

# SINGLE-ENDED, ANALOG-INPUT 24-BIT, 96-kHz STEREO A/D CONVERTER

#### **FEATURES**

- 24-Bit Delta-Sigma Stereo A/D Converter
- Single-Ended Voltage Input: 3 Vp-p
- High Performance:
  - THD + N: -93 dB (Typical)
  - SNR: 99 dB (Typical)
  - Dynamic Range: 99 dB (Typical)
- Oversampling Decimation Filter:
  - Oversampling Frequency: ×64
  - Pass-Band Ripple: ±0.05 dB
  - Stop-Band Attenuation: –65 dB
  - On-Chip High-Pass Filter: 0.91 Hz (48 kHz)
- Flexible PCM Audio Interface
  - Master/Slave Mode Selectable
  - Data Formats: 24-Bit I<sup>2</sup>S, 24-Bit Left-Justified
- Power Down and Reset by Halting System Clock
- Analog Antialias LPF Included
- Sampling Rate: 8 kHz-96 kHz
- System Clock: 256 f<sub>S</sub>, 384 f<sub>S</sub>, 512 f<sub>S</sub>
- Dual Power Supplies:
  - 5-V for Analog
  - 3.3-V for Digital
- Package: 14-Pin TSSOP

#### **APPLICATIONS**

- DVD Recorder
- Digital TV
- AV Amplifier/Receiver
- MD Player
- CD Recorder
- Multitrack Receiver
- Electric Musical Instrument

#### DESCRIPTION

The PCM1808 is high-performance, low-cost, single-chip, stereo analog-to-digital converter with single-ended analog voltage input. The PCM1808 uses a delta-sigma modulator with 64-times oversampling and includes a digital decimation filter and high-pass filter that removes the dc component of the input signal. For various applications, the PCM1808 supports master and slave mode and two data formats in serial audio interface.

The PCM1808 supports the power-down and reset function by means of halting the system clock.

The PCM1808 is suitable for wide variety of cost-sensitive consumer applications where good performance and operation with a 5-V analog supply and 3.3-V digital supply is required. The PCM1808 is fabricated using a highly advanced CMOS process and is available in a small, 14-pin TSSOP package.



Please be aware that an important notice concerning availability, standard warranty, and use in critical applications of Texas Instruments semiconductor products and disclaimers thereto appears at the end of this data sheet.

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This integrated circuit can be damaged by ESD. Texas Instruments recommends that all integrated circuits be handled with appropriate precautions. Failure to observe proper handling and installation procedures can cause damage.

ESD damage can range from subtle performance degradation to complete device failure. Precision integrated circuits may be more susceptible to damage because very small parametric changes could cause the device not to meet its published specifications.

#### **ABSOLUTE MAXIMUM RATINGS**

over operating free-air temperature range (unless otherwise noted) (1)

	PCM1808
Analog supply voltage, V <sub>CC</sub>	–0.3 V to 6.5 V
Digital supply voltage, V <sub>DD</sub>	-0.3 V to 4 V
Ground voltage differences, AGND, DGND	±0.1 V
Digital input voltage, LRCK, BCK, DOUT	$-0.3 \text{ V to } (V_{DD} + 0.3 \text{ V}) < 4 \text{ V}$
Digital input voltage, SCKI, MD0, MD1, FMT	−0.3 V to 6.5 V
Analog input voltage, V <sub>IN</sub> L, V <sub>IN</sub> R, V <sub>REF</sub>	$-0.3 \text{ V to } (\text{V}_{\text{CC}} + 0.3 \text{ V}) < 6.5 \text{ V}$
Input current (any pins except supplies)	±10 mA
Ambient temperature under bias, T <sub>A</sub>	-40°C to 125°C
Storage temperature, T <sub>stg</sub>	−55°C to 150°C
Junction temperature, T <sub>J</sub>	150°C
Lead temperature (soldering)	260°C, 5 s
Package temperature (reflow, peak)	260°C

<sup>(1)</sup> Stresses beyond those listed under "absolute maximum ratings" may cause permanent damage to the device. These are stress ratings only, and functional operation of the device at these or any other conditions beyond those indicated under "recommended operating conditions" is not implied. Exposure to absolute-maximum-rated conditions for extended periods may affect device reliability.

#### RECOMMENDED OPERATING CONDITIONS

over operating free-air temperature range (unless otherwise noted)

		MIN	NOM	MAX	UNIT
Analog supply voltage, V <sub>CC</sub>		4.5	5	5.5	V
Digital supply voltage, V <sub>DD</sub>		2.7	3.3	3.6	V
Analog input voltage, full scale (-0 dB)	V <sub>CC</sub> = 5 V		3		Vp-p
Digital input logic family		TTL	TTL compatible		
Digital input clock frequency, system clock		2.048		49.152	MHz
Digital input clock frequency, sampling clock		8		96	kHz
Digital output load capacitance				20	pF
Operating free-air temperature, T <sub>A</sub>		-40		85	°C



#### **ELECTRICAL CHARACTERISTICS**

All specifications at  $T_A = 25$ °C,  $V_{CC} = 5$  V,  $V_{DD} = 3.3$  V, master mode,  $f_S = 48$  kHz, system clock = 512  $f_S$ , 24-bit data, unless otherwise noted

	PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT	
	Resolution			24		Bits	
DATA FO	RMAT						
	Audio data interface format		I <sup>2</sup> S,	left-justified			
	Audio data bit length			24		Bits	
	Audio data format		MSB-first	, 2s compleme	ent		
f <sub>S</sub>	Sampling frequency		8	48	96	kHz	
		256 f <sub>S</sub>	2.048	12.288	24.576		
	System clock frequency	384 f <sub>S</sub>	3.072	18.432	36.864	MHz	
		512 f <sub>S</sub>	4.096	24.576	49.152		
INPUT LO	GIC						
V <sub>IH</sub> <sup>(1)</sup>			2		$V_{DD}$		
V <sub>IL</sub> <sup>(1)</sup>	lanut lania laural		0		0.8	VDC	
V <sub>IH</sub> <sup>(2)(3)</sup>	Input logic level		2		5.5	VDC	
V <sub>IL</sub> <sup>(2)(3)</sup>			0		0.8		
I <sub>IH</sub> (2)		$V_{IN} = V_{DD}$			±10		
I <sub>IL</sub> (2)	Lange to sign assessed	V <sub>IN</sub> = 0 V			±10		
I <sub>IH</sub> (1) (3)	Input logic current	$V_{IN} = V_{DD}$		65	100	μΑ	
I <sub>IL</sub> <sup>(1)(3)</sup>		V <sub>IN</sub> = 0 V			±10		
OUTPUT I	OGIC						
V <sub>OH</sub> <sup>(4)</sup>	Outrod to via laural	I <sub>OUT</sub> = -4 mA	2.8			\/D0	
V <sub>OL</sub> <sup>(4)</sup>	Output logic level	I <sub>OUT</sub> = 4 mA			0.5	VDC	
DC ACCU	RACY						
	Gain mismatch, channel-to-channel			±1	±3	% of FSR	
	Gain error			±3	±6	% of FSR	
DYNAMIC	PERFORMANCE (5)						
		$V_{IN} = -0.5 \text{ dB}, f_{S} = 48 \text{ kHz}$		-93	-87		
TUD . N	Total hammania distantian , naina	$V_{IN} = -0.5 \text{ dB}, f_S = 96 \text{ kHz}^{(6)}$		-87		-10	
THD + N	Total harmonic distortion + noise	$V_{IN} = -60 \text{ dB}, f_S = 48 \text{ kHz}$		-37		dB	
		$V_{IN} = -60 \text{ dB}, f_S = 96 \text{ kHz}^{(6)}$		-39		7	
	Dimensia seres	f <sub>S</sub> = 48 kHz, A-weighted	95	99		.ID	
	Dynamic range	f <sub>S</sub> = 96 kHz, A-weighted <sup>(6)</sup>		101		dB	
C/N	Cinnel to pain patin	f <sub>S</sub> = 48 kHz, A-weighted	95	99		4D	
S/N	Signal-to-noise ratio	f <sub>S</sub> = 96 kHz, A-weighted <sup>(6)</sup>		101		dB	
	Ohannal annand	f <sub>S</sub> = 48 kHz	93	97		dB	
	Channel separation	f <sub>S</sub> = 96 kHz <sup>(6)</sup>		91			

<sup>(1)</sup> Pins 7, 8: LRCK, BCK (Schmitt-trigger input, with  $50-k\Omega$  typical pulldown resistor, in slave mode)

 <sup>(1)</sup> Pins 7, 8. LRCK, BCK (Schinitt-trigger input, with 50-kΩ typical pulldown resistor, in slave mode)
 (2) Pin 6: SCKI (Schmitt-trigger input, 5-V tolerant)
 (3) Pins 10–12: MD0, MD1, FMT (Schmitt-trigger input, with 50-kΩ typical pulldown resistor, 5-V tolerant)
 (4) Pins 7–9: LRCK, BCK (in master mode), DOUT

<sup>(5)</sup> Analog performance specifications are tested using a System Two™ audio measurement system by Audio Precision™ with 400-Hz HPF and 20-kHz LPF in RMS mode.

<sup>(6)</sup>  $f_S = 96 \text{ kHz}$ , system clock = 256  $f_S$ .



## **ELECTRICAL CHARACTERISTICS (continued)**

All specifications at  $T_A = 25^{\circ}\text{C}$ ,  $V_{CC} = 5$  V,  $V_{DD} = 3.3$  V, master mode,  $f_S = 48$  kHz, system clock = 512  $f_S$ , 24-bit data, unless otherwise noted

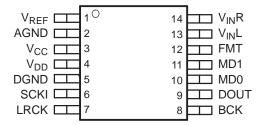
	PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT
ANALO	G INPUT		-			
	Input voltage			0.6 V <sub>CC</sub>		Vp-p
	Center voltage (V <sub>REF</sub> )			0.5 V <sub>CC</sub>		V
	Input impedance			60		kΩ
	Antialiasing filter frequency response	-3 dB		1.3		MHz
DIGITA	L FILTER PERFORMANCE				<u> </u>	
	Pass band				0.454 f <sub>S</sub>	Hz
	Stop band		0.583 f <sub>S</sub>			Hz
	Pass-band ripple				±0.05	dB
	Stop-band attenuation		-65			dB
	Delay time			17.4/f <sub>S</sub>		
	HPF frequency response	–3 dB	0.0	19 f <sub>S</sub> /1000		
POWER	R SUPPLY REQUIREMENTS				·	
V <sub>CC</sub>	Voltage range		4.5	5	5.5	VDC
$V_{DD}$	voltage range		2.7	3.3	3.6	VDC
		$f_S = 48 \text{ kHz}, 96 \text{ kHz}^{(8)}$		8.6	11	mA
I <sub>CC</sub>		Powered down (9)		1		μΑ
	Supply current (7)	$f_S = 48 \text{ kHz}$		5.9	8	mA
$I_{DD}$		$f_S = 96 \text{ kHz}^{(8)}$		10.2		mA
		Powered down (9)		150		μΑ
		$f_S = 48 \text{ kHz}$		62	81	mW
	Power dissipation (7)	f <sub>S</sub> = 96 kHz <sup>(8)</sup> 77			mvv	
		Powered down (9)		500		μW
TEMPE	RATURE RANGE					
T <sub>A</sub>	Operation temperature		-40		85	°C
$\theta_{JA}$	Thermal resistance			170		°C/W

 <sup>(7)</sup> Minimum load on LRCK (pin 7), BCK (pin 8), DOUT (pin 9)
 (8) f<sub>S</sub> = 96 kHz, system clock = 256 f<sub>S</sub>.
 (9) Power-down and reset functions enabled by halting SCKI, BCK, LRCK.



