, dat		100			ns
SCL Clock Low Period	tLOW		1.3			μs
SCL Clock High Period	tHIGH		0.7			μs
Rise Time of Both SDA and SCL Signals, Receiving	t _R	(Notes 4, 6)		20 + 0.1Cb	300	ns
Fall Time of Both SDA and SCL Signals, Receiving	tF	(Notes 4, 6)		20 + 0.1Cb	300	ns
Fall Time of SDA Signal, Transmitting	tF, TX	(Notes 4, 7)		20 + 0.1Cb	250	ns
Pulse Width of Spike Suppressed	tsp	(Notes 4, 8)		50		ns
Capacitive Load for Each Bus Line	Cb	(Note 4)			400	pF

- Note 2: All parameters are tested at T_A = +25°C. Specifications over temperature are guaranteed by design.
- Note 3: All digital inputs at VCC or GND.
- Note 4: Guaranteed by design.
- Note 5: A master device must provide a hold time of at least 300ns for the SDA signal (referred to V_{IL} of the SCL signal) to bridge the undefined region of SCL's falling edge.
- Note 6: C_b = total capacitance of one bus line in pF. t_R and t_F measured between +0.3VCC and +0.7VCC.
- Note 7: $I_{SINK} \leq 6mA$.
- Note 8: Input filters on the SDA, SCL, and AD0 inputs suppress noise spikes less than 50ns.

Typical Operating Characteristics

 $(V_{CC} = +2.5V, T_A = +25^{\circ}C, unless otherwise noted.)$



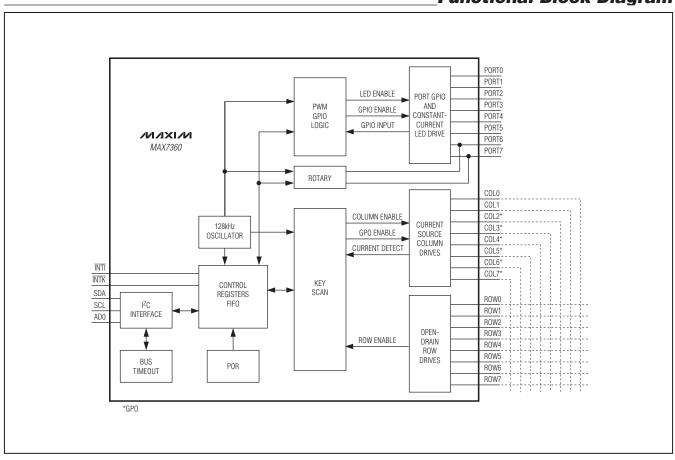
Pin Description

	IN	I	
TQFN	WLP	NAME	FUNCTION
1	A6	ROW0	Row Input from Key Matrix. Leave ROW0 unconnected or connect to GND if unused.
2	B6	ROW1	Row Input from Key Matrix. Leave ROW1 unconnected or connect to GND if unused.
3	C4	ROW2	Row Input from Key Matrix. Leave ROW2 unconnected or connect to GND if unused.
	C6	_	·
4		ROW3	Row Input from Key Matrix. Leave ROW3 unconnected or connect to GND if unused.
5, 15, 25, 35	B4, C5, D2, E4	GND	Ground
6	D6	ROW4	Row Input from Key Matrix. Leave ROW4 unconnected or connect to GND if unused.
7	D5	ROW5	Row Input from Key Matrix. Leave ROW5 unconnected or connect to GND if unused.
8	E6	ROW6	Row Input from Key Matrix. Leave ROW6 unconnected or connect to GND if unused.
9	D4	ROW7	Row Input from Key Matrix. Leave ROW7 unconnected or connect to GND if unused.
10, 20, 27, 30, 40	C2	N.C.	No Connection. Not internally connected. Leave unconnected.
11	F6	COL0	Column Output to Key Matrix. Leave COL0 unconnected if unused.
12	E5	COL1	Column Output to Key Matrix. Leave COL1 unconnected if unused.
13	F5	COL2	Column Output to Key Matrix. Leave COL2 unconnected if unused. COL2 can be configured as a GPO (see Table 9 in the <i>Register Tables</i> section).
14	F4	COL3	Column Output to Key Matrix. Leave COL3 unconnected if unused. COL3 can be configured as a GPO (see Table 9 in the <i>Register Tables</i> section).
16	F3	COL4	Column Output to Key Matrix. Leave COL4 unconnected if unused. COL4 can be configured as a GPO (see Table 9 in the <i>Register Tables</i> section).
17	E3	COL5	Column Output to Key Matrix. Leave COL5 unconnected if unused. COL5 can be configured as a GPO (see Table 9 in the <i>Register Tables</i> section).
18	F2	COL6	Column Output to Key Matrix. Leave COL6 unconnected if unused. COL6 can be configured as a GPO (see Table 9 in the <i>Register Tables</i> section).
19	F1	COL7	Column Output to Key Matrix. Leave COL7 unconnected if unused. COL7 can be configured as a GPO (see Table 9 in the <i>Register Tables</i> section).
21	E2	SDA	I ² C-Compatible, Serial-Data I/O
22	E1	SCL	I ² C-Compatible, Serial-Clock Input
23	D3	INTK	Active-Low Key-Switch Interrupt Output. INTK is open drain and requires a pullup resistor.

Pin Description (continued)

PIN	PIN					
TQFN	WLP	NAME	FUNCTION			
24	D1	ĪNTĪ	Active-Low GPI Interrupt Output. INTI is open drain and requires a pullup resistor.			
26	C1	VCC	Positive Supply Voltage. Bypass VCC to GND with a 0.1µF or higher ceramic capacitor.			
28	B1	AD0	Address Input. AD0 selects up to four device slave addresses (Table 3).			
29	A1	I.C.	Internally Connected. Connect to GND for normal operation.			
31	B2	PORT0	GPIO Port. Open-drain I/O rated at +14V. PORT0 can be configured as a constant-current output.			
32	A2	PORT1	GPIO Port. Open-drain I/O rated at +14V. PORT1 can be configured as a constant-current output.			
33	В3	PORT2	GPIO Port. Open-drain I/O rated at +14V. PORT2 can be configured as a constant-current output.			
34	А3	PORT3	GPIO Port. Open-drain I/O rated at +14V. PORT3 can be configured as a constant-current output.			
36	A4	PORT4	GPIO Port. Open-drain I/O rated at +14V. PORT4 can be configured as a constant-current output.			
37	C3	PORT5	GPIO Port. Open-drain I/O rated at +14V. PORT5 can be configured as a constant-current output.			
38	A5	PORT6	GPIO Port. Open-drain I/O rated at +14V. PORT6 can be configured as a constant-current output, or a rotary switch input.			
39	B5	PORT7	GPIO Port. Open-drain I/O rated at +14V. PORT7 can be configured as a constant-current output, or a rotary switch input.			
_	_	EP	Exposed Pad (TQFN only). EP is internally connected to GND. Connect EP to a ground plane to increase thermal performance.			

Functional Block Diagram



Detailed Description

The MAX7360 is a microprocessor peripheral low-noise key-switch controller that monitors up to 64 key switches with optional autorepeat, and key events that are presented in a 16-byte FIFO. The MAX7360 also features eight open-drain GPIOs configured for digital I/O or constant-current output for LED applications up to +14V.

The MAX7360 features an automatic sleep mode and automatic wakeup that further reduce supply current consumption. The MAX7360 can be configured to enter sleep mode after a programmable time following a key event. The FIFO content is maintained and can be read in sleep mode. The MAX7360 does not enter autosleep when a key is held down. The autowake feature takes the MAX7360 out of sleep mode following a keypress event. Enable/disable autosleep and autowake through the configuration register (Table 8).

To prevent overloading the microprocessor with too many interrupts, interrupt requests are issued on a programmable number of FIFO entries, and/or after a set period of time (Table 10). The key-switch status is checked by reading the key-switch FIFO. A 1-byte read access returns both the next key event in the FIFO (if there is one) and the FIFO status. INTK functions as an open-drain general-purpose output (GPO) capable of driving an LED if key-switch interrupts are not required.

Up to six of the key-switch outputs function as opendrain GPOs capable of driving additional LEDs when the application requires fewer keys to be scanned. For each key-switch output used as a GPO, the number of monitored key switches reduces by eight.

Initial Power-Up

On power-up, all control registers are set to power-up values and the MAX7360 is in sleep mode (Table 1).

Table 1. Register Address Map and Power-Up Condition

			ap and i ontoi o	
ADDRESS CODE (hex)	READ/ WRITE	POWER-UP VALUE (hex)	REGISTER FUNCTION	DESCRIPTION
0x00	Read only	0x3F	Keys FIFO	Read FIFO key-scan data out
0x01	R/W	0x0A	Configuration	Power-down, key-release enable, autowakeup, and I ² C time-out enable
0x02	R/W	0xFF	Debounce	Key debounce time settling and GPO enable
0x03	R/W	0x00	Interrupt	Key-switch interrupt INTK frequency setting
0x04	R/W	0xFE	GPO	COL2-COL7 and INTK GPO control
0x05	R/W	0x00	Key repeat	Delay and frequency for key repeat
0x06	R/W	0x07	Sleep	Idle time to autosleep
0x40	R/W	0x00	GPIO global con- figuration	Rotary switch, GPIO standby, GPIO reset, fade
0x41	R/W	0x00	GPIO control	PORT0-PORT7 input/output control
0x42	R/W	0x00	GPIO debounce	PORT0-PORT7 debounce time setting
0x43	R/W	0xC0	GPIO constant- current setting	PORT0-PORT7 constant-current output setting
0x44	R/W	0x00	GPIO output mode	PORT0-PORT7 output mode control
0x45	R/W	0x00	Common PWM	Common PWM duty-cycle setting
0x46	R/W	0x00	Rotary switch con- figuration	Rotary switch interrupt frequency and debounce time setting
0x48	Read only	0x00	I ² C timeout flag	I ² C timeout since last POR
0x49	Read only	0xFF	GPIO input register	PORT0-PORT7 input values
0x4A	Read only	0x00	Rotary switch count	Switch cycles since last read
0x50	R/W	0x00	PORTO PWM	PORT0 individual duty-cycle setting
0x51	R/W	0x00	PORT1 PWM	PORT1 individual duty-cycle setting
0x52	R/W	0x00	PORT2 PWM	PORT2 individual duty-cycle setting
0x53	R/W	0x00	PORT3 PWM	PORT3 individual duty-cycle setting
0x54	R/W	0x00	PORT4 PWM	PORT4 individual duty-cycle setting
0x55	R/W	0x00	PORT5 PWM	PORT5 individual duty-cycle setting
0x56	R/W	0x00	PORT6 PWM	PORT6 individual duty-cycle setting
0x57	R/W	0x00	PORT7 PWM	PORT7 individual duty-cycle setting
0x58	R/W	0x00	PORT0 configuration	PORT0 interrupt, PWM mode control and blink period setting
0x59	R/W	0x00	PORT1 configuration	PORT1 interrupt, PWM mode control and blink period setting
0x5A	R/W	0x00	PORT2 configuration	PORT2 interrupt, PWM mode control and blink period setting
0x5B	R/W	0x00	PORT3 configuration	PORT3 interrupt, PWM mode control and blink period setting
0x5C	R/W	0x00	PORT4 configuration	PORT4 interrupt, PWM mode control and blink period setting
0x5D	R/W	0x00	PORT5 configuration	PORT5 interrupt, PWM mode control and blink period setting
0x5E	R/W	0x00	PORT6 configuration	PORT6 interrupt, PWM mode control and blink period setting
0x5F	R/W	0x00	PORT7 configuration	PORT7 interrupt, PWM mode control and blink period setting

Table 2. Key-Switch Mapping

PIN	COL0	COL1	COL2*	COL3*	COL4*	COL5*	COL6*	COL7*
ROW0	KEY 0	KEY 8	KEY 16	KEY 24	KEY 32	KEY 40	KEY 48	KEY 56
ROW1	KEY 1	KEY 9	KEY 17	KEY 25	KEY 33	KEY 41	KEY 49	KEY 57
ROW2	KEY 2	KEY 10	KEY 18	KEY 26	KEY 34	KEY 42	KEY 50	KEY 58
ROW3	KEY 3	KEY 11	KEY 19	KEY 27	KEY 35	KEY 43	KEY 51	KEY 59
ROW4	KEY 4	KEY 12	KEY 20	KEY 28	KEY 36	KEY 44	KEY 52	KEY 60
ROW5	KEY 5	KEY 13	KEY 21	KEY 29	KEY 37	KEY 45	KEY 53	KEY 61
ROW6	KEY 6	KEY 14	KEY 22	KEY 30	KEY 38	KEY 46	KEY 54	KEY 62
ROW7	KEY 7	KEY 15	KEY 23	KEY 31	KEY 39	KEY 47	KEY 55	KEY 63

^{*}These columns can be configured as GPOs.

Key-Scan Controller

Key inputs are scanned statically, not dynamically, to ensure low-EMI operation. As inputs only toggle in response to switch changes, the key matrix can be routed closer to sensitive circuit nodes.

The key-scan controller debounces and maintains a FIFO of keypress and release events (including autorepeated keypresses, if autorepeat is enabled). Table 2 shows the key-switch order. The user-programmable key-switch debounce time, and autosleep timer, is derived from the 64kHz clock, which in turn is derived from the 128kHz oscillator. Time delay for autorepeat and key-switch interrupt is based on the key-switch debounce time.

Keys FIFO Register (0x00)

The keys FIFO register contains the information pertaining to the status of the keys FIFO, as well as the key events that have been debounced (see Table 7 in the *Register Tables* section). Bits D0–D5 denote which of the 64 keys have been debounced and the keys are numbered as in Table 2.

D7 indicates if there is more data in the FIFO, except when D5:D0 indicate key 63 or key 62. When D5:D0 indicate key 63 or key 62, the host should read one more time to determine whether there is more data in the FIFO. Use key 62 and key 63 for rarely used keys. D6 indicates if it is a keypress or release event, except when D5:D0 indicate key 63 or key 62.

Reading the key-scan FIFO clears the interrupt INTK depending on the setting of bit D5 in the configuration register (0x01).

Configuration Register (0x01)

The configuration register controls the I²C bus timeout feature, enables key-release detection, enables autowake,

and determines how $\overline{\text{INTK}}$ is deasserted. Write to bit D7 to put the MAX7360 into sleep mode or operating mode. Autosleep and autowake, when enabled, also change the status of D7 (see Table 8 in the *Register Tables* section).

Debounce Register (0x02)

The debounce register sets the time for each debounce cycle, as well as setting whether the GPO ports are enabled or disabled. Bits D0–D4 set the debounce time in increments of 1ms starting at 9ms and ending at 40ms (see Table 9 in the *Register Tables* section). Bits D5, D6, and D7 set which of the GPO ports is enabled. Note the GPO ports are enabled only in the combinations shown in Table 9, from all disabled to all enabled.

Key-Switch Interrupt Register (0x03)

The interrupt register contains information related to the settings of the interrupt request function, as well as the status of the INTK output, which can also be configured as a GPO. If bits D0-D7 are set to 0x00, the INTK output is configured as a GPO that is controlled by bit D1 in the port register. There are two types of interrupts, the FIFObased interrupt and time-based interrupt. Set bits D0-D4 to assert interrupts at the end of the selected number of debounce cycles following a key event (see Table 10 in the Register Tables section). This number ranges from 1-31 debounce cycles. Setting bits D7, D6, and D5 set the FIFO-based interrupt when there are 2-14 key events stored in the FIFO. Both interrupts can be configured simultaneously and INTK asserts depending on which condition is met first. INTK deasserts depending on the status of bit D5 in the configuration register.

Ports Register (0x04)

The ports register sets the values of PORT2-PORT7 and the INTK port, when configured, as open-drain GPOs.

The settings in this register are ignored for ports not configured as GPOs, and a read from this register returns the values stored in the register (see Table 11 in the *Register Tables* section).