## **PIN ASSIGNMENTS**

#### PW PACKAGE (TOP VIEW)



P0032-02

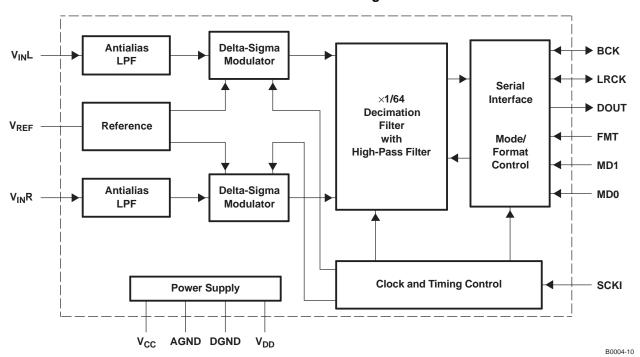
#### **TERMINAL FUNCTIONS**

TERMINAL		I/O	DESCRIPTION		
NAME	PIN				
AGND	2	_	Analog GND		
BCK	8	I/O	Audio data bit clock input/output (1)		
DGND	5	_	Digital GND		
DOUT	9	0	Audio data digital output		
FMT	12	1	Audio interface format select (2)		
LRCK	7	I/O	Audio data latch enable input/output (1)		
MD0	10	- 1	Audio interface mode select 0 (2)		
MD1	11	- 1	Audio interface mode select 1 (2)		
SCKI	6	I	System clock input; 256 f <sub>S</sub> , 384 f <sub>S</sub> or 512 f <sub>S</sub> <sup>(3)</sup>		
V <sub>CC</sub>	3	_	Analog power supply, 5-V		
$V_{DD}$	4	_	Digital power supply, 3.3-V		
V <sub>IN</sub> L	13	1	Analog input, L-channel		
V <sub>IN</sub> R	14	- 1	Analog input, R-channel		
V <sub>REF</sub>	1	_	Reference voltage decoupling (= 0.5 V <sub>CC</sub> )		

- Schmitt-trigger input with internal pulldown (50-kΩ, typical)
   Schmitt-trigger input with internal pulldown (50-kΩ, typical), 5-V tolerant
   Schmitt-trigger input, 5-V tolerant



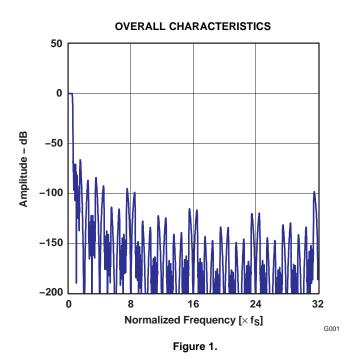
#### **Functional Block Diagram**



#### TYPICAL PERFORMANCE CURVES OF INTERNAL FILTERS

All specifications at  $T_A = 25$ °C,  $V_{CC} = 5$  V,  $V_{DD} = 3.3$  V, master mode,  $f_S = 48$  kHz, system clock = 512  $f_S$ , 24-bit data, unless otherwise noted.

## **DECIMATION FILTER FREQUENCY RESPONSE**



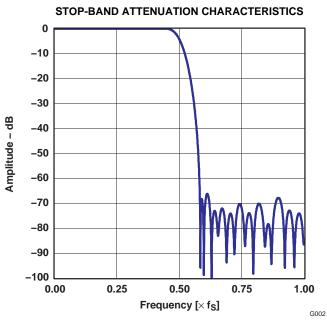


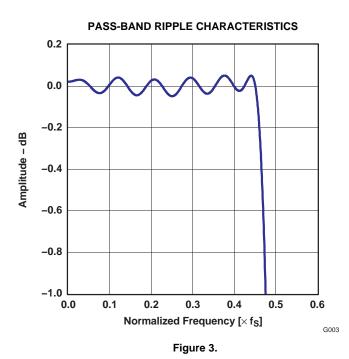
Figure 2.



## TYPICAL PERFORMANCE CURVES OF INTERNAL FILTERS (Continued)

All specifications at  $T_A = 25$ °C,  $V_{CC} = 5$  V,  $V_{DD} = 3.3$  V, master mode,  $f_S = 48$  kHz, system clock = 512  $f_S$ , 24-bit data, unless otherwise noted.

## **DECIMATION FILTER FREQUENCY RESPONSE (Continued)**



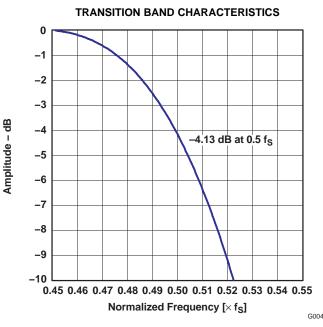
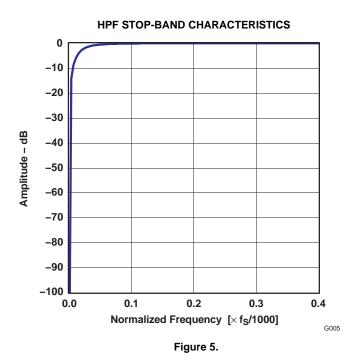
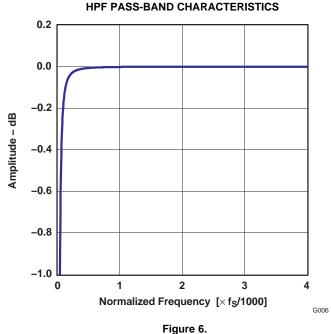


Figure 4.