Autorepeat Register (0x05)

The MAX7360 autorepeat feature notifies the host that at least one key has been pressed for a continuous period. The autorepeat register enables or disables this feature, sets the time delay after the last key event before the key repeat code (0x7E) is entered into the FIFO, and sets the frequency at which the key-repeat code is entered into the FIFO thereafter. Bit D7 specifies whether the autorepeat function is enabled with 0 denoting autorepeat disabled, and 1 denoting autorepeat enabled. Bits D0–D3 specify the autorepeat delay in terms of debounce cycles ranging from 8–128 debounce cycles (see Table 12 in the *Register Tables* section). Bits D4, D5, and D6 specify the autorepeat rate or frequency ranging from 4–32 debounce cycles.

When autorepeat is enabled, holding the key pressed results in a key-repeat event that is denoted by 0x7E. The key being pressed does not show up again in the FIFO.

Only one autorepeat code is entered into the FIFO, regardless of the number of keys pressed. The autorepeat code continues to be entered in the FIFO at the frequency set by bits D[4:6] until another key event is recorded. Following the key-release event, if any keys are still pressed, the MAX7360 restarts the autorepeat sequence.

Autosleep Register (0x06)

Autosleep puts the MAX7360 in sleep mode to draw minimal current. When enabled, the MAX7360 enters sleep mode if no keys are pressed for the autosleep time (see Table 13 in the *Register Tables* section).

Key-Switch Sleep Mode

In sleep mode, the MAX7360 draws minimal current. Switch-matrix current sources are turned off and pulled up to VCC. When autosleep is enabled, key-switch inactivity for a period longer than the autosleep time puts the part into sleep mode (FIFO data is maintained). Writing a 1 to D7 in the configuration register, or a keypress, can take the MAX7360 out of sleep mode. Bit D7 in the configuration register gives the sleep-mode status and can be read any time. The FIFO data is maintained while in sleep mode.

Autowake

Keypresses initiate autowake and the MAX7360 goes into operating mode. Keypresses that autowake the MAX7360 are not lost. When a key is pressed while the MAX7360 is in sleep mode, all analog circuitry, including switch-matrix current sources, turn on in 2ms. The initial key needs to be pressed for 2ms plus the debounce time to be stored in the FIFO. Write a 0 to D1 in the configuration register (0x01) to disable autowakeup.

GPIOs

The MAX7360 has eight GPIO ports with LED control functions. The ports can be used as logic inputs, logic outputs, or constant-current PWM LED drivers. In addition, PORT7 and PORT6 can function as a rotary switch input pair. When in PWM mode, the ports are set up to start their PWM cycle in 45° phase increments. This prevents large current spikes on the LED supply voltage when driving multiple LEDs.

GPIO Global Configuration Register (0x40)

The GPIO global configuration register controls the main settings for the eight GPIOs (see Table 14 in the *Register Tables* section).

Bit D7 enables PORT[7:6] as inputs for a rotary switch. Bit D5 enables interrupt generation for I2C timeouts. D4 is the main enable/shutdown bit for the GPIOs. D3 functions as a software reset for the GPIO registers (0x40 to 0x5F). Bits D[2:0] set the fade in/out time for the GPIOs configured as constant-current sinks.

GPIO Control Register (0x41)

The GPIO control register configures each port as either an input or an output (see Table 15 in the *Register Tables* section). All GPIOs allow individual configurations, and power up as inputs. Enabling rotary switch mode automatically sets D7 and D6 as inputs. The ports consume additional current if their inputs are left undriven.

GPIO Debounce Configuration Register (0x42)

The GPIO debounce configuration register sets the amount of time a GPIO must be held for the MAX7360 to register a logic transition (see Table 16 in the *Register Tables* section). The GPIO debounce setting is independent of the key-switch debounce setting. Five bits (D[4:0]) set 32 possible debounce times from 9ms up to 40ms.

GPIO Constant-Current Setting Register (0x43)

The GPIO constant-current setting register sets the global constant-current amount (see Table 17 in the *Register Tables* section). Bits D1 and D0 set the global current values from 5mA up to 20mA.

GPIO Output Mode Register (0x44)

The GPIO output mode register sets an output as either a constant-current or non-constant-current output for PORT[7:0] (see Table 18 in the *Register Tables* section). Outputs are configured as constant-current outputs by default to prevent accidental loading of an LED across an unregulated output. The constant-current circuits automatically turn off when not in use to reduce current consumption.

Common PWM Register (0x45)

The common PWM register stores the common constant-current output PWM duty cycle (see Table 19 in the *Register Tables* section). The values stored in this register translate over to a PWM duty cycle in the same manner as the individual PWM registers (0x50 to 0x57). Ports can use their own individual PWM value, or the common PWM value. Write to this register to change the duty cycle of several ports at once.

Rotary Switch Configuration Register (0x46)

The rotary switch configuration register stores rotary switch settings for PORT7 and PORT6 (see Table 20 in the *Register Tables* section). D7 determines whether switch counts or a time delay will trigger an interrupt if enabled. D[6:4] set the count or time amount to wait before sending an interrupt. Bits D[3:0] set the debounce cycle time for the rotary switch inputs. Debounce time ranges from 0 to 15ms.

I²C Timeout Flag Register (0x48) (Read Only)

The I²C timeout flag register contains a single bit (D0), which indicates if an I²C timeout has occurred (see Table 21 in the *Register Tables* section). Read this register to clear an I²C timeout initiated interrupt.

GPIO Input Register (0x49) (Read Only)

The GPIO input register contains the input data for all of the GPIOs (see Table 22 in the *Register Tables* section). Ports configured as outputs are read as high. There is one debounce period delay prior to detecting a transition on the input port. This prevents a false interrupt from occurring when changing a port from an output to an input. The GPIO input register reports the state of all input ports regardless of any interrupt mask settings. Ports configured as an input have a 2µA internal pullup to VCC for PORT[5:0] and a 10µA internal pullup to VCC for PORT[7:6].

Rotary Switch Count Register (0x4A) (Read Only)

The MAX7360 keeps a count of the rotary switch rotations in two's compliment format (see Table 23 in the *Register Tables* section). The register values wrap around as the count value switches from a positive to a negative value and back again. The count resets to zero after an I²C read to this register.

PORT0-PORT7 Individual PWM Ratio Registers (0x50 to 0x57)

Each port has an individual PWM ratio register (0x50 to 0x57, see Table 24 in the *Register Tables* section). Use values 0x00 to 0xFE in these registers to configure the number of cycles out of 256 the output sinks current (LED is on), from 0 cycles to 254 cycles. Use 0xFF to have an output continuously sink current (always on). For applications requiring multiple ports to have the same intensity, program a particular port's configuration register (0x58 to 0x5F) to use the common PWM register (0x45). New PWM settings take place at the beginning of a PWM cycle, to allow changes from common intensity to individual intensity with no interruption in the PWM cycle.

PORT0-PORT7 Configuration Registers (0x58 to 0x5F)

Registers 0x58 to 0x5F set individual configurations for each port (see Table 25 in the *Register Tables* section). Bits D7 and D6 determine the interrupt settings for the inputs. Interrupts can assert upon detection of a logic transition, a rising edge, or not at all. D5 sets the port's PWM setting to either the common or individual PWM setting. Bits D[4:2] enable and set the ports' individual blink period from 0 to 4096ms. Bits D1 and D0 set a port's blink duty cycle.

Fading

Set the fade cycle time in the GPIO global configuration register (0x40) to a non-zero value to enable fade in/out (see Table 14 in the *Register Tables* section). Fade in increases an LED's PWM intensity in 16 even steps from zero to its stored value. Fade out decreases an LED's PWM intensity in 16 even steps from its current value to zero. Fading occurs automatically in any of the following scenarios:

- Change the common PWM register value from any value to zero to cause all ports using the common PWM register settings to fade out. No ports using individual PWM settings are affected.
- Change the common PWM register value to any value from zero to cause all ports using the common PWM register settings to fade in. No ports using individual PWM settings are affected.
- 3) Put the part out of shutdown to cause all ports to fade in. Changing an individual PWM intensity during fade

in automatically cancels that port's fade and immediately output at its newly programmed intensity.

4) Put the part into shutdown to cause all ports to fade out. Changing an individual PWM intensity during fade out automatically cancels that port's fade and immediately turns off.

Blink

Each port has its own blink control settings through registers 0x58 to 0x5F (see Table 25 in the *Register Tables* section). The blink period ranges from 0 (blink disabled) to 4.096s. Settable blink duty cycles range from 6.25% to 50%. All blink periods start at the same PWM cycle for synchronized blinking between multiple ports.

GPIO Port Interrupts (INTI)

Three possible sources generate $\overline{\text{INTI}}$: I²C timeout, GPIOs configured as inputs, and the rotary switch (registers 0x48, 0x49, and 0x4A). Read the respective data/status registers for each type of interrupt to clear $\overline{\text{INTI}}$. Set register 0x46 for rotary switch-based interrupts.

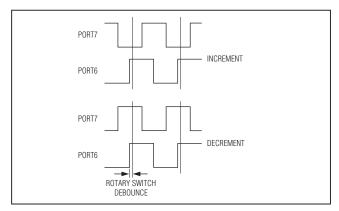


Figure 1. Rotary Switch Input Signal Timing

Set registers 0x58 to 0x5F for individual GPI-based interrupts. If multiple sources generate the interrupt, all the related status registers must be read to clear $\overline{\text{INTI}}$.

Rotary Switch

The MAX7360 can accept a 2-bit rotary switch inputs on PORT6 and PORT7. Rotation of the switch in a clockwise direction increments the count. Enable rotary switch mode from the GPIO global configuration register (0x40). Several settings for PORT6 and PORT7 occur during rotary switch mode:

- 1) Each port has a 10µA pullup to VCC.
- 2) Register 0x46 sets the debounce time.
- 3) A debounced rising edge on PORT6 while PORT7 is high decreases the count.
- 4) A debounced rising edge on PORT6 while PORT7 is low increases the count.

For more details, see Figure 1.

Serial Interface

Figure 2 shows the 2-wire serial interface timing details.

Serial Addressing

The MAX7360 operates as a slave that sends and receives data through an I²C-compatible 2-wire interface. The interface uses a serial-data line (SDA) and a serial-clock line (SCL) to achieve bidirectional communication between master(s) and slave(s). A master (typically a microcontroller) initiates all data transfers to and from the MAX7360 and generates the SCL clock that synchronizes the data transfer.

The MAX7360's SDA line operates as both an input and an open-drain output. A pullup resistor, typically $4.7k\Omega$.

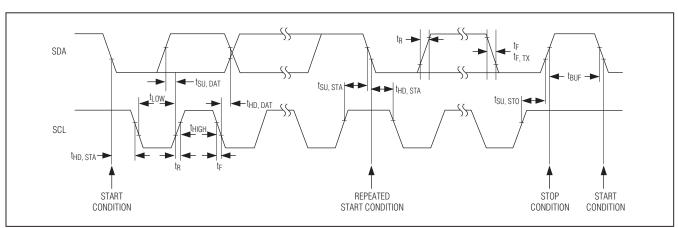


Figure 2. 2-Wire Serial Interface Timing Details

is required on SDA. The MAX7360's SCL line operates only as an input. A pullup resistor is required on SCL if there are multiple masters on the 2-wire interface, or if the master in a single-master system has an open-drain SCL output.

Each transmission consists of a START (S) condition (Figure 3) sent by a master, followed by the MAX7360 7-bit slave address plus R/\overline{W} bit, a register address byte, one or more data bytes, and finally, a STOP (P) condition.

START and STOP Conditions

Both SCL and SDA remain high when the interface is not busy. A master signals the beginning of a transmission with a START condition by transitioning SDA from high to low while SCL is high. When the master has finished communicating with the slave, it issues a STOP condition by transitioning SDA from low to high while SCL is high. The bus is then free for another transmission.

Bit Transfer

One data bit is transferred during each clock pulse (Figure 4). The data on SDA must remain stable while SCL is high.

Acknowledge

The acknowledge bit is a clocked 9th bit (Figure 5), which the recipient uses to handshake receipt of each byte of data. Thus, each byte transferred effectively requires 9 bits. The master generates the 9th clock pulse, and the recipient pulls down SDA during the acknowledge clock pulse; therefore, the SDA line is stable low during the high period of the clock pulse. When the master is transmitting to the MAX7360, the MAX7360 generates the acknowledge bit because the MAX7360 is the recipient. When the MAX7360 is transmitting to the master, the master generates the acknowledge bit because the master is the recipient.

Table 3. 2-Wire Interface Address Map

DIN 4 DO	DEVICE ADDRESS								
PIN AD0	A 7	A6	A 5	A 4	А3	A2	A 1	Α0	
GND	0	1	1	1	0	0	0	R/W	
Vcc	0	1	1	1	0	1	0	R/W	
SDA	0	1	1	1	1	0	0	R/W	
SCL	0	1	1	1	1	1	0	R/W	

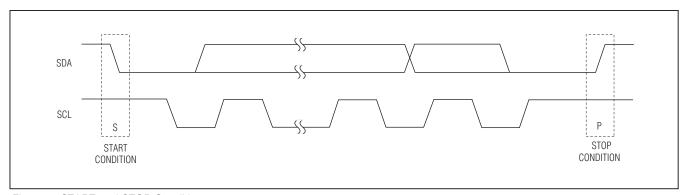


Figure 3. START and STOP Conditions

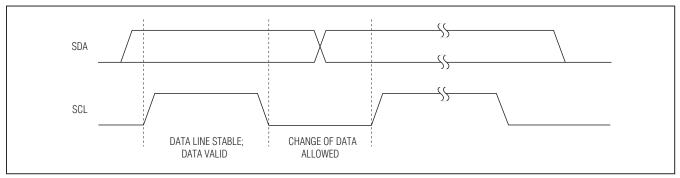


Figure 4. Bit Transfer

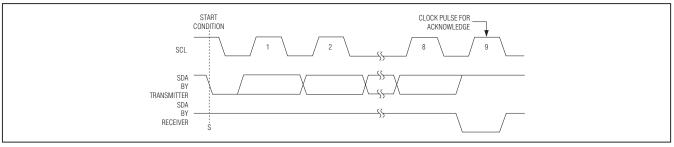


Figure 5. Acknowledge

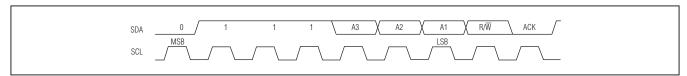


Figure 6. Slave Address

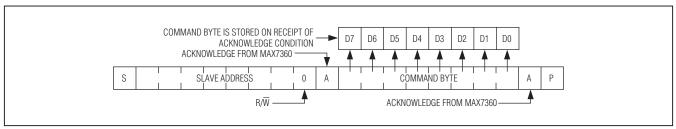


Figure 7. Command Byte Received

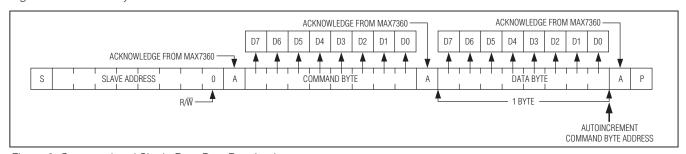


Figure 8. Command and Single Data Byte Received

Slave Addresses

The MAX7360 has a 7-bit long slave address (Figure 6). The bit following a 7-bit slave address is the R/W bit, which is low for a write command and high for a read command.

The first 4 bits (MSBs) of the MAX7360 slave address are always 0111. Slave address bits A3, A2, and A1 correspond, by the matrix in Table 3, to the states of the device address input AD0, and A0 corresponds to the R/W bit. The AD0 input can be connected to any of four signals (GND, VCC, SDA, or SCL), giving four possible slave address pairs and allowing up to four MAX7360 devices to share the bus. Because SDA and SCL are

dynamic signals, care must be taken to ensure that AD0 transitions no sooner than the signals on SDA and SCL.

The MAX7360 monitors the bus continuously, waiting for a START condition, followed by its slave address. When the MAX7360 recognizes its slave address, it acknowledges and is then ready for continued communication.