#### **HIGH-PASS FILTER FREQUENCY RESPONSE**

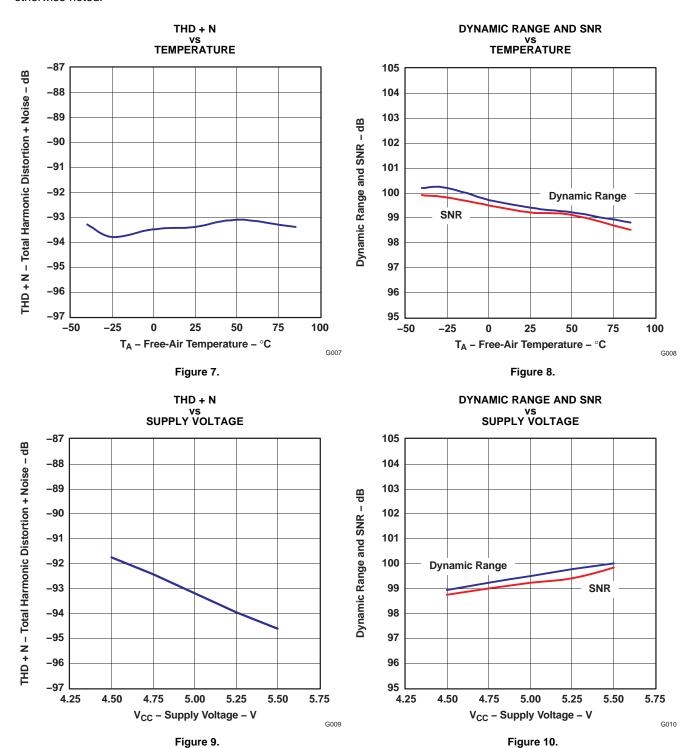






## **TYPICAL PERFORMANCE CURVES**

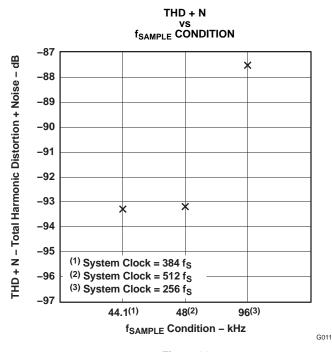
All specifications at  $T_A = 25$ °C,  $V_{CC} = 5$  V,  $V_{DD} = 3.3$  V, master mode,  $f_S = 48$  kHz, system clock = 512  $f_S$ , 24-bit data, unless otherwise noted.





## **TYPICAL PERFORMANCE CURVES (Continued)**

All specifications at  $T_A = 25$ °C,  $V_{CC} = 5$  V,  $V_{DD} = 3.3$  V, master mode,  $f_S = 48$  kHz, system clock = 512  $f_S$ , 24-bit data, unless otherwise noted.

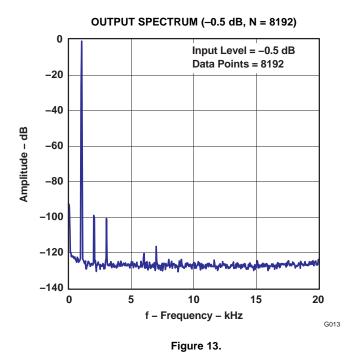


**DYNAMIC RANGE AND SNR** vs f<sub>SAMPLE</sub> CONDITION 105 × Dynamic Range 104 ▲ SNR 103 Dynamic Range and SNR - dB 102 101 100 99 98 97 (1) System Clock = 384 f<sub>S</sub> (2) System Clock = 512 f<sub>S</sub> 96 (3) System Clock = 256 f<sub>S</sub> 95 44.1(1) 48(2) 96(3) f<sub>SAMPLE</sub> Condition - kHz G012

Figure 11.

Figure 12.

#### **OUTPUT SPECTRUM**



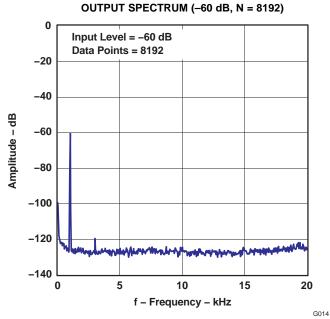


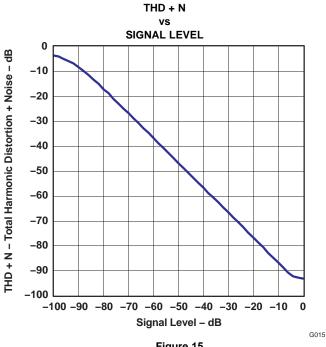
Figure 14.



## **TYPICAL PERFORMANCE CURVES (Continued)**

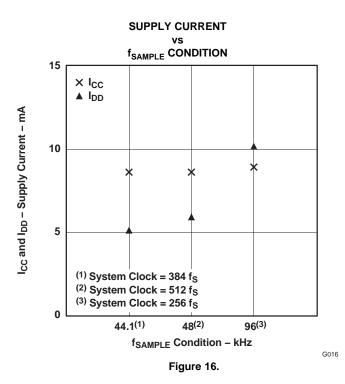
All specifications at  $T_A = 25$ °C,  $V_{CC} = 5$  V,  $V_{DD} = 3.3$  V, master mode,  $f_S = 48$  kHz, system clock = 512  $f_S$ , 24-bit data, unless otherwise noted.

## **OUTPUT SPECTRUM (Continued)**



#### Figure 15.

#### **SUPPLY CURRENT**





#### SYSTEM CLOCK

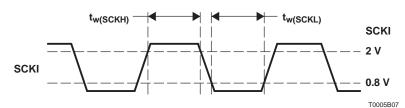
The PCM1808 supports 256  $f_S$ , 384  $f_S$  and 512  $f_S$  as system clock, where  $f_S$  is the audio sampling frequency. The system clock must be supplied on SCKI (pin 6).

The PCM1808 has a system clock detection circuit which automatically senses if the system clock is operating at 256  $f_S$ , 384  $f_S$ , or 512  $f_S$  in slave mode. In master mode, the system clock frequency must be controlled through the serial control port, which uses MD1 (pin 111) and MD0 (pin 10). The system clock is divided down automatically to generate frequencies of 128  $f_S$  and 64  $f_S$ , which are used to operate the digital filter and the delta-sigma modulator, respectively.

Table 1 shows some typical relationships between sampling frequency and system clock frequency, and Figure 17 shows system clock timing.

**SAMPLING FREQUENCY (kHz)** SYSTEM CLOCK FREQUENCY (f<sub>SCLK</sub>) (MHz) 256 f<sub>S</sub> 384 f<sub>S</sub> 512 f<sub>S</sub> 8 2.048 3.072 4.096 16 4.096 6.144 8.192 32 8.192 12.288 16.384 44.1 11.2896 16.9344 22.5792 12.288 18.432 48 24.576 64 16.384 24.576 32.768 88.2 22.5792 33.8688 45.1584 96 36.864 49.152 24.576

**Table 1. Sampling Frequency and System Clock Frequency** 



SYMBOL	PARAMETER	MIN	MAX	UNIT
t <sub>w(SCKH)</sub>	System clock pulse duration, HIGH	8		ns
t <sub>w(SCKL)</sub>	System clock pulse duration, LOW	8		ns
	System clock duty cycle	40%	60%	

Figure 17. System Clock Timing

#### **FADE-IN AND FADE-OUT FUNCTIONS**

The PCM1808 has fade-in and fade-out functions on DOUT (pin 9) to avoid pop noise, and the functions come into operation in some cases as described in several following sections. The level changes from 0 dB to mute or mute to 0 dB are performed using calculated pseudo S-shaped characteristics with zero-cross detection. Because of the zero-cross detection, the time needed for the fade in and fade out depends on the analog input frequency ( $f_{in}$ ). It takes  $48/f_{in}$  until processing is completed. If there is no zero cross during  $8192/f_{S}$ , DOUT is faded in or out by force during  $48/f_{S}$  (TIME OUT). Figure 18 illustrates the fade-in and fade-out operation processing.



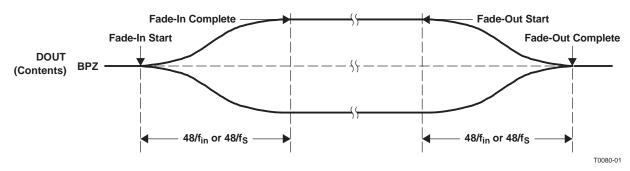


Figure 18. Fade-In and Fade-Out Operations

## **POWER ON**

The PCM1808 has an internal power-on-reset circuit, and initialization (reset) is performed automatically when the power supply ( $V_{DD}$ ) exceeds 2.2 V (typical). While  $V_{DD} <$  2.2 V (typical), and for 1024 system-clock counts after  $V_{DD} >$  2.2 V (typical), the PCM1808 stays in the reset state and the digital output is forced to zero. The digital output is valid after the reset state is released and the time of 8960/ $f_S$  has elapsed. Because the fade-in operation is performed, it takes additional time of  $48/f_S$  until the data corresponding to the analog input signal is obtained. Figure 19 illustrates the power-on timing and the digital output.

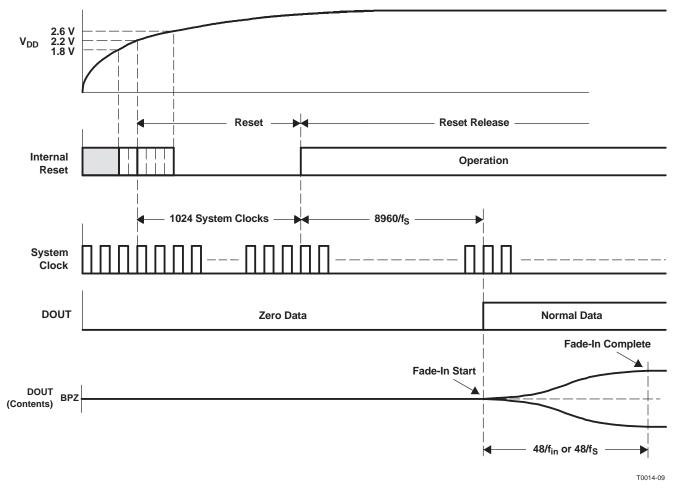


Figure 19. Power-On Timing

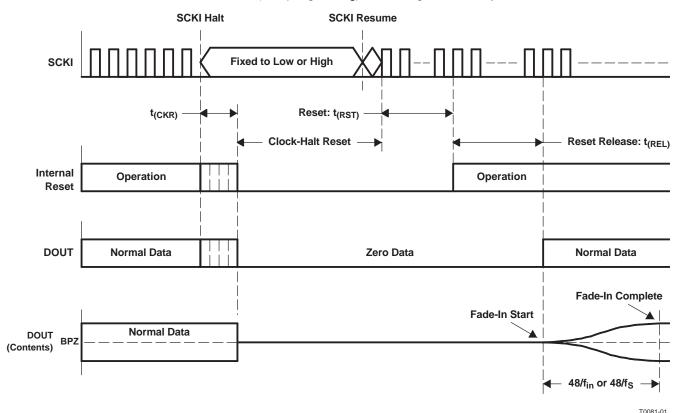


#### **CLOCK-HALT POWER-DOWN AND RESET FUNCTION**

The PCM1808 has a power-down and reset function, which is triggered by halting SCKI (pin 6) in both master and slave modes. The function is available anytime after power on. Reset and power down are performed automatically 4  $\mu$ s (minimum) after SCKI is halted. While the clock-halt reset is asserted, the PCM1808 stays in the reset and power-down mode, and DOUT (pin 9) is forced to zero. SCKI must be supplied to release the reset and power-down mode. The digital output is valid after the reset state is released and the time of 1024 SCKI + 8960/f<sub>S</sub> has elapsed. Because the fade-in operation is performed, it takes additional time of 48/f<sub>in</sub> or 48/f<sub>S</sub> until the level corresponding to the analog input signal is obtained. Figure 20 illustrates the clock-halt reset timing.

To avoid ADC performance degradation, BCK (pin 8) and LRCK (pin 7) are required to synchronize with SCKI within 4480/f<sub>S</sub> after SCKI is resumed. If it takes more than 4480/f<sub>S</sub> for BCK and LRCK to synchronize with SCKI, SCKI should be masked until the synchronization is achieved again, taking care of glitch and jitter. See the typical circuit connection diagram, Figure 26.

To avoid ADC performance degradation, the clock-halt reset also should be asserted when system clock SCKIor the audio interface clocks BCK and LRCK (sampling rate  $f_s$ ) are changed on the fly.



SYMBOL	PARAMETER	MIN	MAX	UNIT
t <sub>(CKR)</sub>	Delay time from SCKI halt to internal reset	4		μs
t <sub>(RST)</sub>	Delay time from SCKI resume to reset release		1024 SCKI	μs
t <sub>(REL)</sub>	Delay time from reset release to DOUT output		8960/f <sub>S</sub>	μs

Figure 20. Clock-Halt Power-Down and Reset Timing



#### **SERIAL AUDIO DATA INTERFACE**

The PCM1808 interfaces the audio system through LRCK (pin 7), BCK (pin 8), and DOUT (pin 9).