Bus Timeout

The MAX7360 features a 20ms minimum bus timeout on the 2-wire serial interface, largely to prevent the MAX7360 from holding the SDA I/O low during a read transaction should the SCL lock up for any reason before a serial transaction is completed. Bus timeout operates by causing the MAX7360 to internally terminate a serial

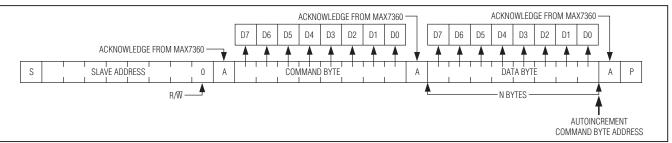


Figure 9. N Data Bytes Received

Table 4. Autoincrement Rules

REGISTER FUNCTION	ADDRESS CODE (hex)	AUTOINCREMENT ADDRESS (hex)	
Keys FIFO	0x00	0x00	
Autoshutdown	0x06	0x00	
All other key switch	0x01 to 0x05	Addr + 0x01	
All other GPIO	0x40 to 0x5F	Addr + 0x01	

transaction, either read or write, if SCL low exceeds 20ms. After a bus timeout, the MAX7360 waits for a valid START condition before responding to a consecutive transmission. This feature can be enabled or disabled under user control by writing to the configuration register (Table 8 in the *Register Tables* section).

Message Format for Writing the Key-Scan Controller

A write to the MAX7360 comprises the transmission of the slave address with the R/W bit set to zero, followed by at least 1 byte of information. The first byte of information is the command byte. The command byte determines which register of the MAX7360 is to be written by the next byte, if received. If a STOP condition is detected after the command byte is received, the MAX7360 takes no further action (Figure 7) beyond storing the command byte.

Any bytes received after the command byte are data bytes. The first data byte goes into the internal register of the MAX7360 selected by the command byte (Figure 8).

If multiple data bytes are transmitted before a STOP condition is detected, these bytes are generally stored in subsequent MAX7360 internal registers, because the command byte address generally autoincrements (Table 4).

Message Format for Reading the Kev-Scan Controller

The MAX7360 is read using the internally stored command byte as an address pointer, the same way the stored command byte is used as an address pointer for a write. The pointer generally autoincrements after each data byte is read using the same rules as for a

write (Table 4). Thus, a read is initiated by first configuring the MAX7360's command byte by performing a write (Figure 7). The master can now read n consecutive bytes from the MAX7360, with the first data byte being read from the register addressed by the initialized command byte. When performing read-after-write verification, remember to reset the command byte's address, because the stored command byte address is generally autoincremented after the write (Figure 9, Table 4).

Operation with Multiple Masters

When the MAX7360 is operated on a 2-wire interface with multiple masters, a master reading the MAX7360 uses a repeated start between the write that sets the MAX7360's address pointer, and the read(s) that takes the data from the location(s). This is because it is possible for master 2 to take over the bus after master 1 has set up the MAX7360's address pointer, but before master 1 has read the data. If master 2 subsequently resets the MAX7360's address pointer, master 1's read can be from an unexpected location.

Command Address Autoincrementing

Address autoincrementing allows the MAX7360 to be configured with fewer transmissions by minimizing the number of times the command address needs to be sent. The command address stored in the MAX7360 generally increments after each data byte is written or read (Table 4). Autoincrement only works when doing a multiburst read or write.

_Applications Information

Reset from I2C

After a catastrophic event such as ESD discharge or microcontroller reset, use bit D7 of the configuration register (0x01) as a software reset for the key-switch state (the key-switch register values and FIFO remain unaffected). Use bit D4 of the GPIO global configuration register (0x40) as a software reset for the GPIOs.

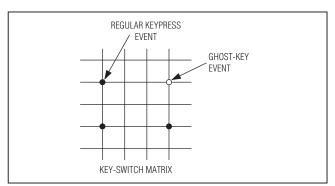


Figure 10. Ghost-Key Phenomenon

Ghost-Key Elimination

Ghost keys are a phenomenon inherent with key-switch matrices. When three switches located at the corners of a matrix rectangle are pressed simultaneously, the switch that is located at the last corner of the rectangle (the ghost key) also appears to be pressed. This occurs because the potentials at the two sides of the ghost-key switch are identical due to the other three connections—the switch is electrically shorted by the combination of the other three switches (Figure 10). Because the key appears to be pressed electrically, it is impossible to detect which of the four keys is the ghost key.

The MAX7360 employs a proprietary scheme that detects any three-key combination that generates a fourth ghost key, and does not report the third key that causes a ghost-key event. This means that although ghost keys are never reported, many combinations of three keys are effectively ignored when pressed at the same time. Applications requiring three-key combinations (such as <Ctrl><Alt>) must ensure that the three keys are not wired in positions that define the vertices of a rectangle (Figure 11). There is no limit on the number of keys that can be pressed simultaneously as long as the keys do not generate ghost-key events and FIFO is not full.

Low-EMI Operation

The MAX7360 uses two techniques to minimize EMI radiating from the key-switch wiring. First, the voltage across the switch matrix never exceeds +0.55V if not in sleep mode, independent of supply voltage VCC. This reduces the voltage swing at any node when a switch is pressed to +0.55V maximum. Second, the keys are not dynamically scanned, which would cause the key-switch wiring to continuously radiate interference. Instead, the keys are monitored for current draw (only occurs when pressed), and debounce circuitry only operates when one or more keys are actually pressed.

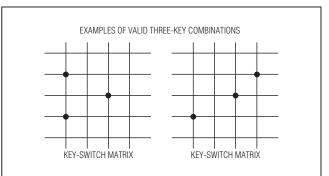


Figure 11. Valid Three-Key Combinations

Switch On-Resistance

The MAX7360 is designed to be insensitive to resistance, either in the key switches, or the switch routing to and from the appropriate COL_ and ROW_ up to $4k\Omega$ (max). These controllers are therefore compatible with low-cost membrane and conductive carbon switches.

Hot Insertion

The $\overline{\text{INTI}}$, $\overline{\text{INTK}}$, SCL, and AD0 inputs and SDA remain high impedance with up to +3.6V asserted on them when the MAX7360 powers down (V_{CC} = 0). I/O ports (PORT0-PORT7) remain high impedance with up to +14V asserted on them when not powered. Use the MAX7360 in hot-swap applications.

Staggered PWM

The LED's on-time in each PWM cycle are phase delayed 45° into eight evenly spaced start positions. Optimize phasing when using fewer than eight ports as constant-current outputs by allocating the ports with the most appropriate start positions. For example, if using four constant-current outputs, choose PORTO, PORT2, PORT4, and PORT6 because their PWM start positions are evenly spaced. In general, choose the ports that spread the PWM start positions as evenly as possible. This optimally spreads out the current demand from the ports' load supply.

INTK/INTI

There are two interrupt outputs, $\overline{\text{INTK}}$ and $\overline{\text{INTI}}$. Each interrupt operates independently from the other. See the *Key-Switch Interrupt Register (0x03)* and the *GPIO Port Interrupts (\overline{\text{INTI}})* sections for additional information regarding these two interrupts.

Power-Supply Considerations

The MAX7360 operates with a +1.62V to +3.6V power-supply voltage. Bypass the power supply to GND with a $0.1\mu F$ or higher ceramic capacitor as close as possible to the device.

ESD Protection

All of the MAX7360 pins meet the 2kV Human Body Model ESD tolerances. Key-switch inputs and GPIOs meet IEC 61000-4-2 ESD protection. The IEC test stresses consist of 10 consecutive ESD discharges per polarity, at the maximum specified level and below (per IEC 61000-4-2). Test criteria include:

- 1) The powered device does not latch up during the ESD discharge event.
- 2) The device subsequently passes the final test used for prescreening.

Tables 5 and 6 are from the IEC 61000-4-2: Edition 1.1 1999-05: Electromagnetic compatibility (EMC) Testing and measurement techniques—Electrostatic discharge immunity test.

Table 5. ESD Test Levels

	CONTACT CHARGE	1B—AIR-0	GAP DISCHARGE
LEVEL TEST VOLTAGE (kV)		LEVEL	TEST VOLTAGE (kV)
1	2	1	2
2	4	2	4
3	6	3	8
4	8	4	10
X	Special	X	Special

X = Open level. The level has to be specified in the dedicated equipment specification. If higher voltages than those shown are specified, special test equipment could be needed.

Table 6. ESD Waveform Parameters

LEVEL	INDICATED VOLTGE (kV)	FIRST PEAK OF CURRENT DISCHARGE ±10% (A)	RISE TIME (t _r) WITH DISCHARGE SWITCH (ns)	CURRENT (±30%) AT 30ns (A)	CURRENT (±30%) AT 60ns (A)
1	2	7.5	0.7 to 1	4	2
2	4	15	0.7 to 1	8	4
3	6	22.5	0.7 to 1	12	6
4	8	30	0.7 to 1	16	8

Register Tables

Table 7. Keys FIFO Register Format (0x00)

SPECIAL FUNCTION			KEY	'S FIFO RI	EGISTER	DATA		
SPECIAL FUNCTION	D7	D6	D5	D4	D3	D2	D1	D0
The key number indicated by D5:D0 is a key event. D7 is always for a key press of key 62 and key 63. When D7 is 0, the key read is the last data in the FIFO. When D7 is 1, there is more data in the FIFO. When D6 is 1, key data read from FIFO is a key release. When D6 is 0, key data read from FIFO is a key press.	FIFO empty flag	Key release flag	X	X	X	X	X	Х
FIFO is empty.	0	0	1	1	1	1	1	1
FIFO is overflow. Continue to read data in FIFO	0	1	1	1	1	1	1	1
Key 63 is pressed. Read one more time to determine whether there is more data in FIFO.	1	0	1	1	1	1	1	1
Key 63 is released. Read one more time to determine whether there is more data in FIFO.	1	1	1	1	1	1	1	1
Key repeat. Indicates the last data in FIFO.	0	0	1	1	1	1	1	0
Key repeat. Indicates more data in FIFO.	0	1	1	1	1	1	1	0
Key 62 is pressed. Read one more time to determine whether there is more data in FIFO.	1	0	1	1	1	1	1	0
Key 62 is released. Read one more time to determine whether there is more data in FIFO.	1	1	1	1	1	1	1	0

Table 8. Configuration Register Format (0x01)

REGISTER BIT	DESCRIPTION	VALUE		FUNCTION	DEFAULT VALUE		
		X (when 0x40 D4 = 1)	when constant-current	node. Key switches always remain active PWM is enabled (bit 4 of register 0x40 is osleep, autowakeup, or an I ² C write to this bit.			
D7	Sleep	0 (when 0x40 D4 = 0)	Key-switch sleep mode. The entire chip is shut down.	When constant-current PWM is disabled (bit 4 of register 0x40 is low), I ² C write,	0		
		1 (when 0x40 D4 = 0)	Key-switch operating mode	autosleep, and autowakeup all can change this bit. This bit can be read back by I ² C any time for current status.			
D6	Reserved	0	_		0		
		0	INTK cleared when FIF	INTK cleared when FIFO is empty			
D5	Interrupt	1		t read. In this mode, I ² C should read the dition is removed or further INT may be lost.	0		
D4	Reserved	0	_		0		
D3	Key-release	0	Disable key releases		1		
Do	enable	1	Enable key releases		I		
D2	Reserved	0	_		0		
D1	Autowakeup	0	Disable keypress wake	eup	1		
	enable	1	Enable keypress wake	ир	'		
D0	Timeout	0	I ² C timeout enabled		0		
	disable	1	I ² C timeout disabled				

Table 9. Debounce Register Format (0x02)

				REGIST	ER DATA			
REGISTER DESCRIPTION	D7	D6	D5	D4	D3	D2	D1	D0
	РО	RTS ENA	BLE		DEE	SOUNCE 1	IME	
Debounce time is 9ms	Χ	Х	Х	0	0	0	0	0
Debounce time is 10ms	Χ	Х	Х	0	0	0	0	1
Debounce time is 11ms	Χ	Х	Х	0	0	0	1	0
Debounce time is 12ms	Χ	Х	Х	0	0	0	1	1
Debounce time is 37ms	Χ	X	X	1	1	1	0	0
		:						
Debounce time is 37ms Debounce time is 38ms	X	X	X	1	1	1	0	1
Debounce time is 39ms	X	X	X	1	1	1	1	0
Debounce time is 40ms	Χ	Х	Х	1	1	1	1	1
GPO ports disabled (full key-scan functionality)	0	0	0	Х	Х	Х	Х	Х
GPO port 7 enabled	0	0	1	Х	Х	Х	Х	Х
GPO ports 7 and 6 enabled	0	1	0	Х	Х	Х	Х	Х

Table 9. Debounce Register Format (0x02) (continued)

		REGISTER DATA						
REGISTER DESCRIPTION	D7	D6	D5	D4	D3	D2	D1	D0
	PORTS ENABLE			DEBOUNCE TIME				
GPO ports 7, 6, and 5 enabled	0	1	1	X	X	X	X	X
GPO ports 7, 6, 5, and 4 enabled	1	0	0	X	X	X	X	X
GPO ports 7, 6, 5, 4, and 3 enabled	1	0	1	Х	Х	Х	Х	Х
GPO ports 7, 6, 5, 4, 3, and 2 enabled	1	1	Х	Х	Х	Х	Х	Х
Power-up default setting	1	1	1	1	1	1	1	1

Table 10. Key-Switch Interrupt Register Format (0x03)

		REGISTER DATA								
REGISTER DESCRIPTION	D7	D6	D5	D4	D3	D2	D1	D0		
	FIFC	-BASED	NTK	TIME-BASED INTK						
INTK used as GPO	0	0	0	0	0	0	0	0		
FIFO-based INTK disabled	0 0 0 Not all zero)					
INTK asserts every debounce cycle	0	0	0	0	0	0	0	1		
INTK asserts every 2 debounce cycles	0	0	0	0	0	0	1	0		
		•								
The second secon		•								
INTK asserts every 29 debounce cycles	0	0	0	1	1	1	0	1		
INTK asserts every 30 debounce cycles	0	0	0	1	1	1	1	0		
INTK asserts every 31 debounce cycles	0	0	0	1	1	1	1	1		
Time-based INTK disabled		Not all zero)	0	0	0	0	0		
INTK asserts when FIFO has 4 key events	0	0	1	0	0	0	0	0		
INTK asserts when FIFO has 6 key events	0	1	0	0	0	0	0	0		
INTK asserts when FIFO has 8 key events	0	1	1	0	0	0	0	0		
INTK asserts when FIFO has 14 key events	1	1	1	0	0	0	0	0		
Both time-based and FIFO-based interrupts active	I	Not all zer	0			Not all zero	0			
Power-up default setting	0	0	0	0	0	0	0	0		

Table 11. Ports Register Format (0x04)

REGISTER BIT	DESCRIPTION	VALUE	FUNCTION	DEFAULT VALUE		
D7	PORT 7 Control	0	Clear port 7 low	4		
	FORT / CONTION	1	Set port 7 high (high impedance)	ı		
D6	PORT 6 Control	0	Clear port 6 low	4		
D6	PORT 6 CONTROL	1	Set port 6 high (high impedance)	'		
D5	PORT 5 Control	0	Clear port 5 low	4		
D5	PORT 5 CONTROL	1	Set port 5 high (high impedance)	'		
D4	PORT 4 Control	0	Clear port 4 low	4		
D4	FORT 4 CONTION	1	Set port 4 high (high impedance)	'		
D3	PORT 3 Control	0	Clear port 3 low	1		
DS	PORT 3 CONTROL	1	Set port 3 high (high impedance)	'		
Do	DODT 2 Control	0	Clear port 2 low	4		
D2	D2 PORT 2 Control		Set port 2 high (high impedance)			
D1	INITI/ Davt Cantral	0	Clear port INTK low	4		
וט	D1 INTK Port Control 1		Set port INTK high (high impedance)			
D0	Reserved	0	_	0		

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Table 12. Autorepeat Register Format (0x05)