#### **INTERFACE MODE**

The PCM1808 supports master mode and slave mode as interface modes, which are selected by MD1 (pin 11) and MD0 (pin 10), as shown in Table 2. MD1 and MD0 must be set prior to power on.

In master mode, the PCM1808 provides the timing of serial audio data communications between the PCM1808 and the digital audio processor or external circuit. While in slave mode, the PCM1808 receives the timing for data transfer from an external controller.

**Table 2. Interface Modes** 

MD1 (Pin 11)	MD0 (Pin 10)	INTERFACE MODE
Low	Low	Slave mode (256 f <sub>S</sub> , 384 f <sub>S</sub> , 512 f <sub>S</sub> autodetection)
Low	High	Master mode (512 f <sub>S</sub> )
High	Low	Master mode (384 f <sub>S</sub> )
High	High	Master mode (256 f <sub>S</sub> )

#### Master mode

In master mode, BCK and LRCK work as output pins, and these pins are controlled by timing which is generated in the clock circuit of the PCM1808. The frequency of BCK is fixed at 64 BCK/frame.

#### Slave mode

In slave mode, BCK and LRCK work as input pins. The PCM1808 accepts 64-BCK/frame or 48-BCK/frame format (only for a 384-f<sub>S</sub> system clock), not 32-BCK/frame format.

#### **DATA FORMAT**

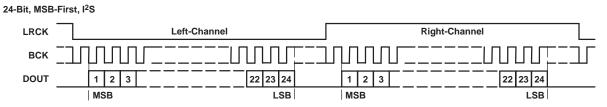
The PCM1808 supports two audio data formats in both master and slave modes. The data formats are selected by FMT (pin 12), as shown in Table 3. Figure 21 illustrates the data formats in slave mode and master mode.

**Table 3. Data Format** 

FORMAT NO.	FMT (Pin 12)	FORMAT				
0	Low	I <sup>2</sup> S, 24-bit				
1	High	Left-justified, 24-bit				



## FORMAT 0: FMT = LOW



## FORMAT 1: FMT = HIGH

24-Bit, MSB-First, Left-Justified

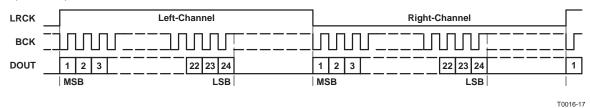
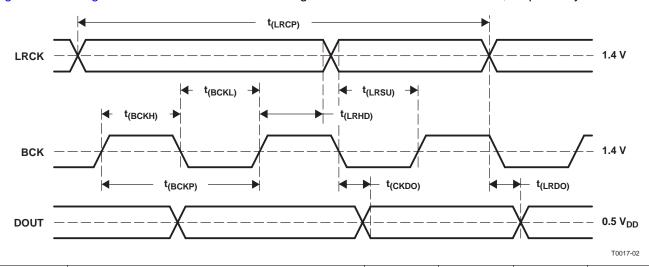


Figure 21. Audio Data Format (LRCK and BCK Work as Inputs in Slave Mode and as Outputs in Master Mode)



#### **INTERFACE TIMING**

Figure 22 and Figure 23 illustrate the interface timing in slave mode and master mode, respectively.

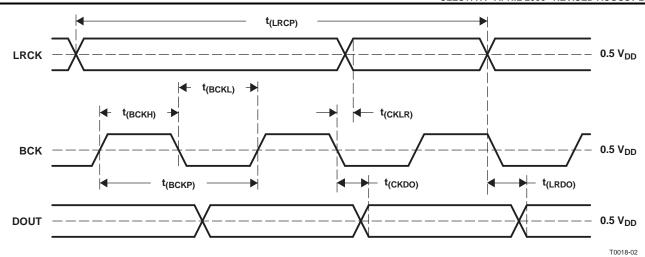


SYMBOL	PARAMETER	MIN	TYP	MAX	UNIT
t <sub>(BCKP)</sub>	BCK period	1/(64 f <sub>S</sub> )			ns
t <sub>(BCKH)</sub>	BCK pulse duration, HIGH	$1.5 \times t_{(SCKI)}$			ns
t <sub>(BCKL)</sub>	BCK pulse duration, LOW	$1.5 \times t_{(SCKI)}$			ns
t <sub>(LRSU)</sub>	LRCK setup time to BCK rising edge	50			ns
t <sub>(LRHD)</sub>	LRCK hold time to BCK rising edge	10			ns
t <sub>(LRCP)</sub>	LRCK period	10			μs
t <sub>(CKDO)</sub>	Delay time, BCK falling edge to DOUT valid	-10		40	ns
t <sub>(LRDO)</sub>	Delay time, LRCK edge to DOUT valid	-10		40	ns
t <sub>r</sub>	Rise time of all signals			20	ns
t <sub>f</sub>	Fall time of all signals			20	ns

NOTE: Timing measurement reference level is 1.4 V for input and 0.5  $V_{DD}$  for output. Rise and fall times are from 10% to 90% of the input/output signal swing. Load capacitance of DOUT is 20 pF.  $t_{(SCKI)}$  is the SCKI period.

Figure 22. Audio Data Interface Timing (Slave Mode: LRCK and BCK Work as Inputs)

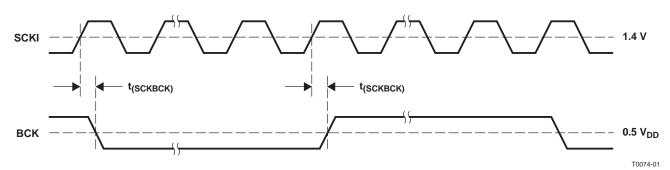




SYMBOL **PARAMETER** MIN TYP MAX UNIT BCK period 150 1/(64 f<sub>S</sub>) 2000 t(BCKP) ns BCK pulse duration, HIGH 65 1200 ns t(BCKH) BCK pulse duration, LOW 1200 65 ns t<sub>(BCKL)</sub> Delay time, BCK falling edge to LRCK valid -1020 ns t(CKLR) LRCK period 10  $1/f_S$ 125 μs t(LRCP) Delay time, BCK falling edge to DOUT valid -1020 t<sub>(CKDO)</sub> ns Delay time, LRCK edge to DOUT valid -10 20 ns t<sub>(LRDO)</sub> Rise time of all signals 20 ns Fall time of all signals 20

NOTE: Timing measurement reference level is 0.5 V<sub>DD</sub>. Rise and fall times are from 10% to 90% of the input/output signal swing. Load capacitance of all signals is 20 pF.