D7 D6 D5 D4 D3 D2 D1	X
Autorepeat is disabled Autorepeat is enabled 1 AUTOREPEAT RATE AUTOREPEAT DE Key-switch autorepeat delay is 8 debounce cycles 1 X X X X X X X X X X X X X X X X X X	XAY 0
Autorepeat is enabled 1 AUTOREPEAT RATE Key-switch autorepeat delay is 8 debounce cycles 1 X X X X 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0	AY 0
Autorepeat is enabled Autorepeat is enabled 1	0 1
Key-switch autorepeat delay is 16 debounce cycles Key-switch autorepeat delay is 24 debounce cycles Key-switch autorepeat delay is 112 debounce cycles Key-switch autorepeat delay is 112 debounce cycles 1	1
Key-switch autorepeat delay is 24 debounce cycles Key-switch autorepeat delay is 112 debounce 1 X X X X 0 0 0 1 Key-switch autorepeat delay is 112 debounce cycles Key-switch autorepeat delay is 120 debounce 1 X X X X 1 1 1 0 Key-switch autorepeat delay is 128 debounce 1 X X X X 1 1 1 1 1 Key-switch autorepeat delay is 128 debounce 1 X X X X X 1 1 1 1 1	
Key-switch autorepeat delay is 112 debounce cycles 1	0
Key-switch autorepeat delay is 120 debounce 1 X X X 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1	
Key-switch autorepeat delay is 120 debounce 1 X X X 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1	
cycles	1
	0
·	1
Key-switch autorepeat frequency is 4 debounce cycles 1 0 0 0 X X X	Х
Key-switch autorepeat frequency is 8 debounce cycles 1 0 0 1 X X X	Х
Key-switch autorepeat frequency is 12 1 0 1 0 X X X X debounce cycles	Х
:	
Key-switch autorepeat frequency is 32 1 1 1 1 X X X X	X
debounce cycles	0

Table 13. Autosleep Register Format (0x06)

REGISTER		REGISTER DATA							
AUTOCI EED DEGISTED		RESE	RVED		AUTOSHUTDOWN TIME				
AUTOSLEEP REGISTER	D7	D6	D5	D4	D3	D2	D1	D0	
No Autosleep	0	0	0	0	0	0	0	0	
Autosleep for (ms)									
8192	0	0	0	0	0	0	0	1	
4096	0	0	0	0	0	0	1	0	
2048	0	0	0	0	0	0	1	1	
1024	0	0	0	0	0	1	0	0	
512	0	0	0	0	0	1	0	1	
256	0	0	0	0	0	1	1	0	
256	0	0	0	0	0	1	1	1	
Power-up default settings	0	0	0	0	0	1	1	1	

Table 14. GPIO Global Configuration Register (0x40)

REGISTER BIT	DESCRIPTION	VALUE	FUNCTION	DEFAULT VALUE
D7	PORT6/PORT7	0	PORT6/PORT7 operate as GPIOs	0
	rotary switch	1	PORT6/PORT7 operate as a rotary switch input	
D6	Reserved	0	<u> </u>	0
	120 #	0	Disabled	_
D5	I ² C timeout interrupt enable	1	INTI is asserted when I ² C bus times out. INTI is deasserted when a read is performed on the I ² C timeout flag register (0x48).	0
D4	GPIO enable	0	PWM, constant-current circuits, and GPIs are shut down. GPO values depend on their setting. Register 0x41 to 0x5F values are stored and cannot be changed. The entire part is shut down if the key switches are in sleep mode (D7 of register 0x01).	0
	1		Normal GPIO operation. PWM, constant-current circuits, and GPIOs are enabled regardless of key-switch sleep mode state (see Table 8).	
		0	Normal operation	
D3	GPIO reset	1	Return all GPIO registers (registers 0x40 to 0x5F) to their POR value. This bit is momentary and resets itself to 0 after the write cycle.	0
		000	No fading	
D[2:0]	Fade in/out time	XXX	PWM intensity ramps up (down) between the common PWM value and 0% duty cycle in 16 steps over the following time period: D[2:0] = 001 = 256ms D[2:0] = 010 = 512ms D[2:0] = 011 = 1024ms D[2:0] = 100 = 2048ms D[2:0] = 101 = 4096ms D[2:0] = 110/111 = Undefined	000

Table 15. GPIO Control Register (0x41)

REGISTER BIT	DESCRIPTION	VALUE	FUNCTION	DEFAULT VALUE
D.7	DODT?	0	Port is an input	
D7	PORT7	1	Port is an output	0
Do	DODTO	0	Port is an input	
D6	PORT6	1	Port is an output	0
D.F.	DODTE	0	Port is an input	
D5	PORT5	1	Port is an output	0
D4	DODT4	0	Port is an input	
D4	PORT4	1	Port is an output	0
D0	DODTO	0	Port is an input	
D3	PORT3	1	Port is an output	0
D0	DODTO	0	Port is an input	
D2	PORT2	1	Port is an output	0
D.1	DODTA	0	Port is an input	
D1	PORT1	1	Port is an output	0
D0	DODTO	0	Port is an input]
D0	PORT0	1	Port is an output	0

Table 16. GPIO Debounce Configuration Register (0x42)

	REGISTER DATA										
D7	D6	D5	D4	D3	D2	D1	D0				
	RESERVEI)		DE	BOUNCE T	IME					
0	0	0	0	0	0	0	0				
0	0	0	0	0	0	0	1				
0	0	0	0	0	0	1	0				
0	0	0	0	0	0	1	1				
0		0	1	1	1	0	0				
 	<u> </u>	_	1	1	1		1				
	1		1	1	1	1	0				
		_									
	0	RESERVED 0	RESERVED 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0	RESERVED 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0	RESERVED 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0	RESERVED	RESERVED DEBOUNCE TIME				

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I²C-Interfaced Key-Switch Controller and LED Driver/GPIOs with Integrated ESD Protection

Table 17. GPIO Constant-Current Setting Register (0x43)

REGISTER BIT	DESCRIPTION	VALUE	FUNCTION	DEFAULT VALUE
D[7:6]	Reserved	11	Set always as 11	11
D[5:2]	Reserved	0000	_	0000
		00	Constant current is 5mA	
D[4 0]	Constant-	01	Constant current is 6.67mA	00
D[1:0]	current setting	10	Constant current is 10mA	00
		11	Constant current is 20mA	

Table 18. GPIO Output Mode Register (0x44)

REGISTER BIT	DESCRIPTION	VALUE	FUNCTION	DEFAULT VALUE
	DODT7	0	Port is a constant-current open-drain output	
D7	PORT7	1	Port is a non-constant-current open-drain output	0
DC	DODTO	0	Port is a constant-current open-drain output	
D6	PORT6	1	Port is a non-constant-current open-drain output	0
Dr	DODTE	0	Port is a constant-current open-drain output	
D5	PORT5	1	Port is a non-constant-current open-drain output	0
D.4	DODT4	0	Port is a constant-current open-drain output	
D4	PORT4	1	Port is a non-constant-current open-drain output	0
50	DODTO	0	Port is a constant-current open-drain output	
D3	PORT3	1	Port is a non-constant-current open-drain output	0
50	DODTO	0	Port is a constant-current open-drain output	
D2	PORT2	1	Port is a non-constant-current open-drain output	0
D.1	DODT4	0	Port is a constant-current open-drain output	
D1	PORT1	1	Port is a non-constant-current open-drain output	0
D0	DODTO	0	Port is a constant-current open-drain output	
D0	PORT0	1	Port is a non-constant-current open-drain output	0

Table 19. Common PWM Register (0x45)

	REGISTER DATA								
REGISTER DESCRIPTION	D7	D6	D5	D4	D3	D2	D1	D0	
				СОММО	ON PWM				
Power-up default setting (common PWM ratio is 0/256)	0	0	0	0	0	0	0	0	
Common PWM ratio is 1/256	0	0	0	0	0	0	0	1	
Common PWM ratio is 2/256	0	0	0	0	0	0	1	0	
Common PWM ratio is 3/256	0	0	0	0	0	0	1	1	

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Table 19. Common PWM Register (0x45) (continued)

		REGISTER DATA						
REGISTER DESCRIPTION	D7	D6	D5	D4	D3	D2	D1	D0
				СОММС	N PWM			
Common PWM ratio is 252/256	1	1	1	1	1	1	0	0
Common PWM ratio is 253/256	1	1	1	1	1	1	0	1
Common PWM ratio is 254/256	1	1	1	1	1	1	1	0
Common PWM ratio is 256/256 (100% duty cycle)	1	1	1	1	1	1	1	1