Figure 23. Audio Data Interface Timing (Master Mode: LRCK and BCK Work as Outputs)



SYMBOL	PARAMETER	MIN	TYP	MAX	UNIT
t <sub>(SCKBCK)</sub>	Delay time, SCKI rising edge to BCK edge	5		30	ns

NOTE: Timing measurement reference level is 1.4 V for input and 0.5  $V_{DD}$  for output. Load capacitance of BCK is 20 pF. This timing is applied when SCKI frequency is less than 25 MHz.

Figure 24. Audio Clock Interface Timing (Master Mode: BCK Works as Output)



#### SYNCHRONIZATION WITH DIGITAL AUDIO SYSTEM

In slave mode, the PCM1808 operates under LRCK (pin 7), synchronized with system clock SCKI (pin 6). The PCM1808 does not require a specific phase relationship between LRCK and SCKI, but does require the synchronization of LRCK and SCKI.

If the relationship between LRCK and SCKI changes more than  $\pm 6$  BCKs for 64 BCK/frame ( $\pm 5$  BCKs for 48 BCK/frame) during one sample period due to LRCK or SCKI jitter, internal operation of the ADC halts within  $1/f_{\rm S}$  and digital output is forced to zero data (BPZ code) until resynchronization between LRCK and SCKI is established.

In the case of changes less than ±5 BCKs for 64 BCK/frame (±4 BCKs for 48 BCK/frame), resynchronization does not occur and the previously described digital output control and discontinuity do not occur.

Figure 25 illustrates the digital output response for loss of synchronization and resynchronization. During undefined data, the PCM1808 can generate some noise in the audio signal. Also, the transition of normal data to undefined data creates a discontinuity in the digital output data, which can generate some noise in the audio signal. The digital output is valid after resynchronization completes and the time of  $32/f_{\rm S}$  has elapsed. Because the fade-in operation is performed, it takes additional time of  $48/f_{\rm in}$  or  $48/f_{\rm S}$  until the level corresponding to the analog input signal is obtained. If synchronization is lost during the fade-in or fade-out operation, the operation stops and DOUT (pin 9) is forced to zero data immediately. The fade-in operation resumes from mute after the time of  $32/f_{\rm S}$  following resynchronization.

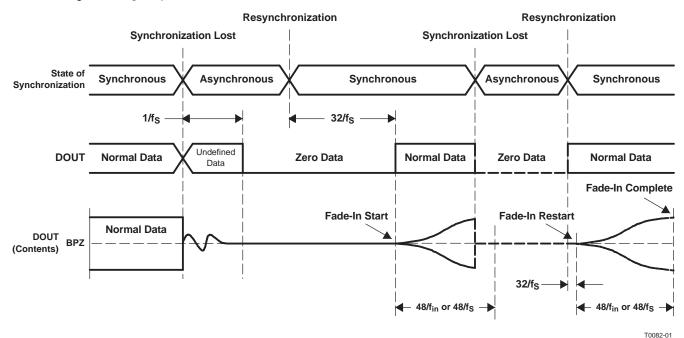


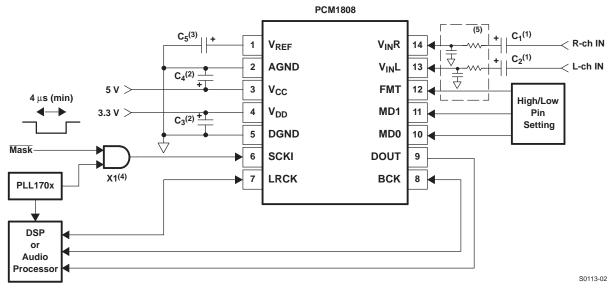
Figure 25. ADC Digital Output for Loss of Synchronization and Resynchronization



#### **APPLICATION INFORMATION**

#### TYPICAL CIRCUIT CONNECTION DIAGRAM

Figure 26 is a typical circuit connection diagram. The antialiasing low-pass filters are integrated on the analog inputs,  $V_{IN}L$  and  $V_{IN}R$ . If the performance of these filters is not adequate for an application, appropriate external antialiasing filters are needed. A passive RC filter (100  $\Omega$  and 0.01  $\mu$ F to 1 k $\Omega$  and 1000 pF) generally is used.



- (1) C1, C2: A 1- $\mu$ F electrolytic capacitor gives 2.7 Hz ( $\tau$  = 1  $\mu$ F  $\times$  60 k $\Omega$ ) cutoff frequency for the input HPF in normal operation and requires a power-on settling time with a 60-ms time constant in the power-on initialization period.
- (2) C3, C4: Bypass capacitors, 0.1-μF ceramic and 10-μF electrolytic, depending on layout and power supply
- (3) C5: 0.1-μF ceramic and 10-μF electrolytic capacitors are recommended.
- (4) X1: X1 masks the system clock input when using the clock-halt reset function with external control.
- (5) Optional external antialiasing filter could be required, depending on the application.

Figure 26. Typical Circuit Connection Diagram

#### **BOARD DESIGN AND LAYOUT CONSIDERATIONS**

#### V<sub>CC</sub>, V<sub>DD</sub> PINS

The digital and analog power supply lines to the PCM1808 should be bypassed to the corresponding ground pins with both 0.1- $\mu$ F ceramic and 10- $\mu$ F electrolytic capacitors as close to the pins as possible to maximize the dynamic performance of the ADC.

#### **AGND, DGND PINS**

To maximize the dynamic performance of the PCM1808, the analog and digital grounds are not internally connected. These grounds should have low impedance to avoid digital noise feedback into the analog ground. They should be connected directly to each other under the PCM1808 package to reduce potential noise problems.

#### VINL, VINR PINS

 $V_{IN}L$  and  $V_{IN}R$  are single-ended inputs. The antialias low-pass filters are integrated on these inputs to remove the high-frequency noise outside the audio band. If the performance of these filters is not adequate for an application, appropriate external antialiasing filters are required. A passive RC filter (100  $\Omega$  and 0.01  $\mu$ F to 1  $k\Omega$  and 1000 pF) is generally used.



## **APPLICATION INFORMATION (continued)**

## **V<sub>REF</sub> PIN**

To ensure low source impedance of the ADC references, 0.1- $\mu F$  ceramic and 10- $\mu F$  electrolytic capacitors are recommended between  $V_{REF}$  and AGND. These capacitors should be located as close as possible to the  $V_{REF}$  pin to reduce dynamic errors on the ADC references.

#### **DOUT PIN**

The DOUT pin has a large load-drive capability, but if the DOUT line is long, locating a buffer near the PCM1808 and minimizing load capacitance is recommended to minimize the digital-analog crosstalk and maximize the dynamic performance of the ADC.

#### SYSTEM CLOCK

The quality of the system clock can influence dynamic performance, as the PCM1808 operates based on a system clock. Therefore, it may be necessary to consider the system clock duty, jitter, and the time difference between system clock transition and BCK or LRCK transition in slave mode.





21-Jul-2010

#### **PACKAGING INFORMATION**

Orderable Device	Status <sup>(1)</sup>	Package Type	Package Drawing	Pins	Package Qty	Eco Plan <sup>(2)</sup>	Lead/ Ball Finish	MSL Peak Temp <sup>(3)</sup>	Samples (Requires Login)
PCM1808PW	ACTIVE	TSSOP	PW	14	90	Green (RoHS & no Sb/Br)	CU NIPDAU	Level-1-260C-UNLIM	Request Free Samples
PCM1808PWG4	ACTIVE	TSSOP	PW	14	90	Green (RoHS & no Sb/Br)	CU NIPDAU	Level-1-260C-UNLIM	Request Free Samples
PCM1808PWR	ACTIVE	TSSOP	PW	14	2000	Green (RoHS & no Sb/Br)	CU NIPDAU	Level-1-260C-UNLIM	Purchase Samples
PCM1808PWRG4	ACTIVE	TSSOP	PW	14	2000	Green (RoHS & no Sb/Br)	CU NIPDAU	Level-1-260C-UNLIM	Purchase Samples

(1) The marketing status values are defined as follows:

ACTIVE: Product device recommended for new designs.

LIFEBUY: TI has announced that the device will be discontinued, and a lifetime-buy period is in effect.

NRND: Not recommended for new designs. Device is in production to support existing customers, but TI does not recommend using this part in a new design.

PREVIEW: Device has been announced but is not in production. Samples may or may not be available.

**OBSOLETE:** TI has discontinued the production of the device.

(2) Eco Plan - The planned eco-friendly classification: Pb-Free (RoHS), Pb-Free (RoHS Exempt), or Green (RoHS & no Sb/Br) - please check http://www.ti.com/productcontent for the latest availability information and additional product content details.

**TBD:** The Pb-Free/Green conversion plan has not been defined.

**Pb-Free** (RoHS): TI's terms "Lead-Free" or "Pb-Free" mean semiconductor products that are compatible with the current RoHS requirements for all 6 substances, including the requirement that lead not exceed 0.1% by weight in homogeneous materials. Where designed to be soldered at high temperatures, TI Pb-Free products are suitable for use in specified lead-free processes. **Pb-Free** (RoHS Exempt): This component has a RoHS exemption for either 1) lead-based flip-chip solder bumps used between the die and package, or 2) lead-based die adhesive used between the die and leadframe. The component is otherwise considered Pb-Free (RoHS compatible) as defined above.

Green (RoHS & no Sb/Br): TI defines "Green" to mean Pb-Free (RoHS compatible), and free of Bromine (Br) and Antimony (Sb) based flame retardants (Br or Sb do not exceed 0.1% by weight in homogeneous material)

(3) MSL, Peak Temp. -- The Moisture Sensitivity Level rating according to the JEDEC industry standard classifications, and peak solder temperature.

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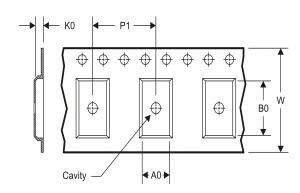
## TAPE AND REEL INFORMATION

#### **REEL DIMENSIONS**





#### **TAPE DIMENSIONS**



A0	Dimension designed to accommodate the component width
В0	Dimension designed to accommodate the component length
K0	Dimension designed to accommodate the component thickness
W	Overall width of the carrier tape
P1	Pitch between successive cavity centers

#### TAPE AND REEL INFORMATION

\*All dimensions are nominal

Device		Package Drawing		SPQ	Reel Diameter (mm)	Reel Width W1 (mm)	A0 (mm)	B0 (mm)	K0 (mm)	P1 (mm)	W (mm)	Pin1 Quadrant
PCM1808PWR	TSSOP	PW	14	2000	330.0	12.4	6.9	5.6	1.6	8.0	12.0	Q1

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#### \*All dimensions are nominal

Device	Package Type	Package Drawing	Pins	SPQ	Length (mm)	Width (mm)	Height (mm)	
PCM1808PWR	TSSOP	PW	14	2000	346.0	346.0	29.0	

PW (R-PDSO-G14)

## PLASTIC SMALL OUTLINE



NOTES:

- A. All linear dimensions are in millimeters. Dimensioning and tolerancing per ASME Y14.5M—1994.
- B. This drawing is subject to change without notice.
  - Sody length does not include mold flash, protrusions, or gate burrs. Mold flash, protrusions, or gate burrs shall not exceed 0,15 each side.
- Body width does not include interlead flash. Interlead flash shall not exceed 0,25 each side.
- E. Falls within JEDEC MO-153



# PW (R-PDSO-G14)

# PLASTIC SMALL OUTLINE



NOTES:

- A. All linear dimensions are in millimeters.
- B. This drawing is subject to change without notice.
- C. Publication IPC-7351 is recommended for alternate designs.
- D. Laser cutting apertures with trapezoidal walls and also rounding corners will offer better paste release. Customers should contact their board assembly site for stencil design recommendations. Refer to IPC-7525 for other stencil recommendations.
- E. Customers should contact their board fabrication site for solder mask tolerances between and around signal pads.



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