Table 20. Rotary Switch Configuration Register (0x46)

				REGISTI	R DATA								
DECICIED DECODIDATION	D7	D6	D5	D4	D3	D2	D1	D0					
REGISTER DESCRIPTION	INT TYPE	COL	JNTS/CYC	LES	DE	BOUNCE	CYCLE T	IME					
No debounce time	X	Χ	Х	Х	0	0	0	0					
Debounce time is 1ms	X	Χ	X	X	0	0	0	1					
Debounce time is 2ms	X	Χ	X	X	0	0	1	0					
Debounce time is 3ms	X	Χ	X	X	0	0	1	1					
Debounce time is 15ms	X	X	X	X	1	1	1	1					
No interrupt generated by rotary switch	Χ	0	0	0	Χ	Χ	Χ	X					
INTI asserted when rotary switch count = ±1	0	0	0	1	Χ	Χ	X	X					
INTI asserted when rotary switch count = ±2	0	0	1	0	Χ	Χ	Χ	Χ					
INTI asserted when rotary switch count = ±3	0	0	1	1	Χ	Χ	X	X					
INTI asserted when rotary switch count = ±7	0	1	1	1	Χ	Χ	X	X					
INTI asserted 25ms after first debounced event	1	0	0	1	Х	Х	X	X					
INTI asserted 50ms after first debounced event	1	0	1	0	Х	Х	Х	X					
INTI asserted 75ms after first debounced event	1	0	1	1	Х	X	Х	X					
INTI asserted 175ms after first debounced event	1	1	1	1	Χ	Χ	X	X					
Power-up default setting	0	0	0	0	0	0	0	0					

Table 21. I²C Timeout Flag Register (0x48) (Read Only)

REGISTER BIT	DESCRIPTION	VALUE	FUNCTION	DEFAULT VALUE
D[7:1]	Reserved	0000000	_	0000000
		0	No I ² C timeout has occurred since last read or POR	
D0	I ² C timeout flag	1	I ² C timeout has occurred since last read or POR. This bit is reset to zero when a read is performed on this register. I ² C timeouts must be enabled for this function to work (see Table 8).	0

Table 22. GPIO Input Register (0x49) (Read Only)

REGISTER BIT	DESCRIPTION	VALUE	FUNCTION	DEFAULT VALUE
D7	DODT7	0	Port is input low	_
D7	PORT7	1	Port is input high	1
DC	DODTO	0	Port is input low	
D6	PORT6	1	Port is input high	1
DE	DODTE	0	Port is input low	
D5	PORT5	1	Port is input high	1
D.4	DODT4	0	Port is input low	
D4	PORT4	1	Port is input high	1
D0	DODTO	0	Port is input low	
D3	PORT3	1	Port is input high	1
D0	DODTO	0	Port is input low	
D2	PORT2	1	Port is input high	1
D.1	DODTA	0	Port is input low	
D1	PORT1	1	Port is input high	1
D0	DODTO	0	Port is input low	
D0	PORT0	1	Port is input high	1

Table 23. Rotary Switch Count Register (0x4A) (Read Only)

	•	• ,	•	• • •				
	REGISTER DATA							
REGISTER DESCRIPTION	D7	D6	D5	D4	D3	D2	D1	D0
	CYCLE COUNT							
Cycle count in two's complement (see the Rotary Switch Configuration Register (0x46) section)	X	×	Х	×	Х	×	Х	X

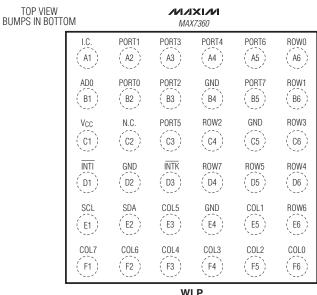
Table 24. PORT0-PORT7 Individual PWM Ratio Registers (0x50 to 0x57)

	REGISTER DATA							
REGISTER DESCRIPTION	D7	D6	D5	D4	D3	D2	D1	D0
	PORT PWM							
Power-up default setting (port PWM ratio is 0/256)	0	0	0	0	0	0	0	0
PORT PWM ratio is 1/256	0	0	0	0	0	0	0	1
PORT PWM ratio is 2/256	0	0	0	0	0	0	1	0
PORT PWM ratio is 3/256	0	0	0	0	0	0	1	1
		•						
		•	1	1		1		
PORT PWM ratio is 252/256	1	1	1	1	1	1	0	0
PORT PWM ratio is 253/256	1	1	1	1	1	1	0	1
PORT PWM ratio is 254/256	1	1	1	1	1	1	1	0
PORT PWM ratio is 256/256 (100% duty cycle)	1	1	1	1	1	1	1	1

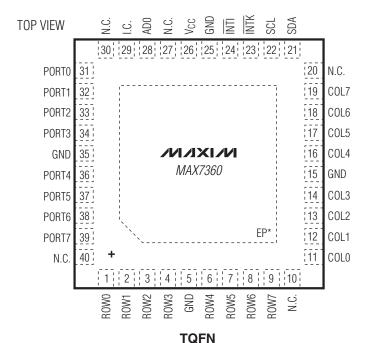
Table 25. PORT0-PORT7 Configuration Registers (0x58 to 0x5F)

REGISTER BIT	DESCRIPTION	VALUE		FUNCTION	DEFAULT VALUE		
		0	Interrupt is not masked				
D7	Interrupt mask	1		nterrupt is masked. PORT7 interrupt mask is ignored when the device is configured for rotary switch input.			
D0	Edge/level	0	Rising edge-triggered interrupts	Interrupts only occur when the GPIO port			
D6	detect	1	Rising or falling edge- triggered interrupts	is configured as an input	0		
DE	O	0	Port uses individual PWM intensity register to set the PWM ra				
D5	Common PWM	11	Port uses common PWM	intensity register to set the PWM ratio	0		
		000	Port does not blink				
		001	Port blink period is 256m	S			
		010	Port blink period is 512m	S			
D[4:2]	Blink period	011	Port blink period is 1024r	ns	000		
		100	Port blink period is 2048r	ns			
		101	Port blink period is 4096r	ms			
		110/111	Undefined				
		00	LED is on for 50% of the	blink period			
D[1.0]	Blink-on time	01	LED is on for 25% of the	blink period	00		
D[1:0]	Dillik-on time	10	LED is on for 12.5% of th	e blink period	00		
		11	LED is on for 6.25% of th	e blink period			

Pin Configurations

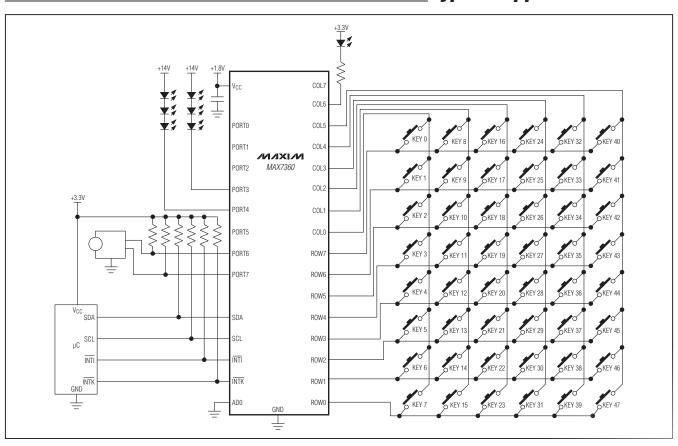


WLP (2.67mm x 2.67mm)



*EP = EXPOSED PAD, CONNECT EP TO GROUND.

Typical Application Circuit



Chip Information

_____Package Information

For the latest package outline information and land patterns, go to www.maxim-ic.com/packages.

PACKAGE TYPE	PACKAGE CODE	DOCUMENT NO.
40 TQFN-EP	T4055+1	21-0140
36 WLP	W362A2+1	21-0301

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PROCESS: BICMOS

Revision History

REVISION NUMBER	REVISION DATE	DESCRIPTION	PAGES CHANGED
0	4/09	Initial release	_
1	8/10	Updated Absolute Maximum Ratings and Notes 7 and 8 (now Notes 6 and 7) in Electrical Characteristics	2, 3, 4

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